

Digital Photogrammetric System

PHOTOMOD

Version 6.4

USER MANUAL

Vectorization

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1. Purpose of the document

This document contains detailed information about vectorization in the *PHOTOMOD* system. It describes work with vector layers, including classifier, as well as features used for vector objects creation and editing, and topology check of created objects. The document also contains a description of all types of import and export in the *PHOTOMOD* system.

2. About vectorization

2.1. Main conventions and terms

This documentation uses the following concepts:

- *Vector graphics* – way of image objects presentation, based on using elementary geometric objects, such as points, lines, broken lines, splines, polygons, described by mathematical functions in contrast to raster graphics, where each object is a set of points (pixels);
- *Vector object* – 2D or 3D-object of vector graphics, described by mathematical function and belongs to one of the following objects types in the system: point, polyline, polygon;
- *Point* – a point object, which is determined by XY coordinates in the plane and by XYZ coordinates in space.
- *Polyline* – a broken line or a curve, containing a set of vertices, joined by straight or curve line pieces called segments.
- *Polygon* – an areal object, which boundaries are closed polyline.
- *CAD-objects* - standard geometric figures, for example, ellipse, circle, rectangle, arc, that are polylines or polygons (see [Section 5.3.5](#)).
- *Vertex* – a point, connecting polyline or polygon segments;
- *Segment* – a straight or curve line, connecting two vertices.
- *Fragment* – a part of polyline/polygon, a set of adjacent vertices/segments of polyline/polygon.
- *Vectorization* – an operation of vector objects creation on a vector layer, for example, for generation of digital maps.

2.2. Stereovectorization

Stereovectorization – an operation of terrain objects vectorization in stereo mode using stereo model, that allows to create digital elevation models and 3D topographic maps.

Stereomodel builds by stereopairs during block adjustment (see the “[Block adjustment](#)” User Manual).

Stereopair – two images for the same terrain acquired from different points of view that have overlap area.

When viewing a stereopair in such a way that each eye can see only one of the images, user can imagine three-dimensional (stereoscopic) picture, reproducing depth of the real object. Stereopairs formed by airborne and space borne images are used to create digital maps and DEM.

During survey images can have *in-strip* (inside a strip) and *inter-strip* (between strips) *overlap*. For stereo effect of optimal quality images have to have the following overlap size: in-strip overlap – at least 60% of image width, inter-strip – at least 20% of image height.

Stereo mode – a mode when each eye can see only one of two images, with stereoscopic effect as a result. It is used for stereo viewing of stereo model, and it is provided by hardware devices and monitor technical features.



Prior to start vectorization operation it is necessary to perform block adjustment in free or non-free model (see the “[Block adjustment](#)” User Manual).

3. Preparing to stereovectorization

3.1. Stereo image settings

When working in stereo mode to obtain the best stereo effect in created vector object area it is recommended to tune stereo image depth. This is important when working with “deep” images, i.e. images with a large Y-parallax difference in stereoscopic viewing area.

To tune stereo place marker to necessary area and project it on object or relief surface (see [Section 3.4](#)). Click the  button or press the **F2** key. Images are moved in such a way that parallax gets zero value in marker position, and the best stereo is obtained in this point vicinity or in its “depth”.



In order to activate *Automatic adjusting parallax in stereo mode* choose **Service > Settings** or click  button of the main toolbar. In **Settings** window select **Control** tab and in the section **Automatically adjust parallax in stereo mode** set the **Activate, with threshold** checkbox. *Threshold of changing marker height* is a value with which automatic adjusting parallax in stereo mode is performed. Threshold value is specified in pixels in corresponding field.

To restore basic stereoscopic effect “depth” click the  button of 2D window toolbar or use the **F3** hotkey.

To change stereo mode phase (i.e. to switch between left and right images) click the  button of 2D window toolbar or use the **F11** hotkey.

To change stereo image depth use the **Shift+Page Up/Page Down** or **Shift+mouse wheel** hotkeys.

3.2. Stereo modes

3.2.1. Anaglyph mode

In anaglyph mode a stereo image is formed using digital coding of stereopair images, that are intended for the right and left eyes, by the “red” and “blue” colour filters correspondingly. To view and measure in anaglyph stereo mode it is necessary to use dedicated spectral anaglyph glasses with the same filters.

Anaglyph mode for stereo measurements does not depend on monitor and graphics card parameters. The main disadvantage of anaglyph mode is inability to work with full color images.



Anaglyph mode of stereoscopic visualization is used in HighColor or TrueColor monitor graphic mode only.

3.2.2. Page-flipping mode

Page-flipping stereo mode provides quality stereo image using full frames. The left and right images are shown on the screen synchronously with frames changing. Synchronization of shutter glasses with vertical interlace of monitor allows to view two images at the same time and to perform stereo measurements on them. A prerequisite of the page-flipping mode is the presence of an appropriate video adapter, and monitor with stereo mode support.

To work in page-flipping mode it is necessary to use shutter stereo glasses. Shutter glasses are glasses with liquid crystals, which are synchronized with vertical interlace of monitor. The system supports page-flipping stereo measurements mode using shutter glasses. To learn more about using the stereo glasses and other special equipment for stereo measurements.

3.2.3. Polarization mode

To view stereo image on stereo monitor screen, which use polarization effect to divide the right and left images of stereopair superimposed on the screen or on a special translucent mirror, there are special polarized glasses. Polarized 3D-glasses (in contrast to shutter 3D-glasses) not fitted with wires and looks very similar to normal vision glasses.



Polarized 3D-glasses are included to stereo monitor delivery set, that supports this mode.

Polarized stereo glasses contain special polarized lenses with transparent polarizing film (polarization filter) inside. This film has the ability not to pass the light rays having a certain direction of transverse vibrations (certain direction of polarization), and does not prevent the passage of the rays with the other polarization directions. Polarized 3D-stereo glasses polarizing filters in the left and right lenses are orthogonally rotated relative to each other. That is why combination on the screen or on a special mirror of orthogonally polarized left and right stereo pair images are divided in the polarizing filter glasses to separate images for the left and right eyes.

3.2.4. Pseudo-stereo mode

The system allows to work in pseudo-stereo mode in the block scheme window.

Pseudo-stereo – is a stereo mode, where orthogonal projection is used for left eye, and for right eye – parallel projection with some angle to normal line. This mode allows to display to raster layers as one stereo image.



Pseudo-stereo mode has no metric characteristics and couldn't be used for stereo measurements.

In order to turn on the pseudo-stereo mode perform the following actions:

1. Choose **Service** › **Settings (Ctrl+Alt+P)**. The **Settings** window opens.
2. On the **Windows** tab set the **Allow pseudo-stereo in block scheme window** checkbox.
3. [optional] To define an angle of projection to normal line, specify the **Separation** parameter.
4. Click OK. To apply the changes, close block 2D-window and then open it again. To do this choose **Window** › **2D-window (block)**.
5. The buttons are the same as buttons in stereopair 2D-window. Buttons used to turn on and setup stereomode are added in 2D-window toolbar.
6. Choose **Raster** › **Load georeferenced image (files)** or **Raster** › **Load georeferenced image (resources)** and select two images to be loaded from file system or from projects resources. The **Load georeferenced image** window opens.

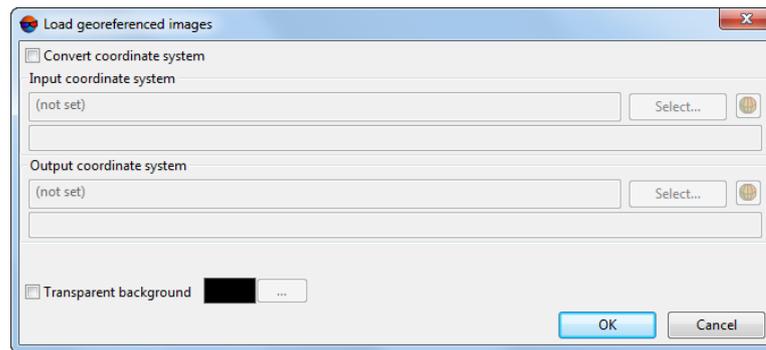


Fig. 1. Loading images

7. [optional] To change image coordinate system set the **Convert coordinate system** checkbox on (see the [Section 10.5.2](#)).
8. [optional] When loading multiple images at once the **Load** window opens. Select **Create separate layer for each file**. After that the images loads to two separate raster layers.

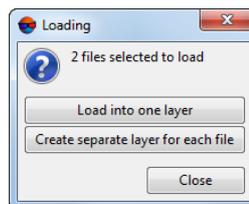


Fig. 2. Loading more than one image

9. Right click the layer with the “left” image in the Manager. In the context menu choose the **Raster layer parameters** item. The **Raster layer parameters** window opens.

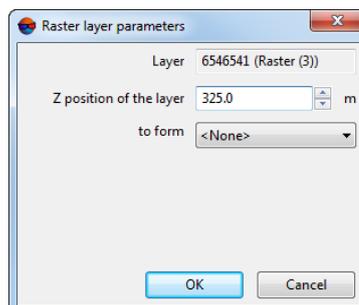


Fig. 3. Raster layer parameters

10. [optional] To set the layer Z level, specify a value in the **Z position of the layer** field.



This value is used as a elevation of stereo zero-parallax (not only for stereoscopic image formed with the other layer, but for a usual raster layer when the stereo is on in block scheme window). If current layer contains stereoscopic image formed with the other layer, then the layer Z position, specified in the window, is applied to both layers.

11. In the **Raster layer to form pseudo-stereo image** list select the layer with the “right” image. Raster layer with the “left” images becomes stereo layer.

In order to estimate a result of obtained pseudo-stereo image perform the following actions:

1. Turn on the stereo mode in the block scheme window. To do this click the  button.
2. Turn off visibility of layer with image, selected as the “right” one, by clicking the  button next to the layer name in the Manager.

3.3. Stereopair selection

3.3.1. Pass to adjacent stereopair

The system provides possibility to pass to the adjacent stereopair when working in 2D-window.



In the navigation window displays the left image of the stereopair.



When vectorizing lengthy objects – for example, roads or rivers, that passes through the whole images block – it is recommended to perform vectorization by sequential passage of stereopairs. At that the system allows to preserve marker position, zoom, parallax value and vector objects activity during smooth continuation of 3D vectorization (see the “[General system's parameters](#)” User Manual).

To pass to another stereopair use the following menu items in 2D-window **Window › Stereopairs** and buttons of the **Change stereopair** additional toolbar.

Table 1. Brief description of the “Stereopairs” menu

Buttons and menu items	Function
 Next stereopair (Ctrl+Alt+RIGHT)	allows to open a stereopair with next image in the strip
 Previous stereopair (Ctrl+Alt+LEFT)	allows to open a stereopair with previous image in the strip
 Stereopair up (Ctrl+Alt+UP)	allows to pass to a stereopair located on one strip up
 Stereopair down (Ctrl+Alt+DOWN)	allows to pass to a stereopair located on one strip down
 Select stereopair	allows to select an arbitrary stereopair to pass to

Buttons and menu items	Function
 Auto change stereopair (Ctrl+J)	allows to choose the best next stereopair related to marker position and move to it
Open reverse stereopair	allows to swap images of opened stereopair and to rotate image by 180 degrees

3.3.2. Pass to chosen stereopair

To select an arbitrary stereopair to pass to, choose **Window > Stereopairs > Select stereopair** or click the  button on the **Change stereopair** toolbar. The **Select stereopair** window opens.

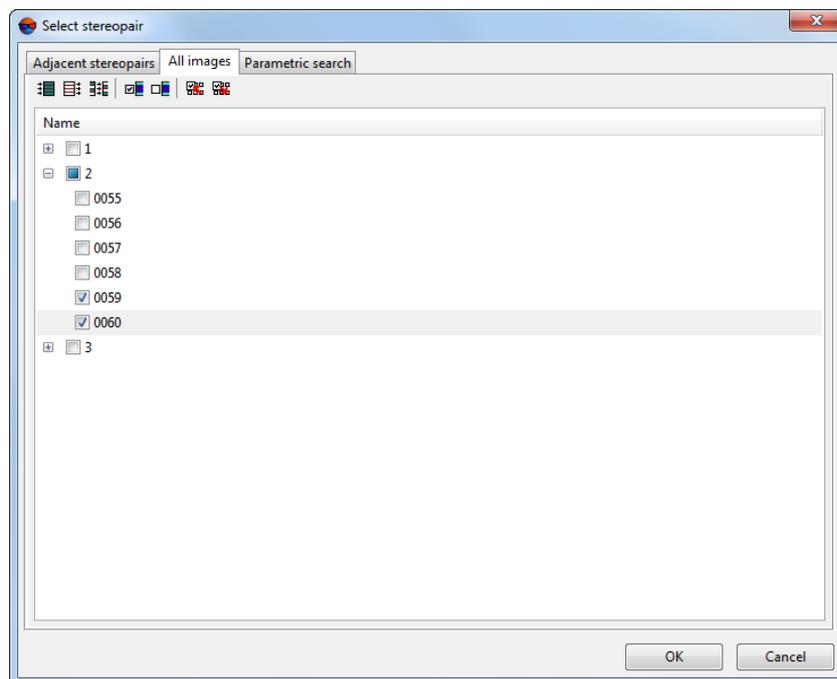


Fig. 4. The “Select stereopair” window

On the **Adjacent stereopairs** tab the system displays a list of all possible stereopairs, including those formed by non-adjacent images or images from different strips provided that all of them are overlapped.

On the **All images** tab a list of all project images displays. Images of the opened stereopair are marked by checkboxes.

The toolbar on the **All images** tab contains the following buttons:

-  – allows to select all images;
-  – allows to unselect all images;
-  – allows to reverse image selection in the table;

-  – allows to select highlighted images;
-  – allows to unselect highlighted images;
-  – allows to select images, highlighted on the block scheme;
-  – allows to highlight selected images on a block scheme.

The **Parametric search** tab is used to select a stereopair using parameters displayed in the table containing the following columns:

- **Score, %** – a score of stereo quality for block stereopairs;
- **Intersection angle, degrees** - an angle between photographing beams at the current terrain point (in marker position);
- **Distance to the boundary, pix.** - the shortest distance from the current marker position to the stereopair boundary;
- **Heading, degree.** - rotation angle of airframe in horizontal plane measured from the north direction (countdown of positive angles counter-clockwise when viewed from above);
- **Roll, degree.** - rotation angle (roll angle) of aircraft in relation to roll axis;
- **Pitch, degree.** - rotation angle of aircraft to main transverse axis of inertia or angle between aircraft roll axis and horizontal plane;
- **Basis angle, degree.** - angle between photographic image base and coordinate system plane;
- **Ray angle, degree.** - angle between ray and coordinate system plane;
- **Projection center height, left image, m** - projection center height for left image, in meters;
- **Projection center height, right image, m** - projection center height for right image, in meters;



Stereopair table displays a list of all stereopairs found in marker's position and the system automatically selects an optimal stereopair (active stereopair) there, i.e. block stereopair with the best quality of stereo. This stereopair is assigned the highest rating.

To select an optimal stereopair (by parameters) perform the following actions:



For VisionMap A3 projects it is not recommended to use parametric mode of stereopair selection.

1. In the **Selection mode** section specify one of the following ways of optimal stereopair selection:



Mode of active stereopair selection and configuring of selection parameters leads to recalculating of stereo quality score of all stereopairs in the table.

- **By stereo angle** - allows to select an active stereopair by optimal or specified stereo angle;
- **By distance to the boundary** - allows to select an active stereopair by distance from current point in marker's position to stereopair's boundary;
- **Advanced** - allows to find an active stereopair which features satisfy extended set of specified parameters values.

2. [optional] Specify optimal parameters values for selected mode in the **Optimal value** section. To configure parameters use calculated value from active stereopair or specify fixed value (with indication of weight percentage for the advanced mode).
3. [optional] Define a range of acceptable values of specified parameters in the **Limits** section. The system suggests by default to specify limits (minimal and maximal values) for stereo angle. To define a range of acceptable values of other parameters set the **Show all limits** checkbox on.

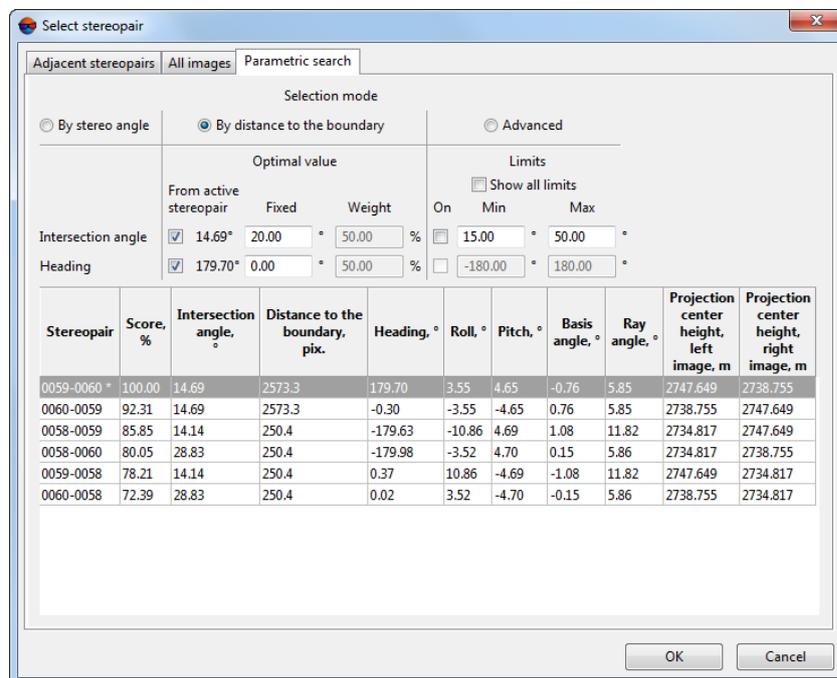


Fig. 5. Parametric stereopair search

To pass select a stereopair on one of the tabs and click OK.

3.3.3. Automatic stereopair selection

The system provides possibility to search for the best stereopair and to pass to it automatically during stereo vectorization.

To select the best stereopair automatically perform the following actions:

1. Place marker in the vicinity of the vectorization object.
2. Click the  button (**Ctrl+J**). The system calculate the best stereopair to pass to, using a value of intersection angle in relation to marker.

3.4. The marker management

3.4.1. The “Marker” window

The system provides possibility to display current marker coordinates both in project coordinate system and WGS-84 geodetic coordinate system, as well as marker move to a point with specified coordinates. The **Marker** window is used for this purpose.

To display current marker coordinates in the project coordinate system choose **Window > Marker window** or click the  button of the main toolbar. The **Marker** window opens.

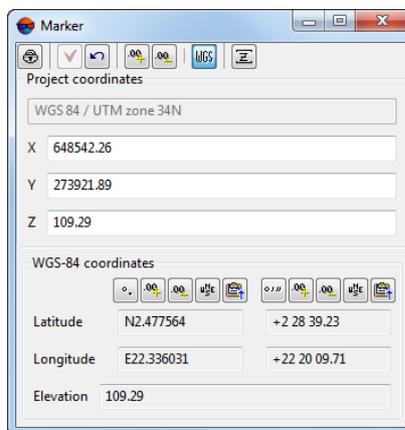


Fig. 6. The “Marker” window

The top toolbar contains the following buttons:

-  - allows to change marker’s position just after input of coordinates values without clicking the  button or press **Enter**.
-  - allows to move marker in accordance with specified coordinates;
-  – allows to cancel changes and return to initial coordinates;
-  - allows to increase number of displayed decimal places by one;

-  - allows to decrease number of displayed decimal places by one;
-  – allows to show/hide bottom part of the window to display geodetic marker coordinates in WGS-84;
-  – allows to fix the marker value by Z coordinate (**Alt+Z**). Is used on vectorization and editing of lines on a constant Z (see the [Section 3.4.5](#)).

The bottom part of the window displays geodetic marker coordinates (latitude/longitude/height). The toolbox contains the following buttons:

-  - allows to change display format of geodetic coordinates;
-  - allows to increase number of displayed decimal places by one;
-  - allows to decrease number of displayed decimal places by one;
-  - allows to turn on display format of units and hemispheres;
-  allows to copy coordinates to clipboard (**Ctrl+C**).



Only plane coordinates copies by default. To copy all coordinates, click the button while holding **Alt** key.

In order to change marker position in project coordinate system perform the following actions:

1. Choose the **Window > Marker window** or click the  button of the main toolbar. The **Marker** window opens.

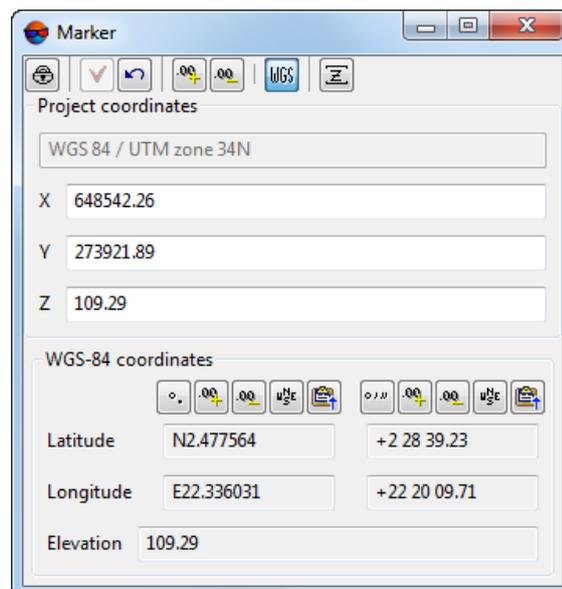


Fig. 7. The “Marker” window

- Input coordinates of a point to move marker to in the **Project coordinates** section.



[optional] To change marker's position automatically just after input of coordinates values click the  button.

- Click the  button or press the **Enter** key. After that marker is moved to the point with specified coordinates.

3.4.2. Marker modes

Depending on the object of vectorization for different stereo vectorization methods the system provides the following modes of marker work:

- moving marker mode* – the marker moves arbitrarily by image “fixed” in XY plane.

Use arrow keys to move marker in XY plane. Use the **Page Up** and **Page Down** hotkeys or rotate mouse wheel to set marker by Z.



Moving marker mode is used in the system by default.

-  *fixed marker mode (F6)* – marker is always in the center of the screen, horizontal parallax on it is zero.



In fixed marker mode a step of model move by Z is defined arbitrarily.



Fixed marker mode is intended for users who have work experience on stereo devices. The advantage of the mode is the ability to vectorize extended objects continuously with a constant automatic moving of image.

To place the marker on the surface of relief model in stereomode use the **Page Up** and **Page Down** hotkeys (in XY plane) or mouse wheel rotation to move marker by Z. To move image in XY plane use mouse or arrow keys.

-  *marker=mouse mode (F4)* – mouse cursor is invisible, all mouse moves lead to marker moving without additional clicks of mouse buttons.



This mode is used for vectorization of extended objects breaklines.



The marker=mouse mode is not available if the [alignment mode](#) is enabled.

- [orthogonal mode](#) – allows to create orthogonal objects; in this mode marker moves at a right angle;
- [snap-to-ground mode](#) – marker is automatically positioned on the relief;

- **streamline mode** – points are added continuously by set distance while mouse button is pressed;
- **fixing by Z** – marker has fixed elevation value.

The system also allows to place marker on a model surface automatically using correlator. The **Space** key is used to do this.



If the correlator failed to work the **Status** panel displays the **Bad point** message and the system produces warning audio signal.



Step of marker moving along Z axis is discrete and inversely proportional to the current image increase when scaling. For fast marker moving along Z use mouse wheel rotation while holding pressed **Alt** key.

To set up marker parameters choose the **Service > Settings**. The **Settings** window opens. It is possible to configure shape, color and size of marker in the **Windows** section on the **Marker (stereopair)** tab (see the “[General information](#)” User Manual).

To change horizontal parallax in stereo mode the system provides the **Shift+PgUp/PhDn** hotkeys, and **Shift+mouse wheel rotation**.



For fast parallax change for high values, move the mouse while holding **Alt+Shift+mouse middle button**.

To change horizontal parallax in *fixed marker mode* it is possible to use **Shift+mouse wheel rotation** and **Ctrl+Shift+mouse wheel rotation** hotkeys by X and Y accordingly. To set parallax to zero in marker position the **F3** hotkey is used.

3.4.3. Snap-to-ground mode

For automatic place marker on terrain relief during stereo vectorization the system provides the **snap-to-ground mode** – a mode of automatic marker following the relief. To enable the snap-to-ground mode choose **Edit > Snap-to-ground mode (T)** or click the  button of the **Vectors** toolbar.

In this mode marker moves on XY plane and automatically set by Z (with correlator).



If the correlator failed to work the **Status** panel displays the **Bad point** message and the system produces warning audio signal. In this case it is possible to place marker on the relief manually using mouse wheel or the **Page Up**, **Page Down** keys.

3.4.4. Streamline mode

The system provides possibility to vectorization in streamline mode. In this mode points add automatically by set distance.

To enable the streamline mode choose **Edit > Streamline mode (Y)** or click the  button of the **Vectors** toolbar. Press **Insert** to create first node. Next nodes add auto-

matically when moving mouse with pressing left button. Nodes add through the distance set in the general system's parameters (see the "[General system's parameters](#)" User Manual).



To add a node in a distance closer than specified, use the **Insert** key.



In classifier layer the streamline mode is used with linear (L) or polygonal (P) code type.

3.4.5. Fixation of Z

To perform vectorization on a constant elevation (for example, during contour lines creation) the system provides fixation of marker by Z mode.

To fix vectorization elevation place marker to necessary position and click the  button in the **Marker** window (**Alt+Z**).

3.4.6. Snapping mode

Snapping called marker movement mode, when it "sticks" to the different elements of the vector objects on the screen (to points, midpoints, lines, etc). The mode is used for precise spatial matching of created objects elements with elements of existing ones.

It is possible to snap created objects not only to objects located in active layer, but to all objects on opened vector layers, as well as to elements of the object being created.

For the work in *snapping* and *multi-snapping* modes (see below) the system provides the **Edit > Snapping** menu items, hotkeys and **Vectors toolbar** buttons (partially).

Snapping types and modes

The system supports two *types* of snapping:

- 2D – XY-plane marker coordinates match to coordinates of object elements, Z-height of marker is not changed;



2D snapping is used while creation an object coinciding with existing one only in XY plane. If, for example, it is necessary to add an extension to building with different height.

- 3D – XYZ marker coordinates match to coordinates of object elements;

Both snapping *types* provide several *modes*, defining an interaction of marker with particular elements of vector objects (see below).

The system also provides *multi-snapping* functionality, which allows for using several snapping modes at once, to generate unique combinations of active snapping options.

Work in snapping mode



For work in snapping mode *only* the [hotkeys](#) are used.

Table 2. Work in snapping mode

Hotkeys and “Snapping” menu items	Function
 3D snapping to vertices (V)	marker moves by vector object vertices, XYZ-coordinates match to a vertex coordinates (when the mode was enabled with hotkey, marker moves to the vertex nearest to the marker position);
 2D snapping to vertices (B)	marker moves by vector object vertices, XY-coordinates match to a vertex coordinates and Z-coordinate doesn't change (when the mode was enabled with hotkey, marker moves to the vertex nearest to the marker position without changing marker's height value);
 3D snapping to lines (N)	marker moves over segments of vector objects (when the mode was enabled with hotkey, marker moves to the point on vector object segment, closest to the marker position, with exact match with XYZ coordinates);
 2D snapping to lines (M)	marker moves over segments of vector objects (when the mode was enabled with hotkey, marker moves to the point on vector object segment, closest to the marker position, without changing marker's height value);

Work in multi-snapping mode

The *multi-snapping* mode allows for using several snapping modes at once, to generate unique combinations of active snapping options.

It is recommended to set snapping parameters before work with vector objects in multi-snapping mode.

To specify snapping settings, select **Service** › **Settings**. Set snapping parameters at the **Snapping** section of **Vectors** tab (see the “Settings of work with vector objects” chapter of the “[General system's parameters](#)” User Manual).

Set the following parameters:

- **Detect radius** (in pixels) – if marker is placed from the object element at the distance of less than **Detect radius**, this element is highlighted by grey colour with no snapping (moving marker);



An element is highlighted in gray, if the default **Show tips** checkbox is not cleared in the **Settings (Service** › **Settings** › **Vectors)** window.

- **Snap radius** (in pixels) – if marker is placed from the object element at the distance of less than **Snap radius**, a marker snapped to this element. A label of snapping mode used appears near it;



A snapping label appears if the default **Show labels** checkbox is not cleared in the **Settings** (**Service > Settings > Vectors**) window.

- **Cache for snapping to coordinates;**

The **Separate 2D and 3D modes** checkbox allows to generate unique combinations of active snapping options (to points, midpoints, lines, coordinates, as well as perpendicular mode) separately for 2D and 3D snapping modes.

The **Create common vertices on snap to lines mode** checkbox allows to add vertices in snapping mode both on marker and source line height.



In the 3D-snapping mode vertices are also becomes topological connected.



For the work in *multi-snapping* mode the system provides the **Edit > Snapping** menu items, hotkeys and **Vectors** toolbar buttons.

To start working in multi-snapping mode make active one of two multi-snapping types:

Table 3. Brief description of the multi-snapping types and modes

Hotkeys and “Snapping” menu items	Function
 2D snapping (2)	Marker moves to vector object elements (vertices, medians etc.), XY-plane marker coordinates match to coordinates of object elements, Z-height of marker is not changed;
 3D snapping (3)	Marker moves to vector object elements (vertices, medians etc.), XYZ marker coordinates match to coordinates of object elements;

Make active at least one of following snapping modes:

 Snap to points (4)	marker snaps to vertices of vector objects. Label End appears near that nodes
 Snap to midpoints (5)	marker snaps to medians of vector objects. In case of detecting object segment at the distance of lower than Detect radius , its median is highlighted by small grey circle symbol. Label Midpoint appears near that medians
 Snap to lines (6)	marker snaps to segments of vector objects. Label Nearest appears near segment point closest to the marker position
 Perpendicular snap (7)	allows to <i>edit</i> vector objects by moving their vertices in directions parallel or perpendicular to adjacent

	segments, as well as to move these vertices to the segments of the edited object (or the segments of neighboring objects) towards the perpendicular to these segments
 Snap to coordinates (8)	allows to <i>create</i> polylines/polygons orthogonal to the basic or additional coordinate system, as well as accurately orient drawing objects regarding vertices of existed vector objects



While activating a snapping mode with a hotkey, a highlighting of corresponding object element or marker move to element position take place automatically if the element is at the distance less than **Detect radius** or **Snap radius** respectively.



In snapping mode there is a possibility to draw a part of the created object over existing one (see [Section 11.7](#)).

Perpendicular snapping



The perpendicular snapping mode is used *only for editing* already created vector objects. To *create* orthogonal vector objects, use [snap to coordinates](#) or [orthogonal mode](#).

When the perpendicular snapping mode is activated, the system allows to edit vector objects by moving their vertices in directions parallel or perpendicular to adjacent segments, as well as to move these vertices to the segments of the edited object (or the segments of neighboring objects) towards the perpendicular to these segments:

- When the perpendicular snapping mode is activated, the system allows to move a vertex of a vector object parallel or perpendicular to the directions of the adjacent segments.

Creation of guides is indicated by Perpendicular and Parallel labels in the vicinity of a vertex, respectively.

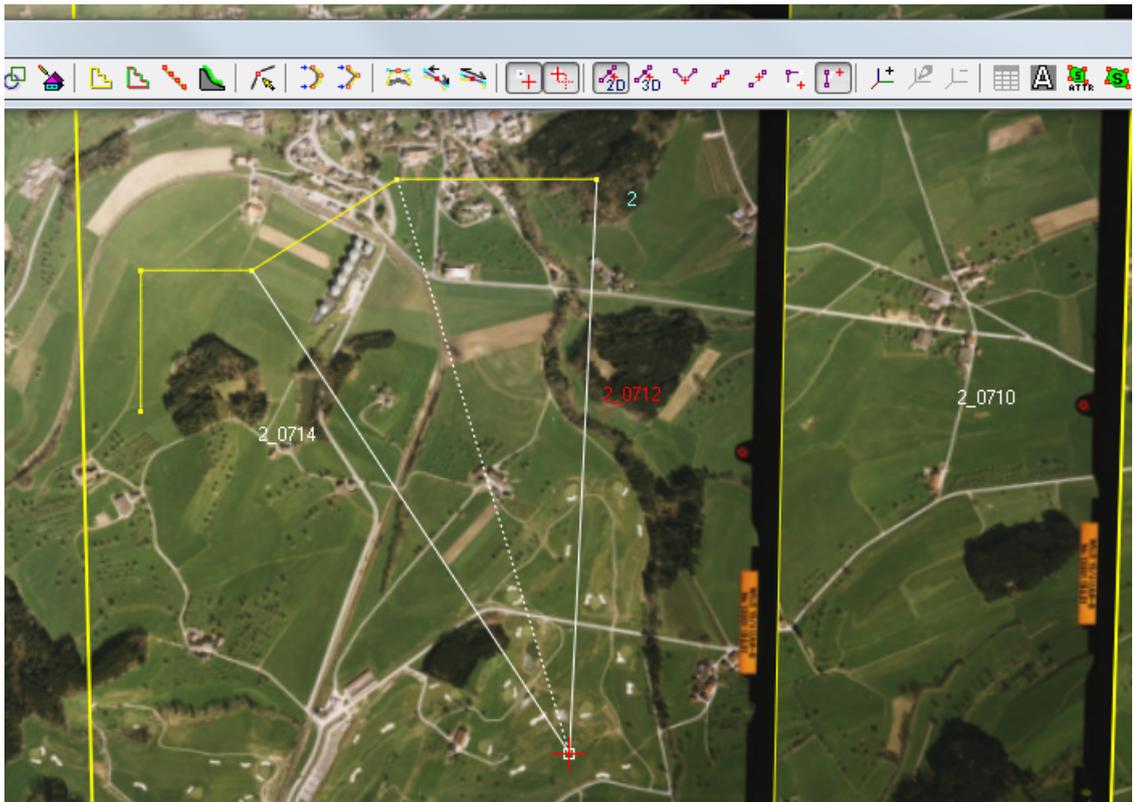


Fig. 8. Moving the vector object vertex

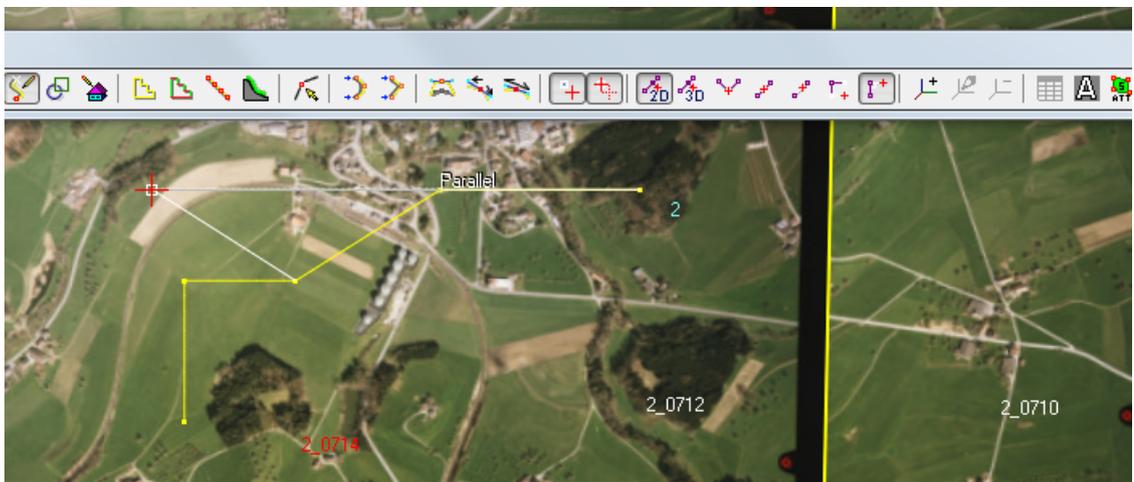


Fig. 9. Moving the vector object vertex parallel to the adjacent segment

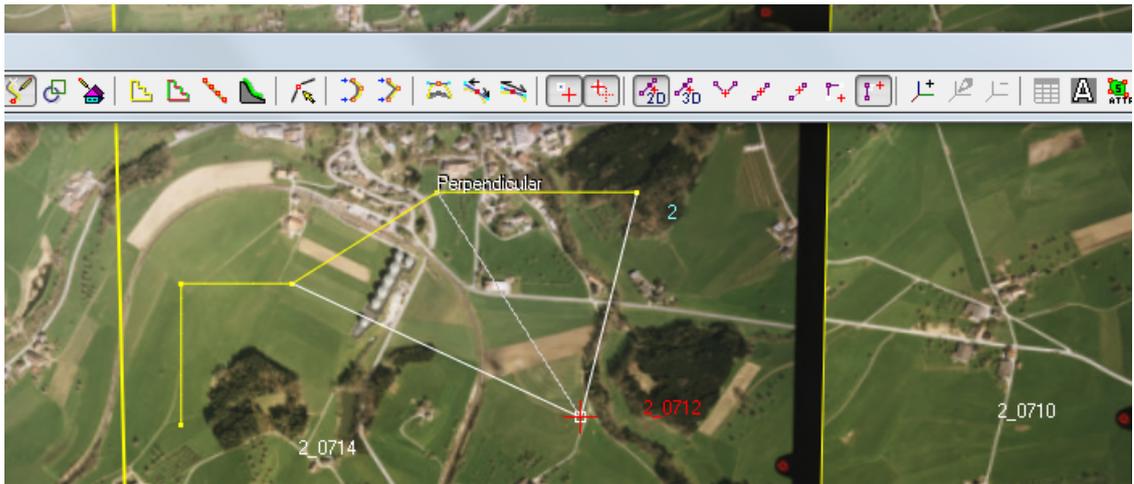


Fig. 10. Moving the vector object vertex perpendicular to the adjacent segment

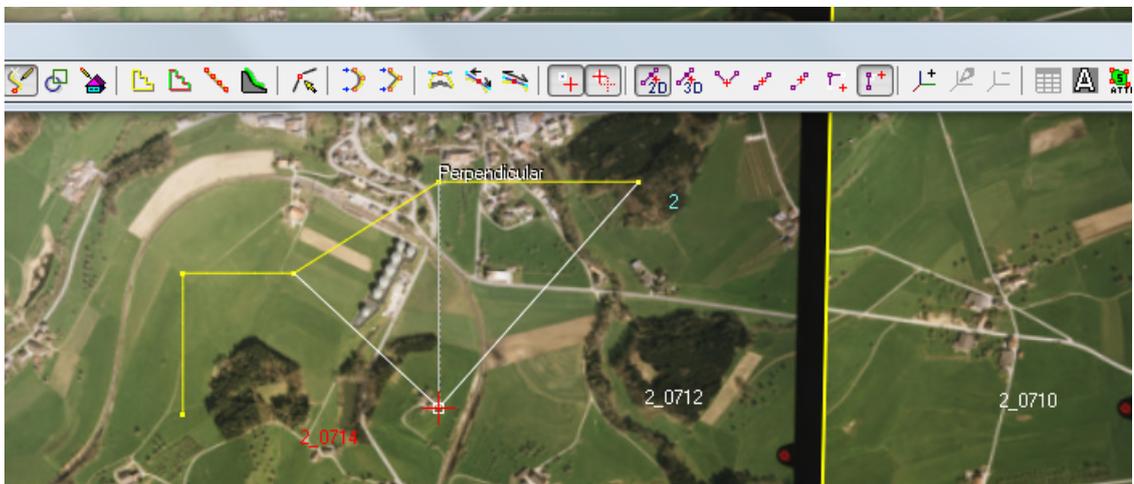


Fig. 11. Moving the vector object vertex perpendicular to the adjacent segment

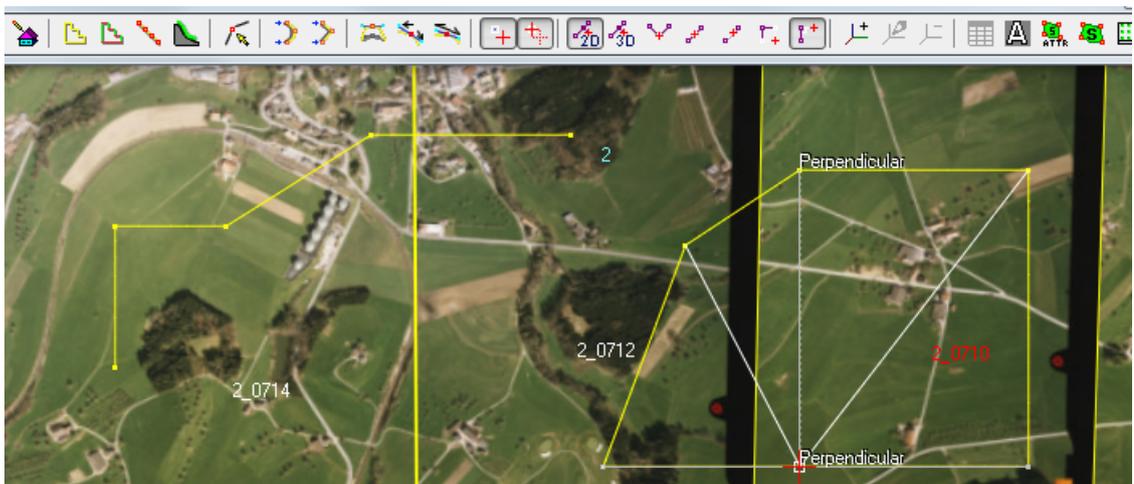


Fig. 12. Perpendicular snapping of the object vertex to the segment of the same object

- When moving an object's vertex to neighboring vector objects (or the edited object segments), "snap points" are created (indicated by a small gray square and a Perpendicular label) located at the intersection of segments and the *perpendicular* (gray dashed line) originating from the location of the moved vertex.

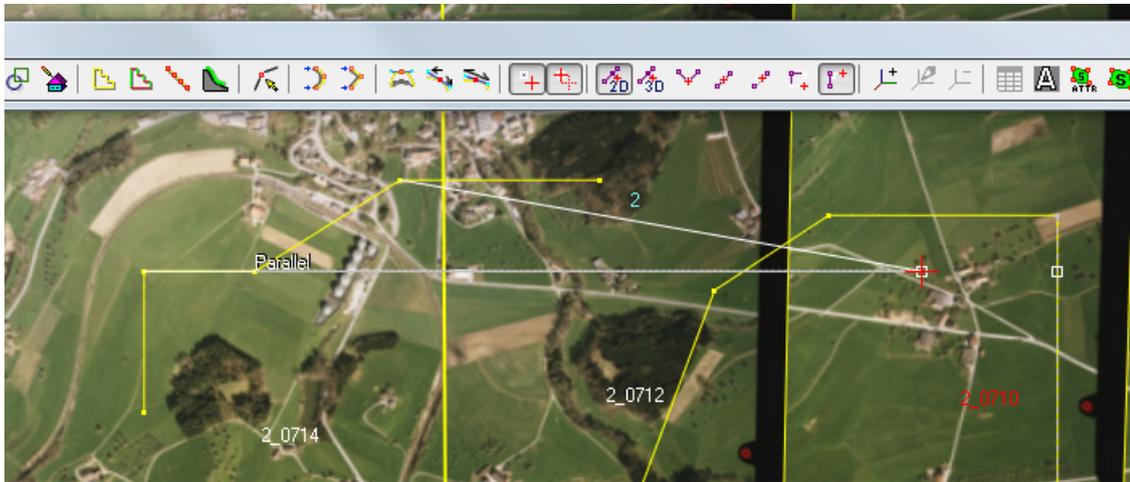


Fig. 13. Moving the object's vertex parallel to the adjacent segment in the direction perpendicular to the neighboring object's segment (marker in detection radius)

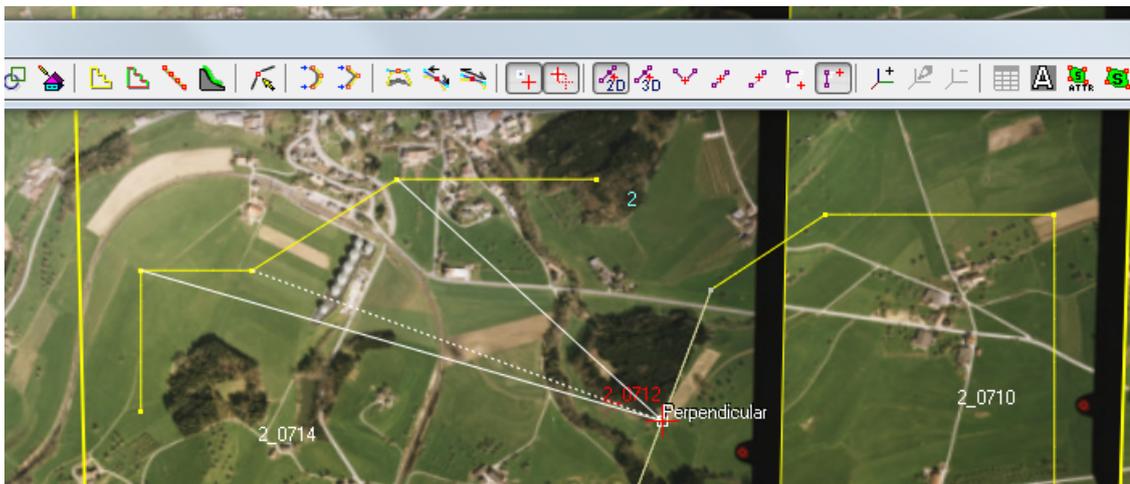


Fig. 14. The object's vertex snapping to the neighboring object segment in the direction perpendicular to the segment



To move vertices, activate **Select vertices when marker moves over them** and **Move marker to selected vertex** modes by setting the appropriate checkboxes in the **Settings (Service > Settings > Vectors)** window, or click and buttons in the **Vectors additional toolbar**.

Snap to coordinates

If **Snap to coordinates** mode is enabled, the system allows to build and edit polylines/polygons orthogonal to the basic or **additional coordinate system** as well as accurately orient drawing objects regarding vertices of existed vector objects.

- While creating polylines/polygons starting from the first vertice, a marker snaps to red and green dash line *guides*, outgoing from the vertices of the created object and co-directed with axes of basic and additional coordinate systems. Red guide is co-directed with X axis, green guide is co-directed with Y axis.

Guide is shown as a solid line if the marker was placed near the guide (at the distance shorter than **Snap radius**), was snapped to the guide, and drawing segment of polyline/polygon should be co-directed with corresponding axis of coordinate system. In neighbourhood of vertices from which guides outgo labels End appear.



Dashed *guides* are displayed only if default **Show tips** checkbox is not cleared in the **Settings (Service > Settings > Vectors)** window and if the distance between the previously created object's vertices and the marker position does not exceed the **Detect radius**.

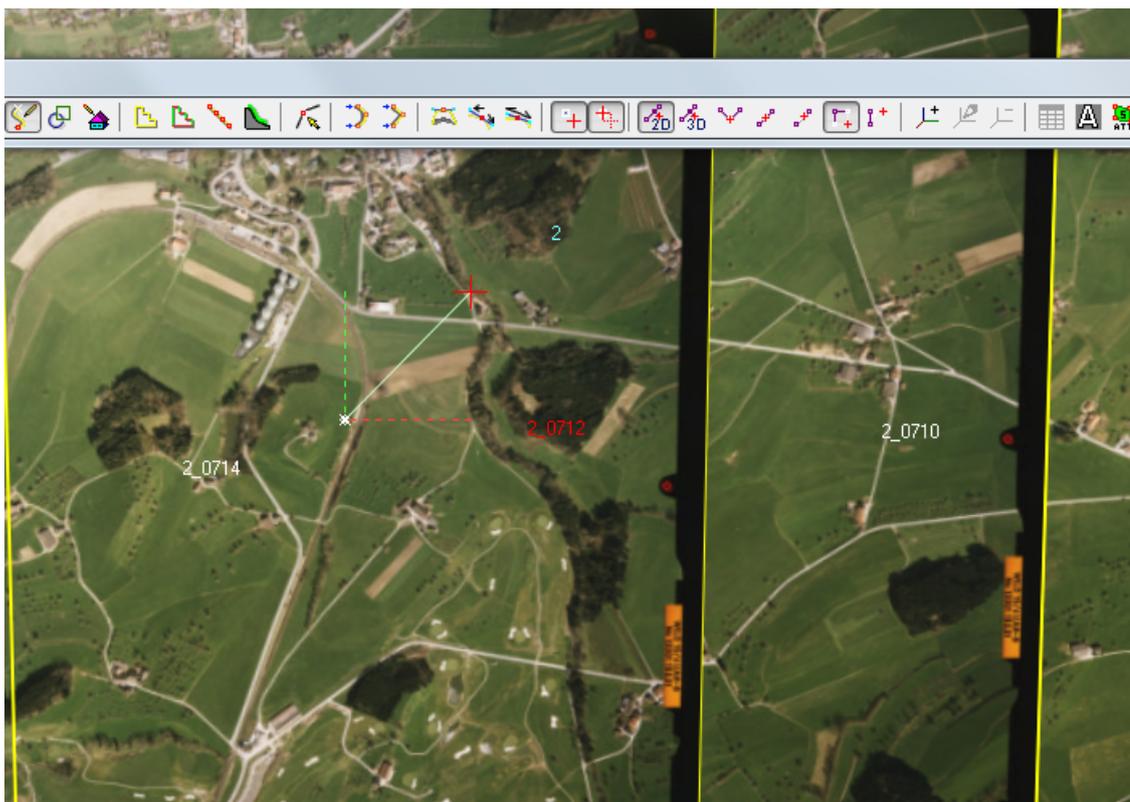


Fig. 15. The beginning of the vector object creation in **Snap to coordinates** mode.

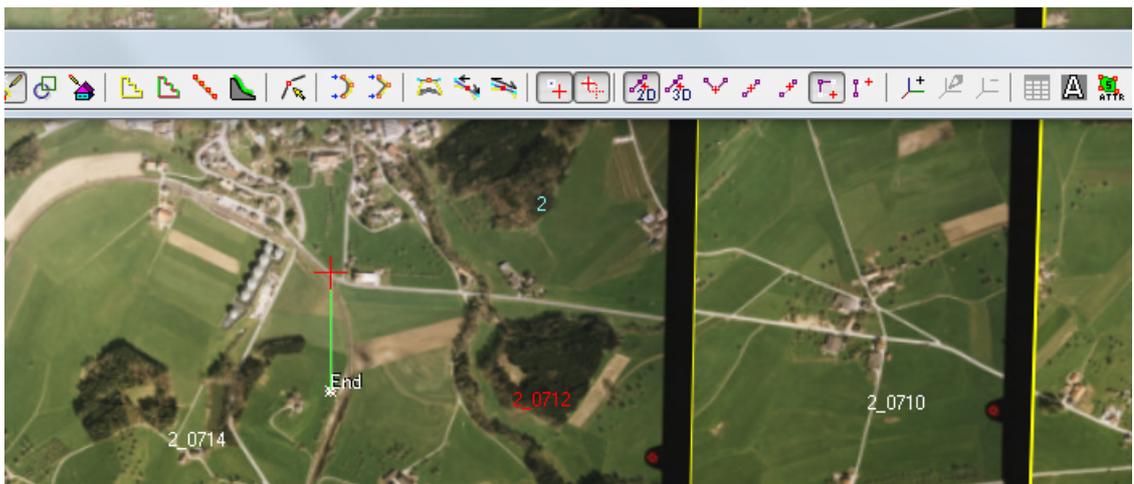


Fig. 16. Creation of the segment, co-directed with Y axis.

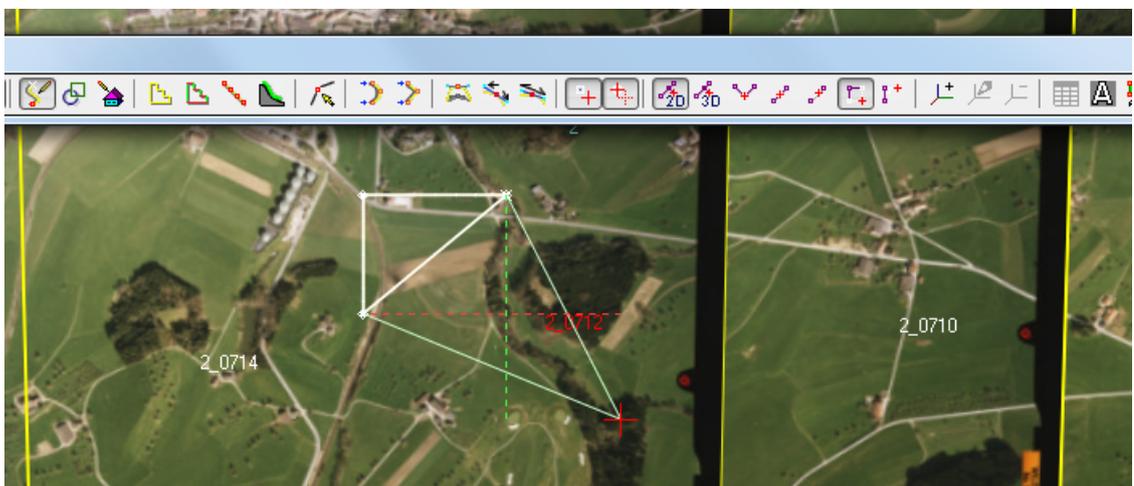


Fig. 17. Guides, outgoing from 2 previous created vertices

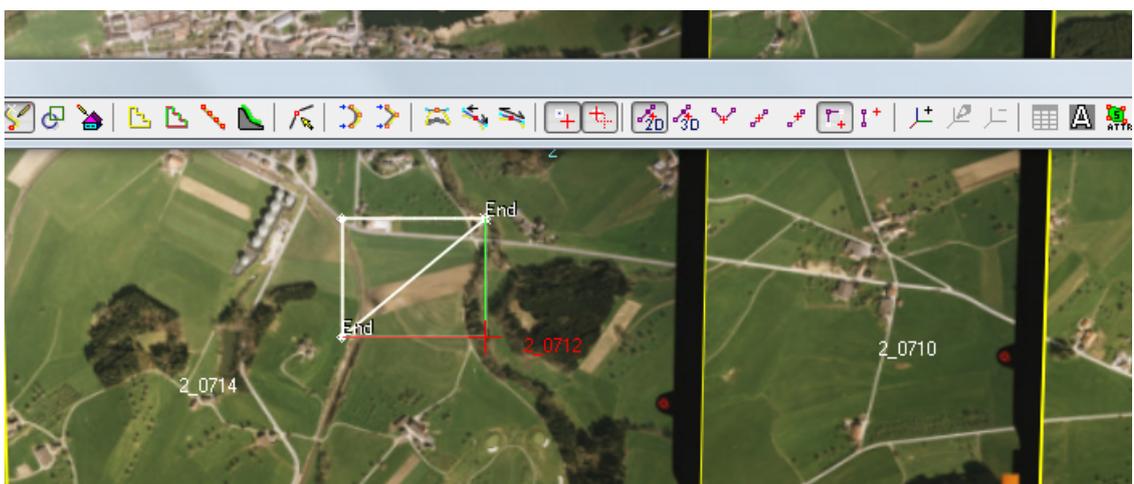


Fig. 18. Guides, outgoing from 2 previous created vertices

- If **Snap to points** mode is enabled as well, while drawing polyline/polygon in the neighborhood of existed vector objects, the *guides* outgoing from the vertices of existed vector objects are also built.

To have guides from the vertices of an existing object (in the process of a new object creation), you should first snap to at least one of the vertices of this object.

While snapping marker to intersection of guides, guides are shown like solid lines. In neighbourhood of vertices from which guides outgo labels End appear.



The system provides for memorizing the fixed number of selected vertices of existing objects to snap to coordinates which is determined by the **Cache for snapping to coordinates** option that can be set in the **Settings (Service > Settings > Vectors)** window.

Maximum value for **Cache for snapping to coordinates** is 100. If the value of **Cache for snapping to coordinates** is equal to 0, the selection of vector object's vertices (by snapping to them) will not result in appeared guides, and it will not be possible to set the marker on their intersection.



Snapping functions are active not only when creating new objects but when editing positions of the existing object's vertices.



In default while **Snap to coordinates** mode is enabled guides outgo just from the vertices of existed objects. If **Snap to medians** mode is enabled as well, additional guides outgoing from segment medians are built.

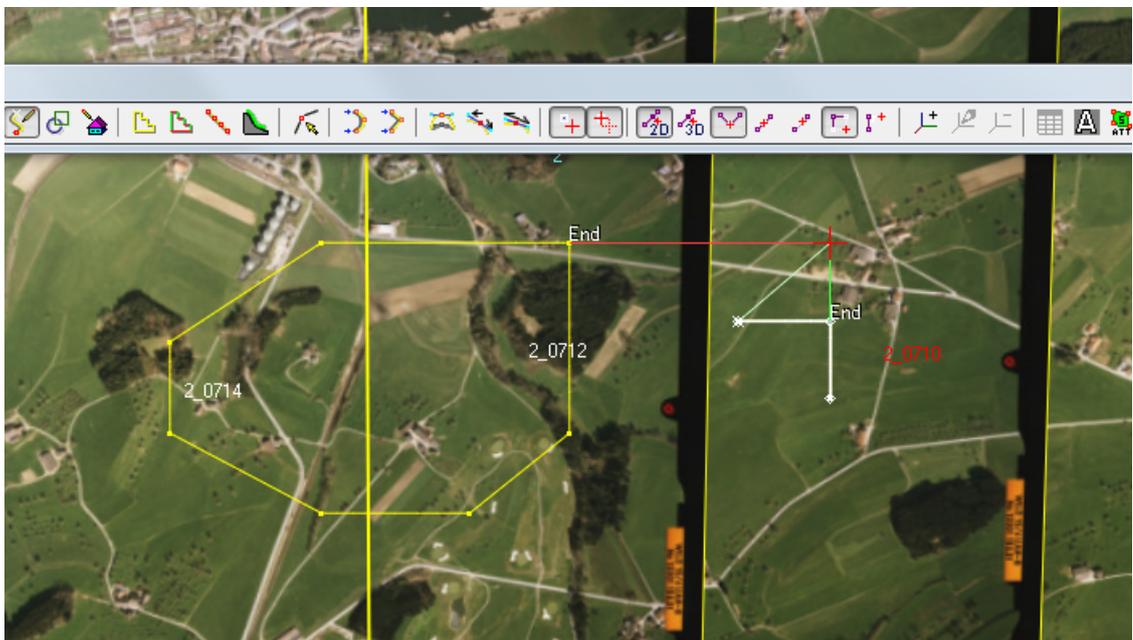


Fig. 19. Guides originating both from the vertex of the created object and the neighboring object's vertex

“Manual” snapping to coordinates

With enabled snapping to coordinates mode, the system allows to create vertices of vector objects in so called “manual snapping to coordinates” mode at the points of intersection of the preset direction and the perpendicular from it to *guides* originating from the vertices of the created object, as well as from the vertices of the existing objects (if **Snap to midpoints** is additionally activated) and the medians of object’s segments (if **Snap to midpoints** is additionally activated).

For manual snapping, perform the following:

1. Create at least one polygon/polyline vertex;
2. Press and hold the **left mouse button** and move the marker, thus setting the direction;

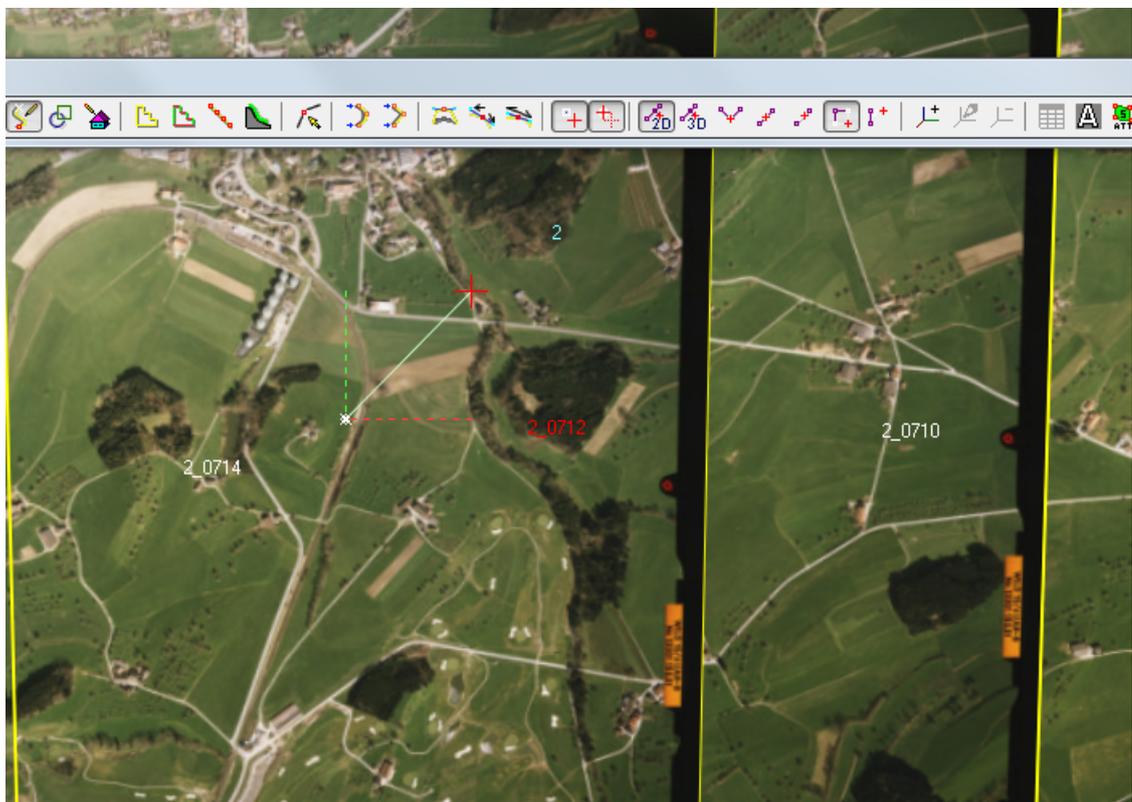


Fig. 20. Start of an object creation in the manual snapping to coordinates mode (when moving the marker, press the **left mouse button**)

3. **Holding the left mouse button**, press **Shift**;
4. Holding the **left mouse button** and the **Shift** key, keep moving the marker. The following will be created:

- A solid grey *guide* that prolongs the direction set in paragraph 2;
- A dashed grey *perpendicular* from this *guide* to the dashed red and green *guides* co-directed with the axes of main or additional coordinate systems which originate from the vertices of the created object (and from the vertices of the existing objects, their segments, and medians of their segments, depending on the snapping modes that are active)
- The point of intersection marking the place of the next vertex creation denoted with a small grey x-type cross.

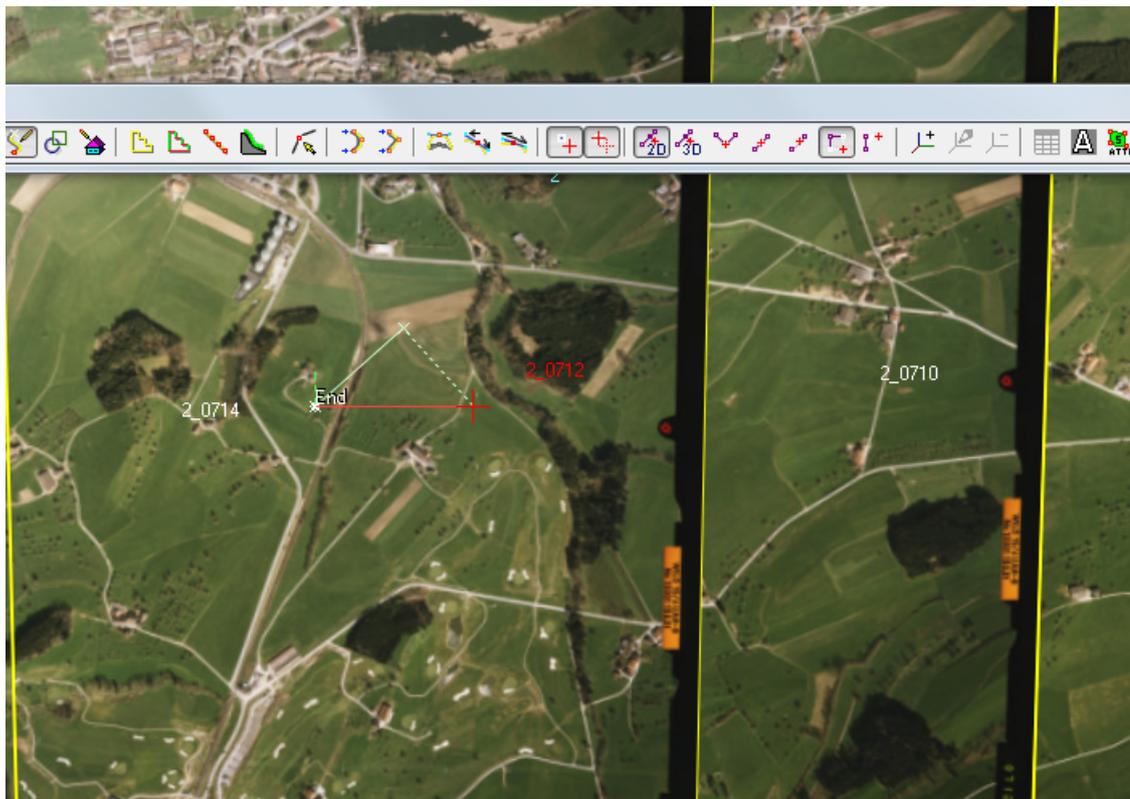


Fig. 21. Moving the point of the next vertex creation strictly in the direction set in paragraph 2 (both the **left mouse button** and **Shift** button are pressed)

5. Move the marker to the desired position, release the **left mouse button** and the **Shift** button, press the **Insert** button to create a new vertex at the intersection point denoted with a small grey x-type cross.

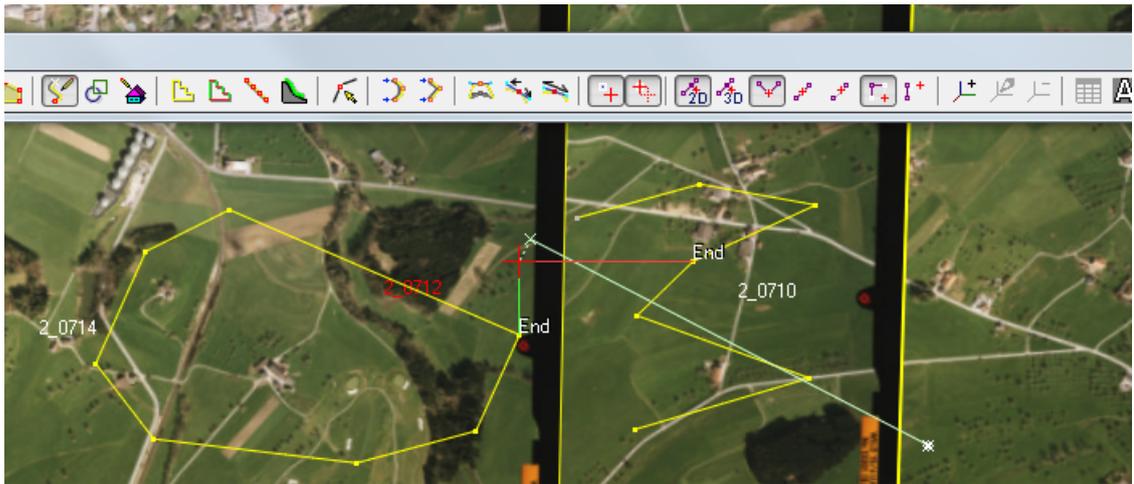


Fig. 22. Working in the manual snapping to coordinates mode

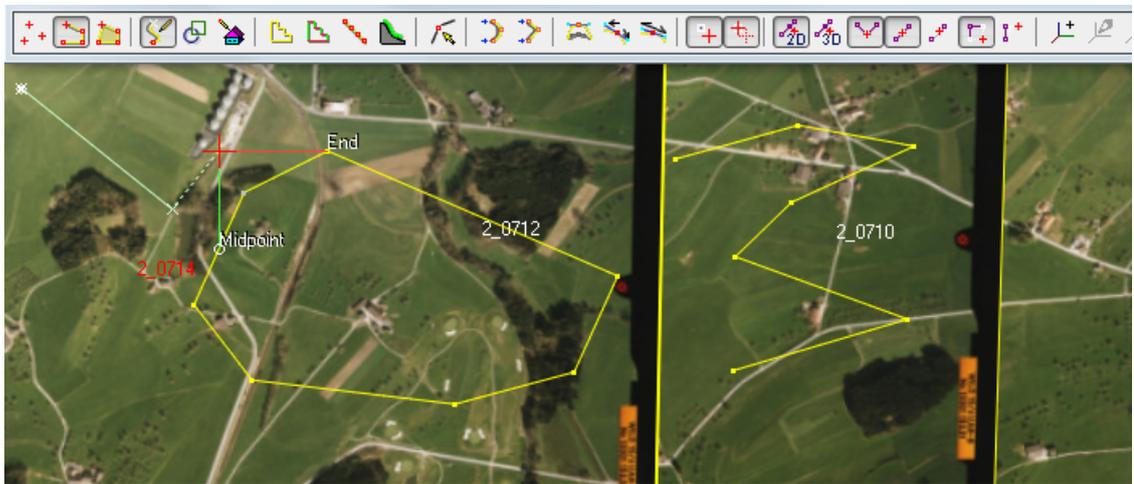


Fig. 23. Working in the manual snapping to coordinates mode

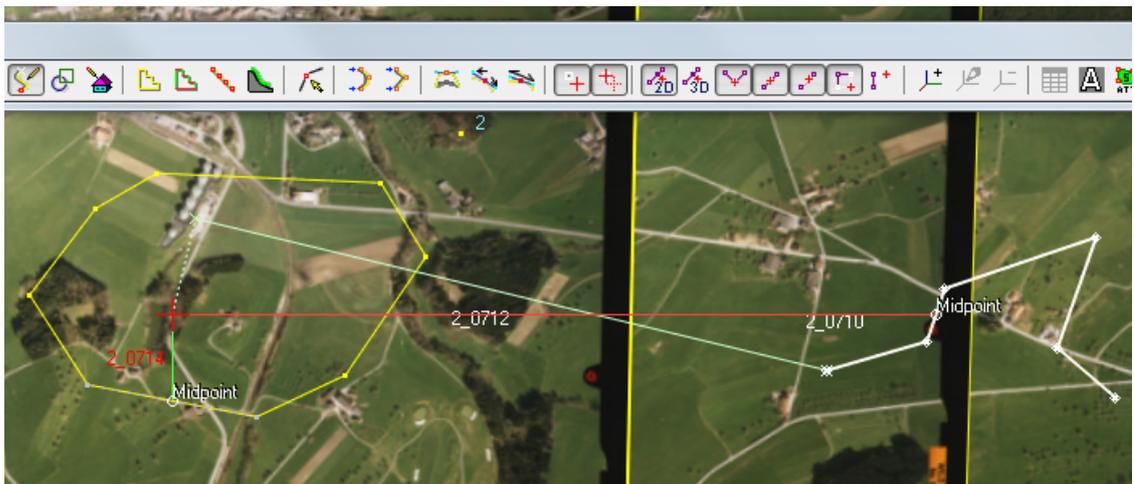


Fig. 24. Working in the manual snapping to coordinates mode

3.5. Creation of “stereo quality” map

The system allows to estimate stereo quality for images block that contains stereopairs. The principle of building a stereo “quality maps” is as follows. Stereopair with the best stereo quality is automatically formed from images. This stereopair is then used by the system for evaluation of other characteristics of other stereopair, as well as their quality score.

Stereo “quality map” is a grid which nodes are colored in images overlap areas according to assigned score.



To create stereo “quality map” it is necessary to complete block adjustment step (see the “[Block adjustment](#)” User Manual).

To create stereo “quality map” perform the following actions:

1. Select **Grid › Properties** to create a grid. After that the **Grid** layer creates in the Manager and the **Grid properties** window opens.

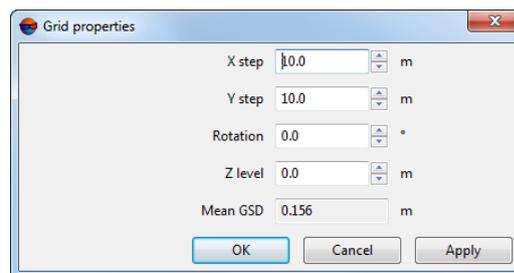


Fig. 25. Regular grid parameters

2. Set a grid step by X and Y in the **X step** and **Y step** fields.



The less the grid step, the more time is needed for creating the map of stereo quality.

3. Click OK. The grid is displayed in 2D-window on the images block as a set of nodes of the same colour according to specified step by X and Y.
4. Place marker to overlap area on any stereopair of images block in 2D-window.
5. Choose **Vectors › Create stereo quality map**. The **Select stereopair** window opens.

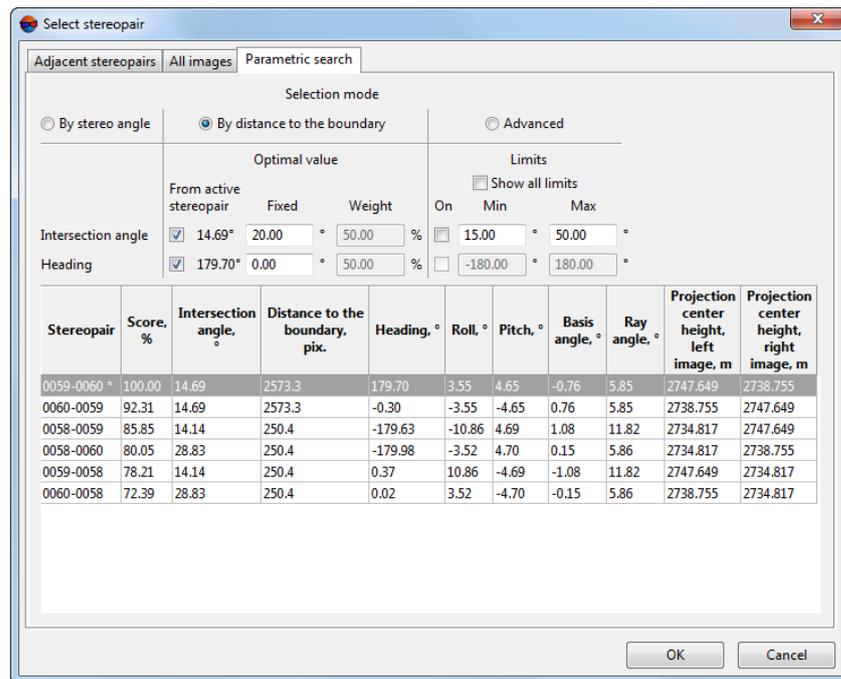


Fig. 26. Parametric method of stereopair selection

Stereopair table displays a list of all stereopairs found in marker position. The system selects automatically an optimal stereopair – block stereopair with the best stereoscopic effect. This stereopair is assigned the highest rating.

For each stereopair in the table the following parameters values are shown:

- **Score, %** – a score of stereo quality for block stereopairs;
- **Intersection angle, degrees** - an angle between photographing beams at the current terrain point (in marker position);
- **Distance to the boundary, pix.** - the shortest distance from the current marker position to the stereopair boundary;
- **Heading, degree.** - rotation angle of airframe in horizontal plane measured from the north direction (countdown of positive angles counter-clockwise when viewed from above);
- **Roll, degree.** - rotation angle (roll angle) of aircraft in relation to roll axis;
- **Pitch, degree.** - rotation angle of aircraft to main transverse axis of inertia or angle between aircraft roll axis and horizontal plane;
- **Basis angle, degree.** - angle between photographic image base and coordinate system plane;

- **Ray angle, degree.** - angle between ray and coordinate system plane;
 - **Projection center height, left image, m** - projection center height for left image, in meters;
 - **Projection center height, right image, m** - projection center height for right image, in meters;
6. [optional] To select an optimal stereopair manually perform the following actions:



It is not recommended to select parameters manually for VisionMap A3 projects.

1. In the **Selection mode** section specify one of the following ways of optimal stereopair selection:



Mode of active stereopair selection and configuring of selection parameters leads to recalculating of stereo quality score of all stereopairs in the table.

- **By stereo angle** - allows to select an active stereopair by optimal or specified stereo angle;
 - **By distance to the boundary** - allows to select an active stereopair by distance from current point in marker's position to stereopair's boundary;
 - **Advanced** - allows to find an active stereopair which features satisfy extended set of specified parameters.
2. [optional] Specify optimal parameters values for selected mode in the **Optimal value** section. To configure parameters use calculated value from active stereopair or specify fixed value (with indication of weight percentage for the advanced mode).
 3. [optional] Define a range of acceptable values of specified parameters in the **Limits** section. The system suggests by default to specify limits (minimal and maximal values) for stereo angle. To define a range of acceptable values of other parameters set the **Show all limits** checkbox on.
7. Click OK. After that the system generates stereo quality map in 2D-window and the new *Stereo quality map* layer appears in the *Manager*.

The layer is a grid, which each node is assigned the following [attributes](#) values, corresponding to selected parameters of the table:

- **quality** – quality **score** assigned to the stereo, depending on which a node in images overlap areas is colored;

- `st_ang` – **angle of stereo** between photographing beams at the current terrain point (in marker position), corresponds to the table parameter;
- `heading` – **heading**, rotation angle of airframe in horizontal plane measured from the north direction (countdown of positive angles counter-clockwise when viewed from above);
- `roll` – **Roll**, degrees;
- `pitch` – **Pitch**, degrees;
- `basis_roll` – **Basis roll**, degrees;
- `nadir_ang` – **Ray angle**, degrees;
- `bounds_dist_pix` – **Distance to boundary**, pix;
- `overlap_pix` – overlap value, pix;
- [for central projection images only] `z_l`, `z_r` – **projection center elevation** for the left and right image, in meters;
- `code_im_l`, `code_im_r` – codes of left and right images, that compose a stereopair, according to assigned code in the **Catalogue of exterior orientation parameters** (see the “[Aerial triangulation](#)” User Guide).

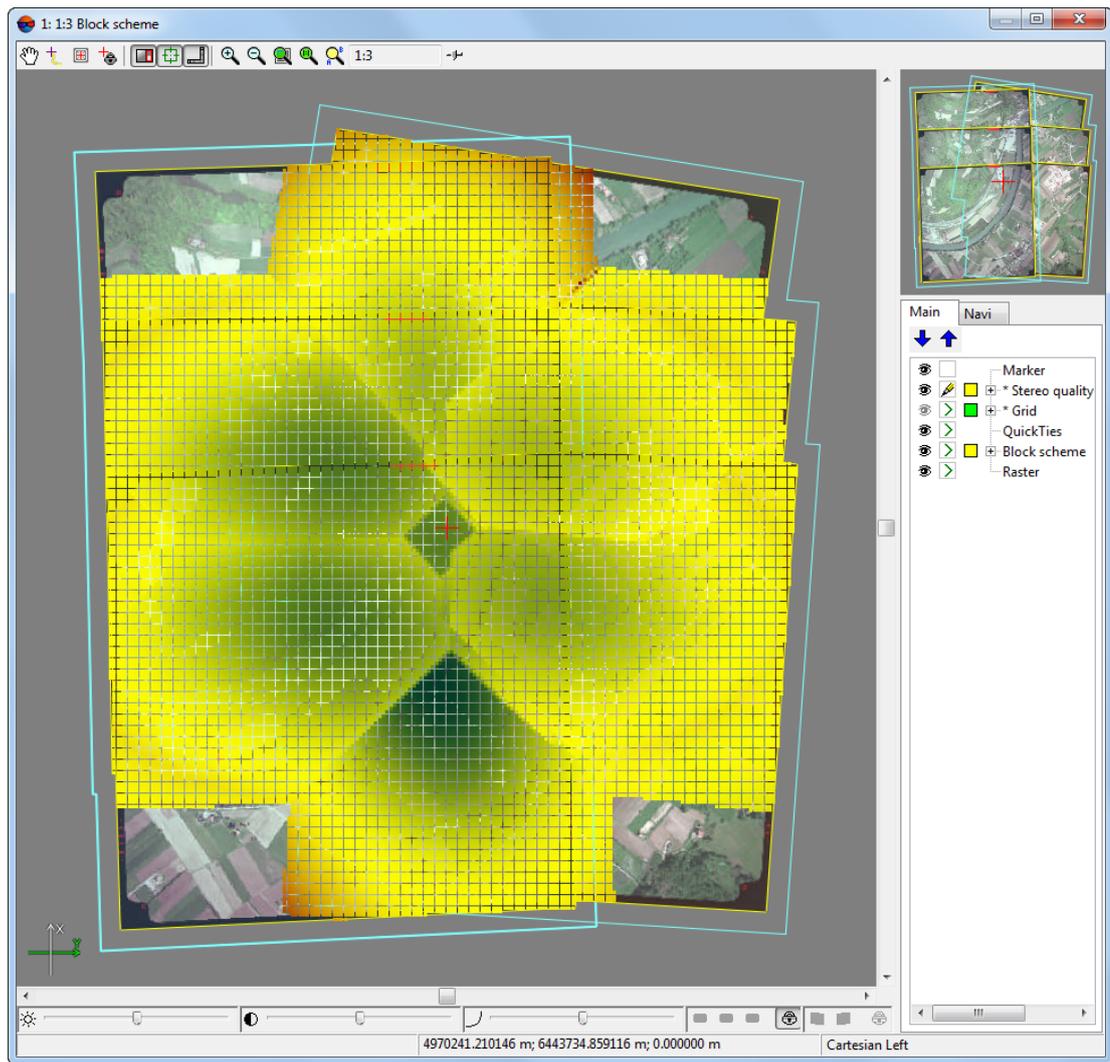


Fig. 27. Stereo quality map

3.6. Measurements on images

The system provides possibility to perform measurements on images.

To go to measurements mode use the **Measurements** window.

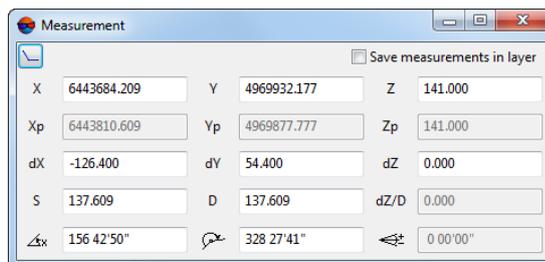


Fig. 28. The "Measurements" window

The window contains fields with marker coordinates values:

- X – marker X geodetic coordinate;
- Y – marker Y geodetic coordinate;
- Z – marker Z geodetic coordinate;
- X_p – marker X_p geodetic coordinate;
- Y_p – marker Y_p geodetic coordinate;
- Z_p – marker Z_p geodetic coordinate;
- dX – current segment incrementation by X ;
- dY – current segment incrementation by Y ;
- dZ – current segment incrementation by Z ;

Besides, the **Measurements** window contains fields with values of the following parameters of segment:

- S – a length of segment;
- D – a length of horizontal distance (projection on a plane) of segment by Z ;
- dZ/D – a value of segment slope (Z increment ratio to the horizontal distance);
-  – direction of current segment relative to X axis;
-  – direction of current segment relative to previous one;
-  – vertical angle of current segment.

Do the following actions to perform measurements:

1. Choose **Window > Measurements window (Ctrl+Alt+D)** or click the  button of the main toolbar to turn on the measurements mode. The *Marker* layer becomes active and the **Measurements** window opens.

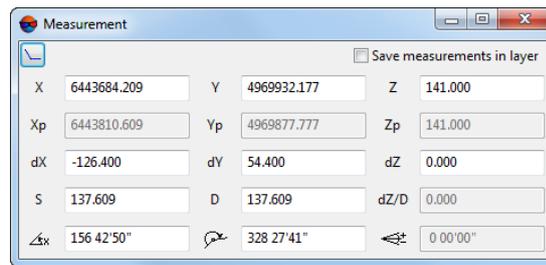


Fig. 29. The “Measurements” window

2. [optional] To save measurements to separate layer as vectors set the **Save measurements in layer** checkbox.



The layer with measurements is used for example as error vectors to convert vector objects (see [Section 10.1.4](#)).

3. Place marker to start point of measurement and press **Insert**.



During measuring the system creates temporary line (“rubber line”), that disappears after exit from measurements mode. To start temporary line creation click the  button.

4. Use the **Page Up** and **Page Down** hotkeys or rotate mouse wheel to set marker by Z.

5. Place marker to next point of measurement and press **Insert**. Parameters of created segment are displayed in the **Measurements** window.



Measurements are performed between current marker position and the last point where the **Insert** key was pressed.



The system provides possibility to input using keyboard marker geodetic coordinates and segment parameters to fields of the **Measurements** window. Marker moves to a point with specified coordinates and segment parameters after pressing the **Enter** key.

6. To complete measurements, close the **Measurements** window.



To leave the *Marker* layer active, close the **Measurements** window holding pressed **Ctrl** key.



The system provides possibility to make measurements both in 2D-windows during stereo vectorization, and in the **Points measurement**.

4. Vector layer creation

There are two vector layer types supported by the program:

- *vector layer without classifier* – is a vector objects layer without thematic classification;
- *vector layer with classifier* – is a vector objects layer assigned to a classifier;

To create a vector layer without classifier select **Vectors** > **Create layer**. After that the *Vector* layer is created in the Manager and it has a serial number (starting from the second).

To create a vector layer with classifier select **Vectors** > **Create layer with classifier**. After that the *Vector* layer is created in the Manager and it has a serial number (starting from the second) and the **Classifier** window opens.

5. Vector objects

5.1. The “Vectors” toolbar

For quick access to functions of vector objects creating and editing, and also to change modes with vector objects work the system provides the **Vectors** additional toolbar, which buttons partly duplicate the **Edit** menu items. To show the **Vectors** toolbar choose **Window** > **Toolbars** > **Vectors**.

Table 4. The “Vectors” toolbar

Buttons	Function
	allows to enable point objects input mode (P) (see Section 5.3.1)
	allows to enable non-closed polylines input mode (L) (see Section 5.3.2)
	allows to enable polygons input mode (G) (see Section 5.3.3)
	allows to enable creating mode of polylines and polygons as smooth lines (see Section 8.6.2)
	allows to enable CAD-objects creating mode (see Section 5.3.5)
	allows to enable roofs creating mode (see Section 5.3.6)
	allows to enable orthogonal input mode of vector objects (see Section 5.3.4)
	allows to enable orthogonal input mode of vector objects for additional coordinate system (see Section 5.3.4)
	allows to enable streamline input mode of vector objects (see Section 3.4.4)
	allows to turn on tracing mode (see Section 3.4.3)
	allows to enable vertices editing mode (see Section 8.4.1)
	allows to convert selected broken lines to smooth ones (see Section 8.6.3)
	allows to convert selected smooth lines to broken ones (see Section 8.6.3)
	allows to recalculate automatically smoothing of curve line segments during editing (see Section 8.6.4)
	allows to enable curve check points editing (see Section 8.6.5)
	allows to preserve the smoothness during editing of check points (see Section 8.6.5)
	allows to select a vertex, located in marker area on a distance specified in the Swath field (Service > Settings > Vectors)

Buttons	Function
	allows to move marker to the selected vertex automatically (see the “Settings of vector objects display” chapter of the “General system’s parameters” User Manual)
	allows to turn on/off 2D multi-snapping mode (see Section 3.4.6)
	allows to turn on/off 3D multi-snapping mode (see Section 3.4.6)
	allows to turn on/off Snapping to points mode (see Section 3.4.6)
	allows to turn on/off Snapping to medians mode (see Section 3.4.6)
	allows to turn on/off Snapping to lines mode (see Section 3.4.6)
	allows to turn on/off Perpendicular snapping mode (see Section 3.4.6)
	allows to turn on/off Snapping to coords mode (see Section 3.4.6)
	allows to create additional (user) coordinate system which is used as a helping vectorization tool together with Snapping to coords function: (see Section 8.8)
	allows to change default axes direction of additional coordinate system (see Section 8.8)
	allows to delete additional coordinate system (see Section 8.8)
	allows to hide/show the classifier window (see Section 6)
	allows to hide/show the objects attributes window (see Section 7)
	allows to open window that allows to choose autofilled layer attributes (see the Section 7.3.4)
	allows to refresh values of autofilled attributes (see Section 7.3.4)
	allows to calculate density of canopy

5.2. Types of vector objects

The system supports the following types of 3D vector objects:

- *point* – point 3D objects, defined in the space by X, Y, Z coordinates (see Section 5.3.1);
- *polyline* – closed/opened broken line or smooth curve, which consists of vertices connected by segments – straight or curve lines (see Section 5.3.2);
- *polygon* – an areal object, which boundaries are closed polyline (see Section 5.3.3);
- *CAD-objects* standard geometric figures, for example, ellipse, circle, rectangle, arc (see Section 5.3.5);

During vector objects creation use the tools for stereomarker managing (see Section 3.4).



The system provides possibility to synchronously display marker position in multiple opened windows for created vector objects. To do this use the **Edit > Sync markers** menu item.

To increase vectorization performance the system provides possibility to use special 3D or multibutton mice, as well as to use programming of buttons of usual mouse to perform particular operations (see the “General system’s parameters” User Manual).

To draw or edit vector objects, create, load or make active vector layer in the Manager panel.

For quick access to modes and functions of vector objects editing, use buttons of the **Vectors** additional toolbar (see [Section 5.1](#)).

5.3. Creation of vector objects

5.3.1. Points creation

Perform the following actions for creating a point:

1. Choose **Edit › Vectors create mode › Points (P)** or click the  button of the **Vectors** additional toolbar to turn on points creation mode.
2. Place marker to selected point on image in 2D-window.
3. Press **Insert** to create a point.

5.3.2. Polylines creation

Perform the following actions for creating a polyline:

1. Choose **Edit › Vectors create mode › Polylines (L)** or click the  button of the **Vectors** additional toolbar to turn on polylines creation mode.
2. For each polyline vertex perform the following actions:
 - place marker to selected point on image in 2D-window;
 - press **Insert** to create a vertex.
3. Press **Enter** or **Esc** to complete polyline creation.

To close a polyline while its creation select **Vectors › Topology › Close polyline** or use the **Shift+C** hotkeys after input of the last vertex (see [Section 11.4.1](#)). See description of orthogonal polyline creation in the [Section 5.3.4](#).

5.3.3. Polygons creation

Perform the following actions for creating a polygon:

1. Choose **Edit › Vectors create mode › Polygons (G)** or click the  button of the **Vectors** additional toolbar to turn on polygons creation mode.
2. For each line vertex:
 - place marker to selected place on image in 2D-window;

- press **Insert** to create a vertex.

3. Press **Enter** or **Esc** to close polygon and end its creation.

See description of orthogonal polygon creation in the [Section 5.3.4](#).

5.3.4. Creation of orthogonal objects

During vectorization of some types of vector objects (buildings, for instance) polyline or polygon should be composed of segments connected to each other at right angles.

To do this use the following modes of vector objects creation:

- Orthogonal mode;
- Orthogonal mode for [additional coordinate system](#);
- **Snap to coordinates** mode.



These modes are used during creation of both polylines and polygons (see [Section 5.3.3](#) and [Section 5.3.2](#)).

In order to enable orthogonal mode of vector objects creation use one of the following ways:

- if it is necessary to make part of a line with right angle, when you enter the next line segment, press and hold the **A** key; to continue the line in usual mode, release the key;
- click the  button of the **Vectors** additional toolbar or choose **Edit > Orthogonal mode** to enable continuous orthogonal vectorization mode.



To close a polyline in orthogonal mode after entering of the last vertex select **Vectors > Topology > Close polyline** or use the **Shift+C** hotkeys, and then press **Esc** (see [Section 11.4.1](#)).



In order to finish the vector object to a rectangular shape, after entering the last vertex use hotkeys **A+Enter** (or press **Enter**, if the orthogonal mode is on). As a result, the last vertex of a vector object is moved so that the object takes a rectangular shape.



To move the first vertex use the **A+Ctrl+Enter** hotkeys (or **Ctrl+Enter**, if the orthogonal mode is on).

In order to enable orthogonal mode of vector objects creation for additional coordinate system perform the following:

1. [create additional coordinate system and change its default axes direction](#);
2. click the  button of the **Vectors** additional toolbar or choose **Edit > Orthogonal mode in coordinate system** to enable continuous orthogonal vectorization mode in additional coordinate system.



Created vector objects will be orthogonal to the axes of the additional coordinate system, and their directions are user-defined.

In order to enable **Snap to coordinates** mode of vector objects creation use one of the following ways:

- choose **Edit** › **Snapping** › **2D snapping** or **Edit** › **Snapping** › **3D snapping** to enable continuous **2D snapping** or **3D snapping** mode (see [Section 3.4.6](#)). Choose **Edit** › **Snapping** › **Snap to coordinates** to enable continuous **Snap to coordinates** mode;
- press the **B** key to enable continuous **2D snapping** mode. Press the **M** key to enable continuous **Snap to coordinates** mode;
- click the  or  button of the **Vectors additional toolbar** to enable continuous **2D snapping** or **3D snapping** mode. Click the  button of the **Vectors additional toolbar** to enable continuous **Snap to coordinates** mode.

See the detailed description of working in **Snap to coordinates** mode in the [Section 3.4.6](#).

The system also allows to **edit** vector objects moving their vertices in directions parallel or perpendicular to the adjacent segments, as well as to move these vertices to the segments of the edited object (or the segments of the neighboring objects) towards the perpendicular to these segments using the [perpendicular snapping mode](#).

See the description of orthogonality control in the [Section 10.2.6](#).

5.3.5. CAD-objects creation

To create vector objects of standard geometric shape click the  button of the **Vectors additional toolbar**, or choose **Window** › **Toolbars** › **CAD objects** or choose **Edit** › **Vectors create mode** › **CAD objects**. The **CAD objects** window opens.

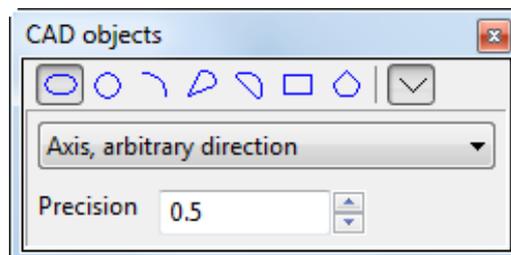


Fig. 30. Menu for CAD-objects creation

The  button allows to open the options bar for each object type, in accordance with which the object is created.

Table 5. Functionality of the “CAD objects” window

Buttons	Function
	<p>Ellipse creation ways:</p> <ul style="list-style-type: none"> • Axis, arbitrary direction – allows to set a size of one of axes; another axis is created at arbitrary direction from the specified one; • Axis, fixed direction – allows to set a size of one of axes; second axis is built strictly perpendicular to a given one; • Center, arbitrary direction – allows to set a center and a size of one of axes; another axis is created at arbitrary direction from the specified one; • Center, fixed direction – allows to set a center and a size of one of axes; second axis is built strictly perpendicular to a given one;
	<p>Round creation ways:</p> <ul style="list-style-type: none"> • 2 points – allows to specify a diameter of the round created; • Center, radius – allows to specify the round center and radius; • 3 points – allows to create a round using three points.
	<p>Arc creation ways:</p> <ul style="list-style-type: none"> • 3 points – allows to create a arc using three points, the first point is the beginning of the arc; • Center, arbitrary radius – allows to draw an arc with arbitrary radius, the first point is the center of the arc; • Center, fixed radius – allows to draw an arc with fixed radius, the first point is the center of the arc;
	<p>Sector creation ways:</p> <ul style="list-style-type: none"> • Center, arbitrary radius – allows to set center, drawing direction and arc radius; • Center, fixed radius – allows to set center, arc radius and size;
	<p>Segment creation ways:</p> <ul style="list-style-type: none"> • Start, end, arc – allows to set start and end points of straight part of segment and arc size; • 3 points – allows to create segment using three points, the first point is the beginning of the segment; • Center, arbitrary radius – allows to set center, drawing direction and arc radius; • Center, fixed radius – allows to set center, arc radius and size;
	<p>Rectangle creation ways:</p>

Buttons	Function
	<ul style="list-style-type: none"> • 3 points – allows to specify three vertices of the rectangle; • Axis, arbitrary direction – allows to set a center and a size of one of sides; the second size is created at arbitrary direction from the specified one; • Axis, fixed direction – allows to set a center and a size of one of sides; second axis is built strictly perpendicular to a given one;
	Polygon creation ways: <ul style="list-style-type: none"> • 2 points – allows to create a polygon using two specified points. • Center, radius – allows to set center, drawing direction and polygon radius;

 Creation of any type of CAD-objects starts from pressing the **Insert** key.

Perform the following actions to create CAD-object of selected type:

1. Click one of buttons of the **CAD objects** window toolbar.
2. [optional] Specify approximation accuracy in the **Precision** field.

 CAD-objects, presented in the form of curves are approximated by broken lines, that is why, curvature of the object can be measured by approximation precision, that is maximal distance from broken line segment to the curve between its two closest vertices. Creation precision could be specified for objects that contain curvy parts (ellipse, round, arc, sector, segment). This parameters default value is – 0.5, in measurement units of current project.

3. [optional] Specify number of polygon vertices (when creating polygons). By default creates polygons with 3 vertices.

 It is possible to create polygon with up to 500 vertices.

4. Press **Insert** to start create object.
5. Move mouse and press **Insert** to specify parameters and size of the object.
6. To complete drawing press **Enter**, to cancel object creation – **Esc**.

 To create in a layer with classifier linear CAD-objects (arcs), select in classifier type (L), if it is necessary to create areal object – select type (C) (see [Section 6](#)).

Conversion of vector object to geometric shape is described in [Section 11.4.3](#).

Adding an arc to a polyline

The system allows for adding an **arc**-type CAD-object to a polyline (as its **fragment**) directly during polyline creation. As a result, the system allows to immediately create a single vector object, partially eliminating appropriate **topological operations**.

To do this, perform the following:

1. Choose **Service** › **Settings** or click  button of the main toolbar. In **Settings** window select **Vectors** tab and set the **Join polylines and arcs** checkbox;
2. Start polyline **creation**;
3. Not finishing polyline creation, select an **arc** object by clicking the appropriate button on the **CAD objects** toolbar;
4. Switch on the **Snap to points** mode (**2D snapping** or **3D snapping** depending on the need);
5. Using enabled **Snap to points** mode, place the marker at the location of the latest input vertex of the created polyline by clicking the **left mouse button**. The End label appears in the vicinity of this vertex;
6. Press **Insert** to start create arc.
7. Move mouse and press **Insert** to specify parameters and size of the arc.
8. To complete arc creation press **Enter**. A single vector object is created, which is a polyline with an arc as an end fragment;



The system allows to go on creating this polyline as a single vector object using **standard topological operations**. To do this, perform the following:

9. Switch off the CAD objects creation mode;
10. [optional] Switch off snapping mode;
11. [optional] Clear the **Join polylines and arcs** checkbox in the **Vectors** tab of the **Settings** window;
12. **Select** polyline in 2D-window;
13. Place marker in vicinity of vertex of polyline fragment beginning, to which it is necessary to add new vertices;
14. Choose **Vectors** › **Topology** › **Object fragment** › **Select start point of fragment (Alt+S)**;

15. Add more vertices to continue creation of polyline;

16. Press **Esc** to complete polyline editing.

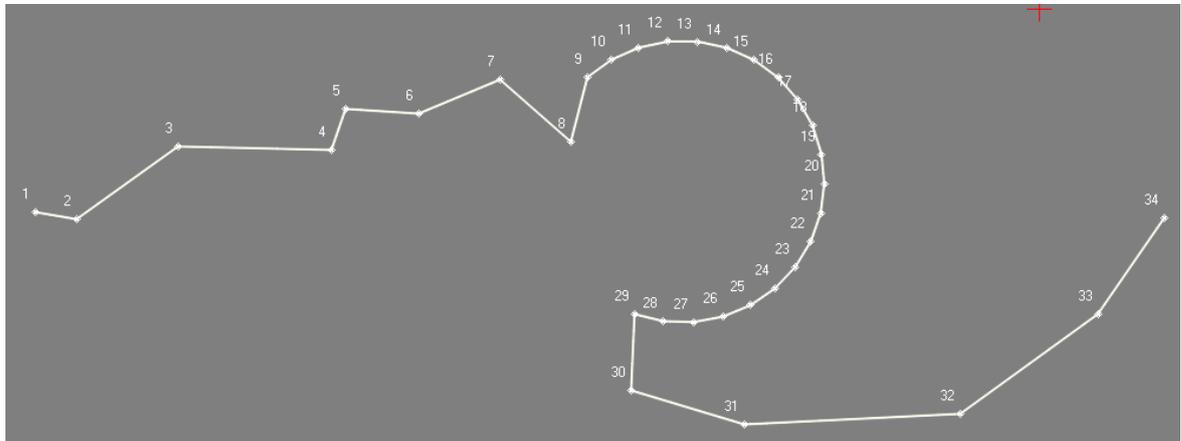


Fig. 31. A polyline with an arc as its fragment

5.3.6. Roofs creation

The system allows to create the following types of roofs:

- **Shed** – rests on two outer walls of varying heights;
- **Flat** – rests on outer walls of the same height;
- **Gable** – rests on two outer walls of the same height;
- **Butterfly** – gable roof with slopes directed “inside” to collect moisture;
- **Mansard** – single-level with gambrel roof;
- **Hip** – gable roof with ridge beam;
- **Gambrel** – gable roof, each plane slope is 2 rectangles connected at an obtuse angle;
- **Combi** – consists of elements of a mansard and attic roofs;
- **Steeple** – roof with highly elongated cone or pyramid;
- **Hangar** – arch-type elongated roof;
- **Cone** – **Steeple** with an arbitrary number of faces;
- **Parapet** – low barrier at the edge of building roof. The system allows to create such type of roofs in **manual** and **semiautomatic** mode.

Perform the following actions for creating a roof:

1. Open a stereopair for vectorisation and turn on **stereo mode**.
2. Click the  button of the **Vectors** toolbar, or choose **Window › Toolbars › Roofs** or choose **Edit › Vectors create mode › Roofs**. The roofs creation mode turn on and the **Roofs** window opens.

In the left part of **Roofs** window a list of roof types is placed. In the right side – a figure of selected roof type and an order of roof corners to be drawn (1, 2, 3 etc.). For **Hangar**, **Cone** and **Parapet** roof types in the right side of the window fields to input additional parameters are placed.

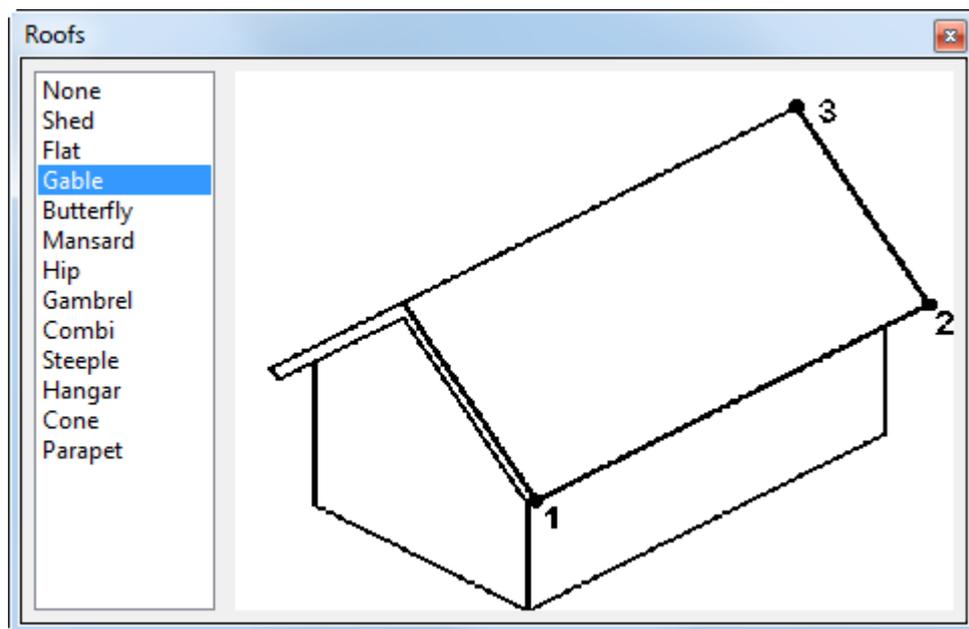


Fig. 32. Roofs types

3. Select desirable roof type in the **Roofs** window.
4. Place marker to roof lower corner and press **Insert**.
5. Sequentially place marker to two other corners of the roof and press **Insert** in each corner.
6. [optional] While creating a complex shape roof add missing points to draw the roof ridge.
7. Rotate mouse wheel to set the ridge height.



While creating a **Shed** roof type the system allows to start drawing from its top (like in a figure of **Roofs**) or from its bottom.



If to set a height of **Gable** rooftop less than a height of its bottom corner, the roof is rebuilt automatically (a rooftop and the bottom corner will «change places»). Respectively for a **Butterfly**, roof type a converse is true.

8. [optional] Edit a width of the roof keeping **left mouse button**.
9. To complete editing press **Insert**.



Roof vertices edit in the same way as any [vector objects](#).



To exit roofs creation mode, close the **Roofs** window.



Is it possible to view DTM (including vector objects) in a 3D-space in mono or stereomode (see the “Process in 3D-window” chapter of the “[General information](#)” User Manual). To perform visual control of roofs creation choose **Window > 3D window**. The **3D window** opens.

Creating Hangar roof type

Perform the following actions to create a **Hangar** roof:

1. Open a stereopair for vectorisation and turn on [stereo mode](#).
2. In the **Roofs** window choose the **Hangar** roof type.

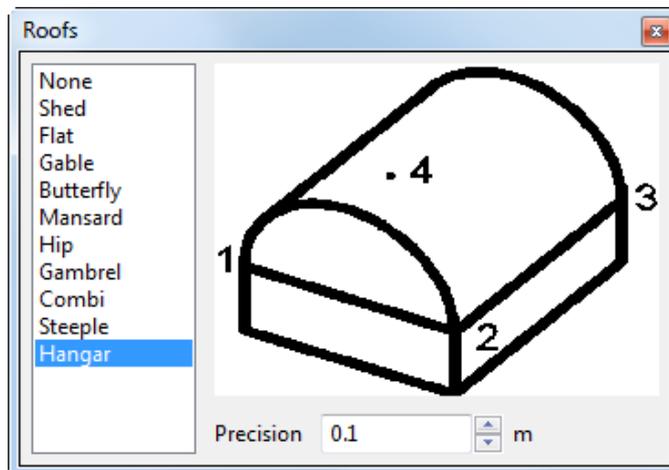


Fig. 33. Hangar roof type

3. In the **Precision** type set the precision of arches cycle approximation (in meters).
4. Place marker to roof lower corner and press **Insert**.
5. Place marker to the second lower corner (to set width of roof) and press **Insert**.
6. Place marker to set the length of roof and press **Insert**.

7. Set marker inside of roof contour.
8. Rotate mouse wheel to set the ridge height.



The system generates approximation lines during height setting.

9. To complete editing press **Insert**. To exit roofs creation mode, close the **Roofs** window.

Creating Cone roof type

To create **Cone** roof type, perform the following:

1. Open a stereopair and turn on [stereovectorization mode](#);
2. In **Roofs** window select **Cone** roof type;

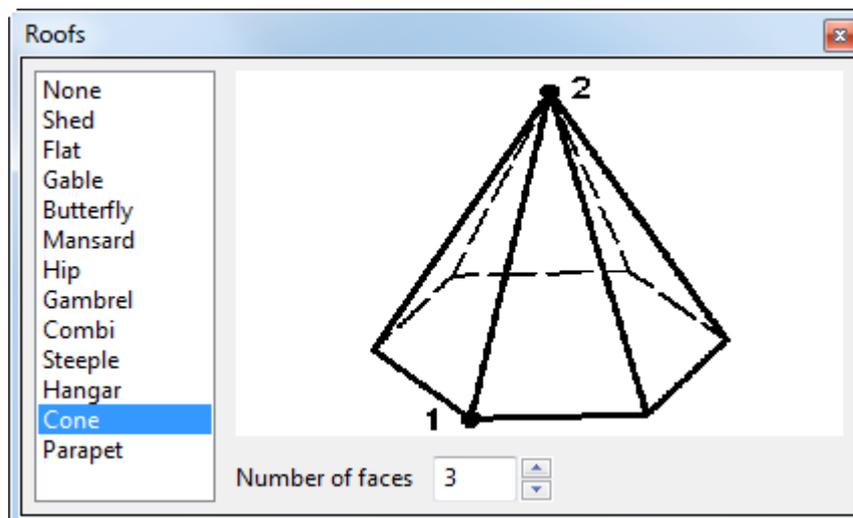


Fig. 34. Roof type "Cone"

3. Input **number of faces**;
4. Set marker in the bottom corner of the roof and click **Insert** key;
5. Set marker in the rooftop;
6. Rotate a mouse wheel to set a height of the rooftop;



If to set a height of rooftop less than a height of its bottom corner, the roof is rebuilt automatically (a rooftop and the bottom corner will "change places").

7. [optional] Edit a size and position of the roof keeping **left mouse button**;
8. To complete editing click **Insert** key. To exit Roof creation mode, close **Roofs** window.

Creating Parapet roof type in manual mode

To create **Parapet** roof type in manual mode, perform the following:

1. Open a stereopair and turn on [stereovectorization mode](#);
2. In **Roofs** window select **Parapet 1** roof type;

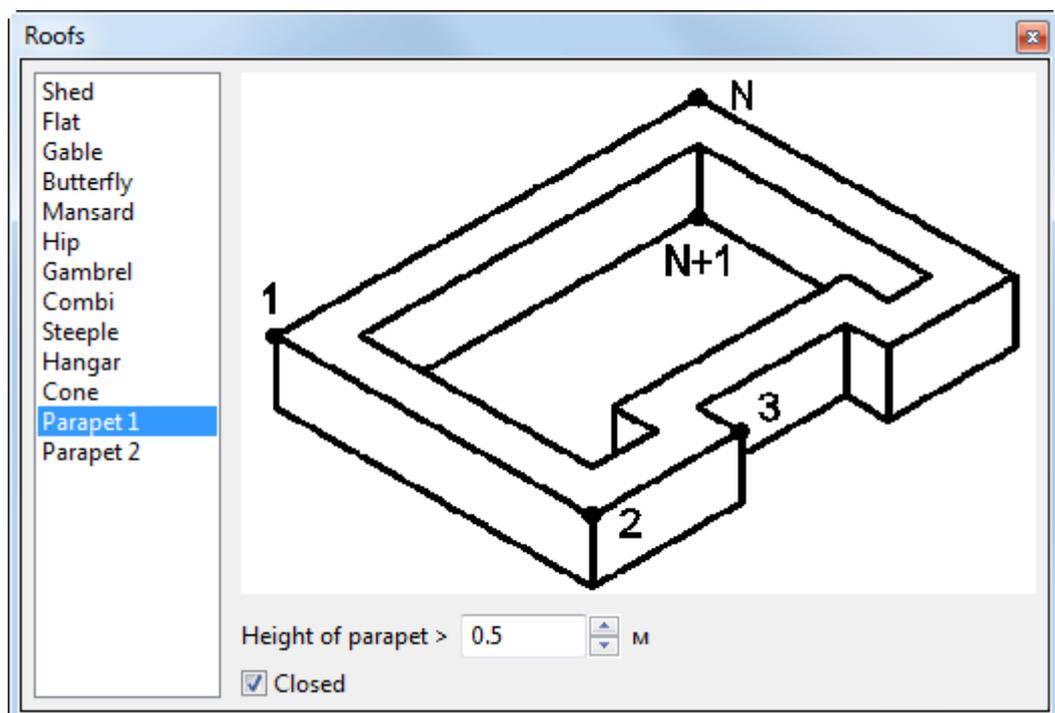


Fig. 35. Roof type "Parapet"

3. [optional] Turn off a checkbox **Closed** to create non-closed parapet;
4. Set a minimum parapet height with inputting **Height of parapet >** value;



A meaning of **Height of parapet >** parameter is the following. A difference of heights between point "N" and "N+1" is no less than <...> m. A height of parapet is set by user while stereovectorization later but no less than input value, otherwise a parapet will not be built.

5. Move a marker to parapet corners step by step and click **Insert** key N times;



Do not move a marker after corner “N” is specified.



A parapet shape is not limited by rectangle one. It can be a polygon with arbitrary number of vertices.

6. Once specified roof corner “N” with **Insert** key, *no moving marker*, set a *height difference* between points “N” and “N+1” while rotating mouse wheel.

After a height difference is over **Height of parapet >** value a parapet is closed between corners “1” and “N” (in case of creating closed parapet). If a height difference is less than **Height of parapet >** value again, a parapet will be unclosed.



Further parapet editing is impossible if specified height difference is less than **Height of parapet >** value.



In case of creating non-closed parapet, the system does not close it while specifying a height with rotating mouse wheel.

7. Set a position of point “N+1” (i.e. a width of parapet) with moving a marker;
8. [optional] If necessary, edit a width and a height of parapet with moving marker and rotating a mouse wheel respectively;
9. To complete editing click **Insert** key. To exit Roof creation mode, close **Roofs** window.

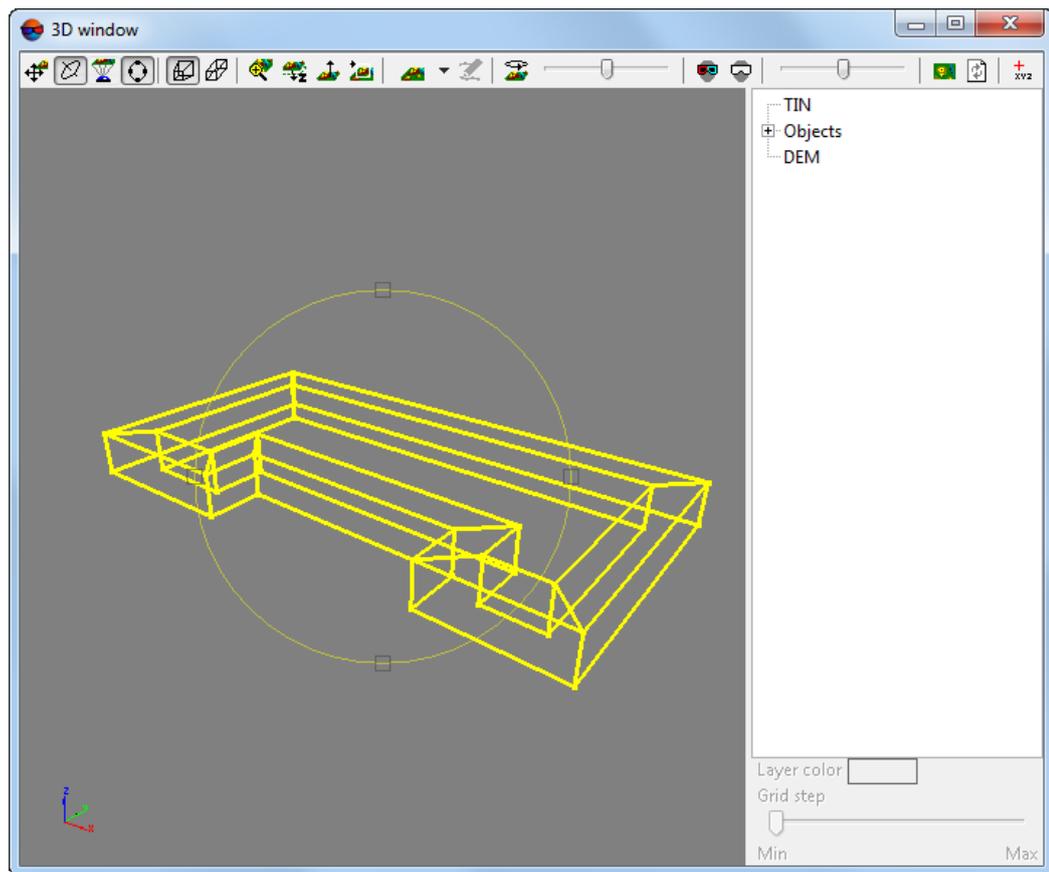


Fig. 36. Roof type “Parapet” in 3D-window

Creating Parapet roof type in semiautomatic mode

To create **Parapet** roof type in semiautomatic mode, perform the following:

1. Open a stereopair and turn on [stereovectorization mode](#);
2. In **Roofs** window select **Parapet 2** roof type;

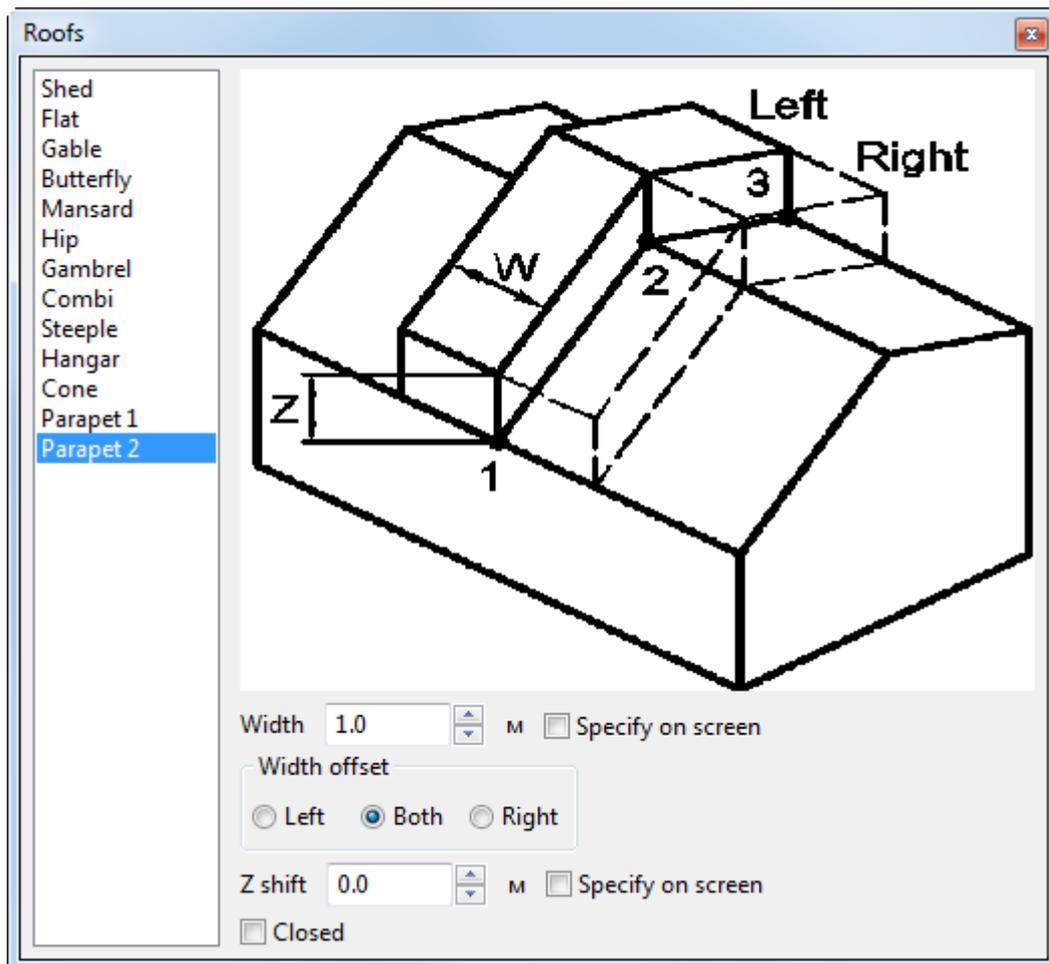


Fig. 37. Parapet-type roof, where: W is the parapet **Width**, Z is the parapet height, Left or Right is the parapet's position in relation to the polyline segments (between vertices **1**, **2**, **3**, and so on) which determine the position of the parapet in XY plane (see **Width offset** parameter).

3. Set the parapet's width (W) in meters using the following methods:
 - Enter the value of the parapet's width in the **Width** field;
 - Set the parapet's width using a mouse. To do this, perform the following:
 1. Set the **Specify on screen** checkbox;
 2. Set the start point of the interval which sets the parapet's width by **left mouse button** click;
 3. Move the marker and click the **left mouse button** to set the final point of the interval which sets the parapet's width. The interval defining the width of the parapet is displayed on the screen as a gray guide, and its size in meters is automatically displayed in the **Width** field;

4. [optional] If necessary, edit the parapet's width by moving the marker and clicking the **left mouse button**;
 5. Press **Enter** to set the parapet's width. The **Specify on screen** checkbox will be cleared automatically.
4. In **Width offset** section set the position of the parapet in relation to the polyline which determine the position of the parapet in XY plane:
- **Left** – the parapet will be placed to the left of the polyline;
 - **Right** – the parapet will be placed to the right of the polyline;
 - **Both** – the polyline will be the central axis of the created parapet.
5. Set the parapet's height (Z) in meters doing one of the following:
- Enter the parapet's height in the **Z shift** field;
 - Set the parapet's height using a mouse. To do this, perform the following:
 1. Set the **Specify on screen** checkbox;
 2. Clicking the **left mouse button**, turn on the height setting mode;

 Repeated **left mouse button** click resets the height value in the **Z shift** field to zero.
 3. Set the parapet's height rotating the **mouse wheel** (height in meters is automatically displayed in the **Z shift** field);
 4. Press **Enter** to set the parapet's height. The **Specify on screen** checkbox will be cleared automatically.
6. [optional] Set a checkbox **Closed** to create closed parapet;
7. Moving the marker stepwise in the XY plane and pressing the **Insert** button, create vertices which determine the position of the parapet in the XY plane according to the order in the scheme (vertices 1, 2, 3, and so on);
-  The polyline which determine the position of the parapet in XY plane is not displayed on the screen. The created parapet is displayed as gray polygons until the parapet is finished.
8. To finish the parapet creation, press **Enter**. The parapet is automatically heightwise shifted according to the value set in the **Z shift** field. In case of a closed parapet, the parapet's contour closes automatically.

-  To create a non-closed parapet, it is enough to enter two vertices.
-  To create a closed parapet, enter at least three vertices.
-  When creating a closed parapet, **self-intersection** of the polyline determining the parapet's position on the plane is not allowed. This is true also for the last segment, which is created automatically when the parapet closes (i.e. closes the polyline into a polygon).

9. [optional] To exit Roof creation mode, close **Roofs** window.

-  To create a parapet above the roof (as on the schematic image), perform the following:
 1. **Create** a roof (e.g. **gable**);
 2. Turn **snapping** mode on to provide exact spatial coincidence of the roof and parapet (e.g. **Snap to lines** and **Snap to coordinates** combination in 3D-snapping mode);
 3. "Abutting" to an eave or a hip using 3D-snapping, create a parapet in semiautomatic mode;

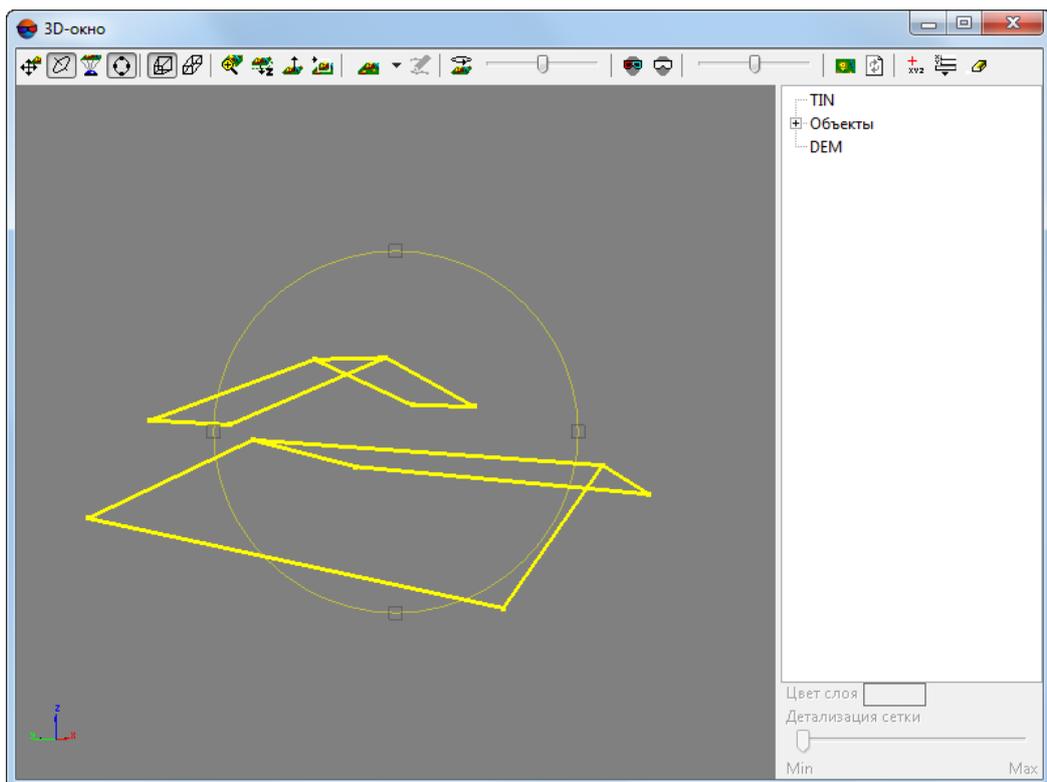


Fig. 38. A parapet above a **gable** roof created in semiautomatic mode

-  Parapets created in semiautomatic mode (unlike those created in **manual** mode) have no vertical hips.



The system allows to vary **Z shift** manually during parapet creation in semiautomatical mode. To do this, when creating vertices determining the parapet position (see item 6), move marker not only horizontally but also vertically (by rotating **mouse wheel**).

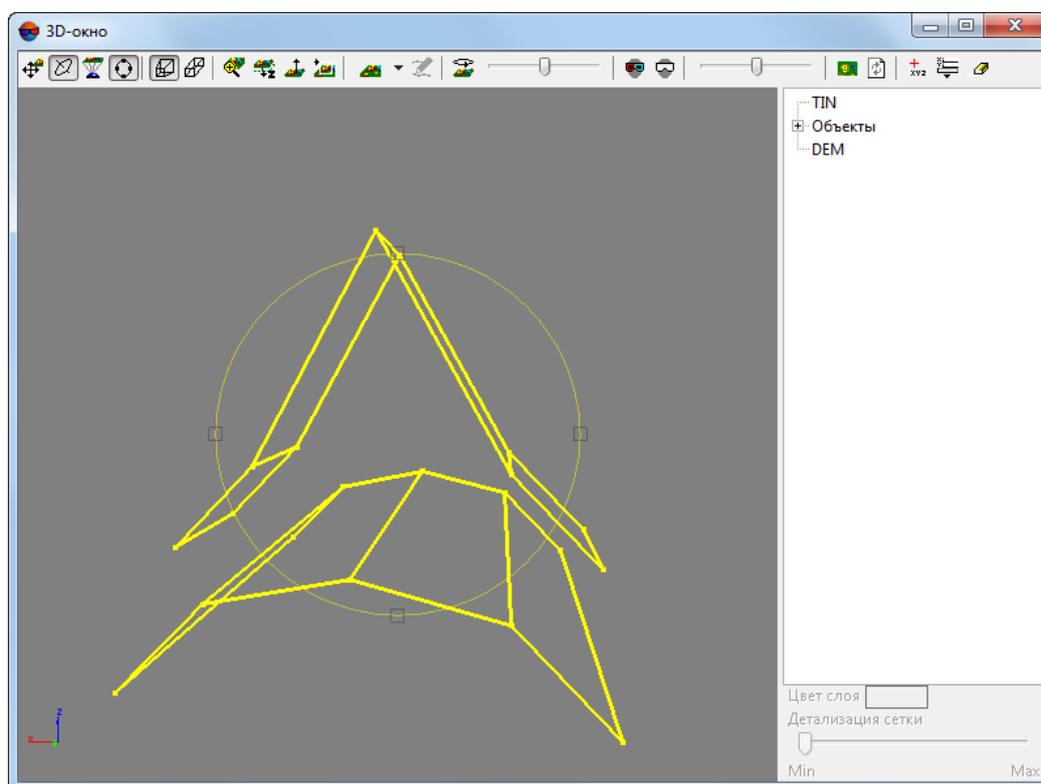


Fig. 39. A parapet above a **gambrel** roof in the 3D-window. **Z shift** of the parapet vertices above the roof hip is enlarged manually.



To change **Z shift** manually when creating a parapet vertex, you need temporarily disable **3D snapping** mode if it is used (e.g. by turning **2D snapping** mode on).

5.3.7. Vector object properties

To display vector object properties, select the object and choose **Vectors** › **Polyline properties** or use the **I** hotkey. The **Object properties** window contains the following parameters of 2D-object:

- number of vertices;
- maximal and minimal object coordinates separately and for each axes;
- length/perimeter;
- plain area (in case of polygon) – in project *coordinate system* or *on the reference surface*;



Reference surface (during baseline measurements) – level surface that coincides with the sea-level surface and is used for reducing the measurement results on the physical surface of the Earth.



A value of the area *on the reference surface* is calculated only when using *global* working coordinate system.

- length of polyline or length of polygon boundary projected on plane.

In the **Object vertices** section is displayed the list with numbers and coordinates (XYZ) of selected object vertices. The vertices are numbered in the order they were created during vectorization.

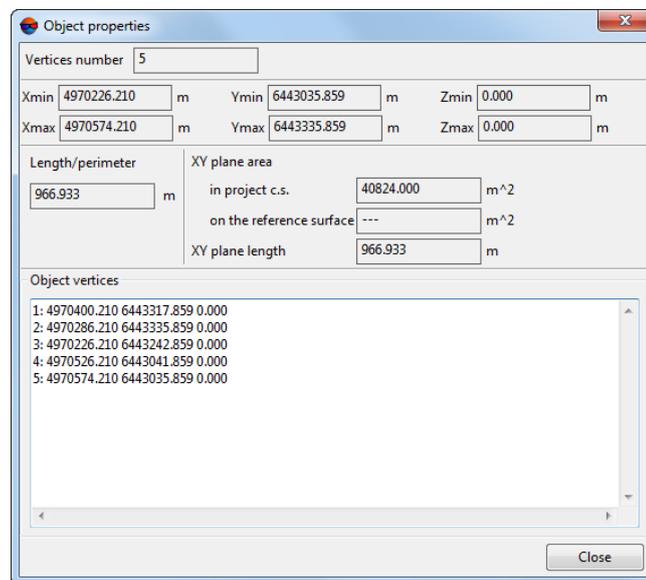


Fig. 40. The “Object properties” window

5.4. Vector objects loading

In order to load vector objects perform the following actions:

1. Choose **Vectors** > **Load** or click the  button of the main toolbar.

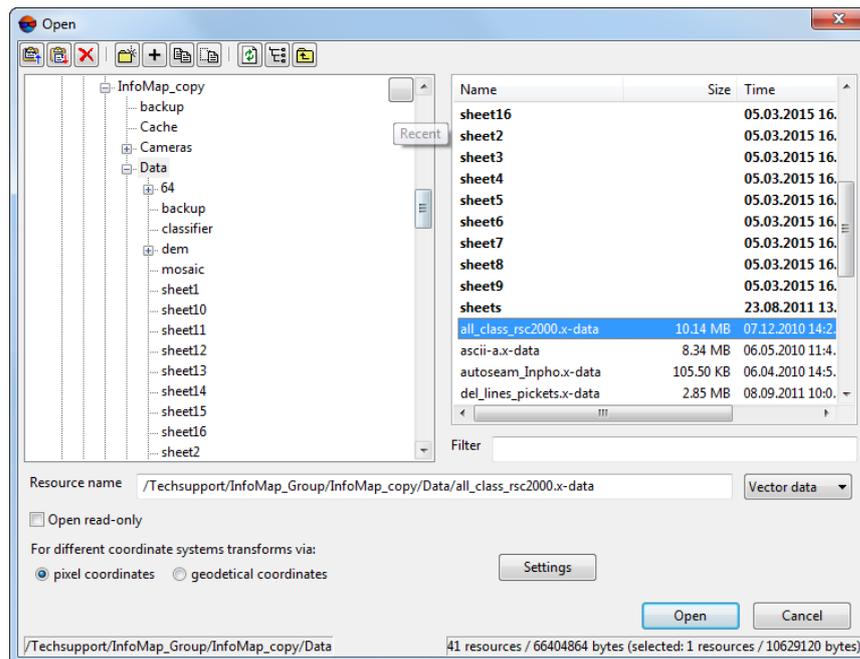


Fig. 41. Vector layer loading

2. Select one or multiple vector files with *.x-data extension.



After that when multiple files are selected the system suggests two ways of loading: to load all in the same layer or to load each file in a separate layer.

3. [optional] To disable saving and rewriting of selected file, set the **Open read only** checkbox on.
4. [optional] Select method of objects coordinates recalculation **For different coordinate systems transforms via** – using pixel or geodetic coordinates (see details in the “[General system’s parameters](#)” User Manual).
5. Click the **Open** button. If one or multiple vector layers are already loaded to active project, then during loading of new vector layer the window of loading type is opened.

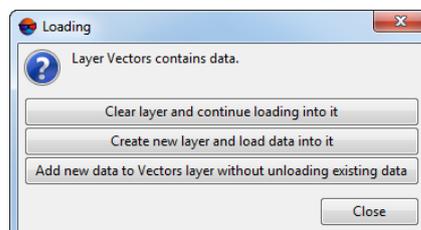


Fig. 42. Vector layer loading

The system provides the following variants of new layer loading to existing vector layer:

- **Clear layer and continue loading into it** – vector data of active layer is replaced by data from loading layer;
- **Create new layer and load data into it** – vector data is loaded to a new layer;
- **Add new data to Vectors layer without unloading existing data** – during loading vector data is added to objects of active vector layer.

When it is necessary to load two or more vector files at once, there is the following ways of loading:

- **Clear layer and load all files into it** – vector data of active layer is replaced by data from loading layers;
- **Load all into one new layer** – vector data is loaded to a single new vector layer;
- **Create separate layer for each file** – vector data of each file are loaded to separate layers;
- **Load all layers into Vectors without unloading existing data** – vector data of all files adds to objects of active vector layer.

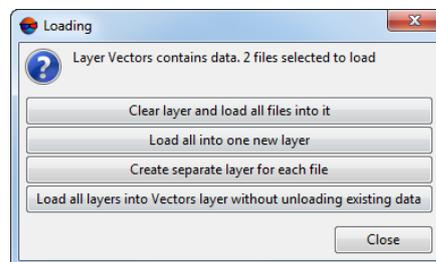


Fig. 43. Vector layer loading

Vector layers are displayed in Manager.

If vector data layer is saved to different coordinate system or in a project with different adjustment results, the system recalculates coordinates automatically. After loading produces information message about coordinates recalculation.

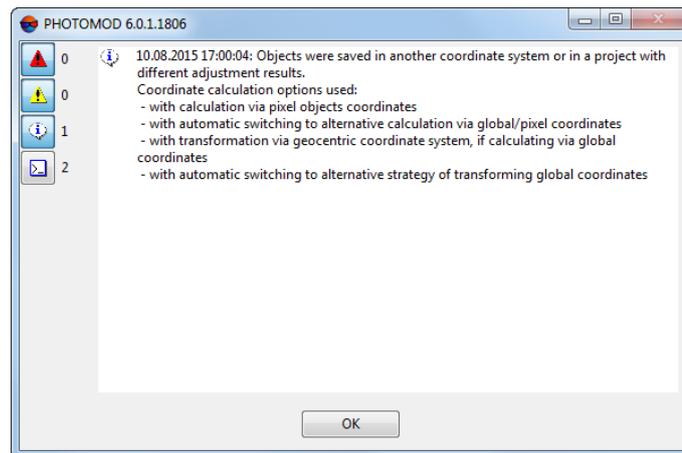


Fig. 44. Coordinates recalculating during vector layer loading

The system provides a possibility of quick access to recently loaded vector data files. To do this use the **Vectors** › **Recent** menu item. If necessary, the default coordinates recalculation uses.

To close a vector layer, select **Vectors** › **Close**. To close all vector layers, select **Vectors** › **Close all opened layers**.

5.5. Vector objects saving

To save (or rewrite) active vector data layer select **Vectors** › **Save** or click the layer name by mouse right button in the *Manager* and choose the **Save** in context menu.

To save active layer with new name select **Vectors** › **Save as** or click the layer name by mouse right button in the *Manager* and choose the **Save as** in context menu, specify file name and path in active profile resources.

To save just selected vector objects, select all vector objects that should be saved and select **Vectors** › **Save selected as**. After that vector objects are still associated with classifier.

The **Vectors** › **Recent** menu item allows to load the last saved version of active vector layer.

5.6. Displaying objects list

The system provides possibility to show list of active layer objects and their parameters.

Choose **Window** › **Objects list**. The **Objects list (Total objects)**.

N	Name	Code	Code name	Type	Size	Vert. number	image_title	image_name
0		1	1	C	1.0	43	R09_S85	file://PROJ...
1		1	1	C	1.0	57	R09_S86	file://PROJ...
2		1	1	C	1.0	56	R09_S87	file://PROJ...
3		1	1	C	1.0	57	R10_S05	file://PROJ...
4		1	1	C	1.0	44	R10_S06	file://PROJ...
5		1	1	C	1.0	18	R10_S06	file://PROJ...
6		1	1	C	1.0	49	R10_S07	file://PROJ...

Fig. 45. Objects list

The window displays the table containing number of objects, their codes, names, types, size and vertices number.



To sort points in the table by data of column, click on the name of this column.

If the **Auto refresh** checkbox is set on, table refresh automatically after any changes of objects on active layer.

The **Show attributes** checkbox allows to show in the table attributes of all layer objects. To show attribute click the  button after the checkbox is set on.

The  button allows to refresh window manually.

When the **Select object** checkbox is set on, an object selected in the table is highlighted in 2D-window, marker is placed to the first vertex of the object (in case of polylines and polygons), and the screen is centered by marker.

To save the list of objects to *.dbf file format, click the  button.

6. Classifier

6.1. The “Classifier” window

The classifier is a set of standard attributes, used for thematic objects classification.

All vector objects created in the classifier layer, are assigned to one of classifier’s record.

The system allows to create, edit, import and export a classifier. The **Classifier** window is used for this purpose.

Classifier is a tool to systematize vector objects. For example, during work with classifier there is a possibility to highlight all objects with the same code, delete them or display different objects classes using different colors.



Vector objects codes are used for [vectors export](#) to different exchange formats.

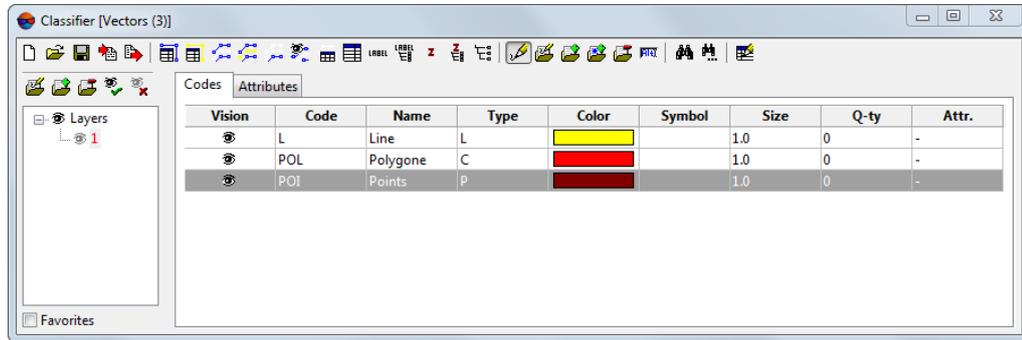


Fig. 46. The “Classifier” window

The left part of the window contains a list of project thematic layers, the right part – a table of vector objects codes, and includes three tabs: **Codes** and **Attributes**.

Table 6. Overview of the “Classifier” window toolbar.

Buttons	Function
	allows to close opened classifier and create a new one (see Section 6.2)
	allows to open created classifier
	allows to save changes to a classifier
	allows to open a window used to select a file to import codes to active classifier
	allows to open a window used to select a file to export codes to Panorama format with *. rsc extension
	allows to change a code of object selected in 2D-window (see Section 6.6 и Section 6.7)
	allows to assign a code to all non-assigned objects of the same type (see Section 6.6 and Section 6.7)
	allows to select all objects with this code (see Section 8.2.3)
	allows to select all un-assigned objects (see Section 8.2.3)
	allows to select all objects of the code group (see Section 8.2.3)
	allows to select all visible objects of the layer, except for those with disabled visibility (to disable object’s visibility, click the button to the left from a codename or a word); is used for batch export of all selected objects
	allows to display codes of vector object in a classifier when it is selected in 2D-window
	is used to scroll the codes list to selected code
	allows to set a note for active code (see Section 6.5)
	allows to set a note for all codes of a layer (see Section 6.5)
	allows to assign height values to object vertices, if after import these values were added to a classifier attributes (is used to import contour lines from MIF/MID and SIT formats, see Section 13.11)
	allows to assign height values to vertices of all objects, if after import these values were added to a classifier attributes (is used to import contour lines from MIF/MID and SIT formats, see Section 13.11)

Buttons	Function
	allows to display in the codes list all codes of vector objects, that belong to the selected layer
	allows to enable classifier editing mode (see Section 6.3)
	allows to open window used for editing of selected code or attribute (see Section 6.3)
	allows to open window used for creation of new code or attribute (see Section 6.3)
	allows to add selected code to a separate list of codes, that is used for easy search for frequently used codes. To display the list set the Favourites checkbox in the left lower part of the Classifier window
	allows to delete selected code or attribute from the classifier
	allows to assign selected hotkeys (Shift+1,2,3,4,5) to active vector object code, and to use them for code quick code display in classifier
	allows to search string By code or By code name0
	allows to perform further search for records in selected mode
	allows to load existing classifier during creation of a new layer with classifier by default

The **Attributes** tab in a classifier is used to create and edit attribute information.

On the **Codes** tab there is a table of classifier properties, that contains the following columns:

- **Visible** – shows visibility of the objects with selected codes in 2D-window;
- **Code** – an object code;
- **Name** – arbitrary text, unique name, for example, “Earth roads”;
- **Type** – object type: P – point, L – polyline, C – polygon (see [Section 6.2](#));
- **Color** – a color of object display;
- **Symbol** – ASCII symbol corresponding to objects code, is used for point objects and is selected from the symbols list in existing library;
- **Size** – real number, which describes the size of a vector object used in a real system of coordinates; for points this parameter determines the size of the characters, that display them on the image;
- **Q-ty** – number of objects with specified code;
- **Attr.** – number of object’s attributes (see [Section 7.1.1](#)).

To sort lines in the **Code**, **Name**, **Type** or **Q-ty** columns click on column name.

If the  to the left from the layer name or object code is active, objects of active code or layer are displayed in 2D-window.

To switch visibility mode of selected objects or layers in 2D-window, perform one of the following actions:

- click on the  icon to the left from the layer name or object code;
- use the  buttons to show and  button to hide the layer.

6.2. Classifier creation

Perform the following actions for creating a classifier:

1. Load or **create** vector layer with classifier.
2. Choose **Window > Classifier**. The **Classifier** window opens.



After first creation or loading layer with classifier the **Classifier** window opens automatically.

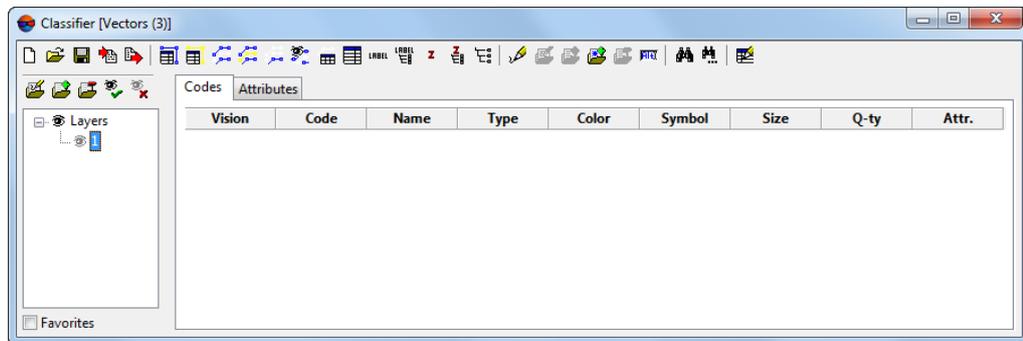


Fig. 47. The “Classifier” window

3. [optional] To create a new classifier instead of opened one click the  button.
4. Click the  button of the **Classifier** window additional toolbar to create a layer.

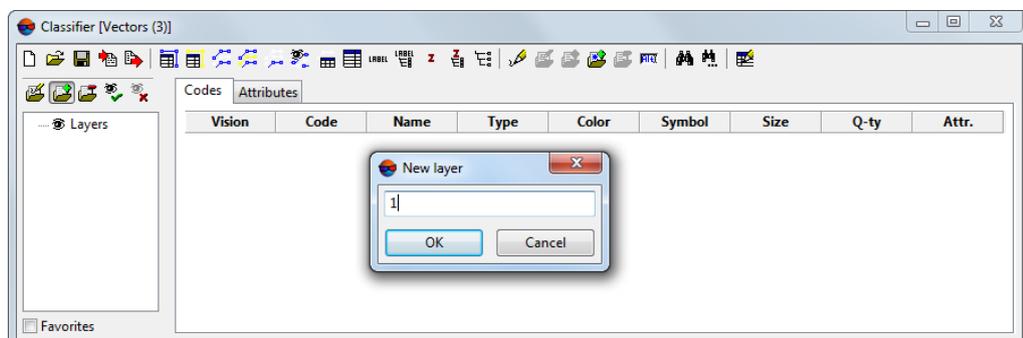


Fig. 48. Creation of layers list in classifier

5. Select layer to create new code.
6. Click the  button to set on the classifier edit mode.
7. Click the  button of the **Classifier** window main toolbar to create a new code in the classifier. The **Add code** window opens.

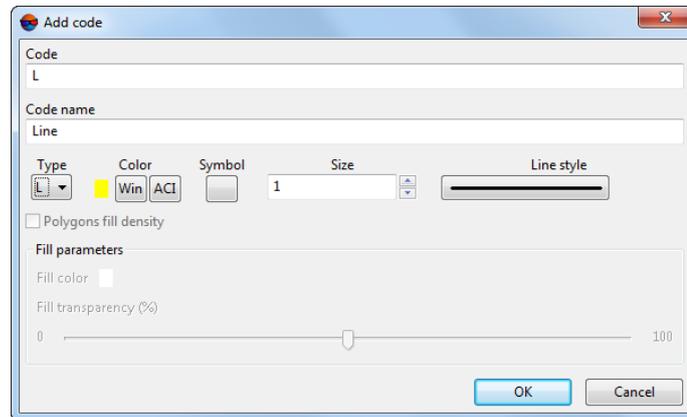


Fig. 49. Creating new code

8. Specify unique object **Code**, for example, its serial number or a numerical code.
9. Specify unique object **Code name**, arbitrary text (for example, “Water object”).
10. Select the object **type**:
 - for the point object select its type P and define the symbol (from standard symbols library), and symbol’s color (from standard color palette of *MS Windows*(the **Win** button) or from *AutoCAD program* palette (the **ACI** button)) and a size (in points in corresponding field).
 - for linear object select its type L, for polygon – type C; for these objects it is possible to specify a color of line (from standard color palette of *MS Windows* (the **Win** button) or from *AutoCAD program* (the **ACI**) button).
11. [optional] To change line style and size for polylines and polygons click on the **Line style** button.

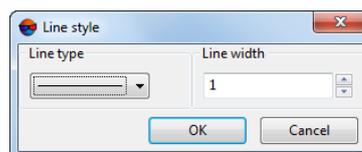


Fig. 50. Select line style



Selected line style is preserved during export of linear objects to DXF and DGN formats (see [Section 14.4](#) and [Section 14.5](#)).

12. [optional] To configure color and transparency of C type vector objects set the **Polygons fill** checkbox on. In the **Fill parameters** section define the following settings:

- **Fill color** – is used to select fill color;
- **Fill transparency (%)** – is used to setup fill transparency.



Fill color saves during [import/export](#) in *KML* format.

13. Click OK. Created code is added to the layer, which name is selected in the layers list, id objects are not divided into layers.

In order to save codes and layers classifier click the  button. Define file name and path in active profile resources. During following program launches the classifier is loaded automatically.

To load another classifier click the  button and select a file with classifier in active profile resources. For more details about classifier import see [Section 6.4](#).

To use existing classifier during new layer creation use the  button.

6.3. Classifier editing

In the **Classifier** window there is a possibility to edit a list of layers in the left panel and a list of codes and attributes – in the right one. For more details about attributes list editing see [Section 7.1.1](#).

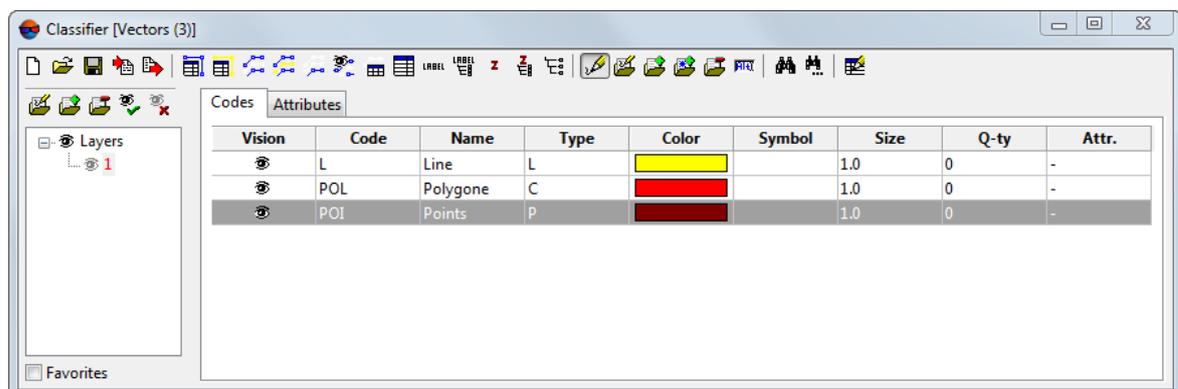


Fig. 51. The “Classifier” window

Above the **Classifier** window there is an additional toolbar, that includes the following buttons:

-  – allows to change selected layer name (**F2**).
-  To save changes press **Enter**, to cancel editing – **Esc**.
-  – allows to create new classifier layer;
-  – allows to delete selected layer from layers;
-  – allows to display all objects of a layer, including sublayers;
-  – allows to hide all objects of a layer, including sublayers;

To edit classifier it is possible to use the following buttons of the main toolbar of the **Classifier** window:

-  – allows to open the **Code editing** window (see [Section 6.2](#));
-  Change of a code *type* is possible only if a layer does not contain objects of a given code.
-  – allows to open the **Add code** window to input values of each classifier field of a new record;
-  – allows to add selected code to separate codes list, that is used to search for frequently used codes and is displayed, if the **Favourites** checkbox is set on in the left lower part of the classifier window;
-  – allows to delete selected catalogue from layers list with preliminary warning;

Context menu of layer list contains the following menu items:

- **Copy layer** – allows to copy a layer selected in the list to clipboard;
- **Paste layer** – allows to paste a layer from clipboard to the layers list;
- **Move layer** – allows to cut selected layer and it list or inside selected layer (as a sub-layer);
- **Show layer with sublayers** – allows to display in 2D-window objects, which codes belong to the selected layer (when the “eye”  to the left of the layer name is enabled);
- **Hide layer with sublayers** – allows to hide in 2D-window objects, which codes belong to the selected layer (when the “eye”  to the left of the layer name is disabled);

Context menu of code list contains the following menu items:

- **Copy code** – allows to copy a code selected in the list to clipboard;
- **Insert code** – allows to paste a code from clipboard to the codes list;
- **Move code** – allows to paste a code from clipboard to the codes list and to delete it from its previous location;
- **Add code to favourites** – allows to add a code selected in the list to the *Favourites*.

6.4. Classifier import

The system provides possibility of vector objects codes import during creation or updating of active classifier. To import is used the  button.

The system provides import of classifier from the following formats:

- import of a rsc-file to classifier layer. In files with the *.rsc extension the symbols libraries (classifier) are used to display and print digital maps. A set of standard classifiers (files with *.rsc extension) is included to the system delivery package and is stored in the \VectOr\DOC folder after system installation. During import of classifier from *Panorama* a set of standard classifiers is used for correct codes display;
- import of classifier assigned to existing map (files *.sit, *.map) to a code table of layer with classifier.

During import of vector objects to a layer with classifier from supported exchange formats, their codes are also imported to a new classifier or are added to the existing one, depending on settings, see [Section 13](#).

6.5. Labels creation

For vector objects the system provides creation of special label (*label*), that is displayed in 2D-window as a label near point object or near vertex of linear object, depending on settings (see the “[General system’s parameters](#)” User Manual).



Such a label is also displayed next to an object after export to DXF file of the *AutoCAD program* (see [Section 14.5](#)).



Labels creation is performed after creation of all objects and prior to their export to DXF.

In order to create labels for vector objects perform the following actions:

1. Select object code in classifier.
2. Click the  button of the **Classifier** window toolbar. The **Set label** window opens.

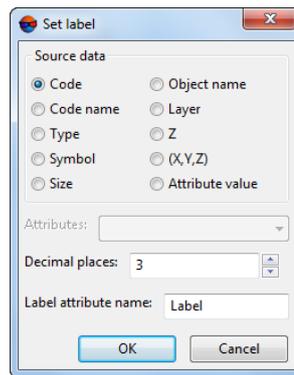


Fig. 52. Label creation

3. In the **Source data** section select one of the data sources to be used to move data to a label (see [Section 6](#)).
4. [optional] If the **Attribute value** was chosen, select code **attribute** in the list. These values show as label to an object in 2D-window or in the *AutoCAD program* (after export of selected code objects to DXF file).
5. [optional] Define **decimal places** to display in numerical labels. By default decimal number is three.
6. [optional] By default the **Label attribute name** is specified as the *Label*. To change the name input necessary name to appropriate field.
7. Click OK. Labels creates for all objects of selected layer. Labels display content of selected source. The labels are also displayed in the object's attributes list (see [Section 7](#)) with the *Label* name by default.

To set a label for all objects of selected layer, click the  button, after that the label is assigned to all objects in selected layer.

6.6. Association of vector objects with classifier.

Classifier's records are assigned to vector objects using two ways:

- during vector object creation select desired code in the classifier and start object vectorization, after that the code is assigned to the object automatically;
- assign code to existing object; to do that select vector object or object's group in 2D-window and desired code in classifier and click the  button (see [Section 8.2](#)).

6.7. Conversion of vector objects types

The system allows to convert polyline to polygon and vice versa while working with classifier.



When working in vector layer without classifier objects types conversion is performed automatically during closing/opening of a polyline (see [Section 11.4](#)).

In order to convert a polyline to polygon perform the following actions:

1. **Select** a polyline or a group of polylines.
2. Select in the classifier the C code type (polygon) and click the  button in the **Classifier** window. Polyline becomes closed and selected code is assigned to it.

In order to convert a polygon to polyline perform the following actions:

1. **Select** a polygon or a group of polygons.
2. Select in the classifier the L code type (polyline).
3. Click the  button of the **Classifier** window toolbar. The **Parameters of converting 'C' -> 'L'** window opens.

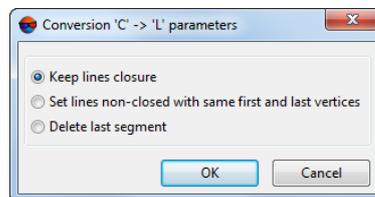


Fig. 53. Parameters of polygon to polyline conversion

4. Select one of the following ways of conversion:
 - **Keep lines closure** – a polygon is converted to closed polyline (non-areal object);
 - **Set lines non-closed with the same first and last vertices** – a polygon is converted to opened polyline, which the first and the last vertices coincide;
 - **Delete last segment** – a polygon is converted to a polyline, and the segment between the first and the last vertices is deleted.
5. Click OK. Polygon converts to a polyline and selected code assigns to it (see the [Section 6.6](#)).

7. Vector objects attributes

Table 7. Brief description of the “Attributes” menu”

Menu items	Function
Copy attributes from points to polygons	provides possibility to copy attributes of point objects and to assign them to polygonal objects
Merge point objects by attribute	allows to find all groups of points objects with equal values of defined attribute or replace any group of found points objects with one, placed in the center of all group
Select by attribute	provides possibility to search objects both by value and by attribute values list
Select by attribute value range	provides possibility to search objects by attribute values range
Select by attribute list	allows to search objects using attributes values list
Attribute value range...	allows to display minimal and maximal value of selected attribute
Color by attribute value...	provides possibility to display layer objects by different colors depending on the height, or by selected attribute of numerical type
Collate objects...	allows to perform search on a vector layer objects closest to the objects of another vector layer
Interpolate attribute value...	allows to interpolate attribute values
Set labels...	provides possibility to create labels to vector objects both from attribute values and code table fields, and in the form of coordinates
Assign unique attribute value...	allows to assign a unique values to attributes of vector objects
Assign height from attribute	allows to set a height of vector objects from attribute
Save the objects height in the attribute	allows to save the objects height in the attribute
Obligatory layer attributes	allows to assign required attributes to all layer's objects
 Autofilled layer attributes...	allows to fill layer's attributes automatically
 Automatic attributes filling	allows to automatically calculate area in specified measurement units
Label attributes	provides possibility to display labels of vector objects combined from multiple attributes with delimiters
Check layer semantic...	provides possibility to check layer's semantics – type, size and accuracy of selected attribute; existence of attribute value; uniqueness of attribute values set
 Calculate canopy of forest	provides possibility to calculate a value of <i>canopy</i> of trees cover (in range from 0 to 1) using measuring grid

7.1. Creation of vector objects attributes

7.1.1. Attributes creating and editing

The system provides possibility to create attributes both for vector objects codes and for vector objects created in a layer without classifier. Any additional parameter of the object, for example, object number, could be specified as attribute.

The **Vectors > Attributes** menu provides to work with attributes the system, as well as the **Attributes** tab in the **Classifier** window. Attributes table creates in the tab. It consists of attributes **Name**, **Type** and **Size** fields.

During work in a layer with classifier perform the following actions:

1. Select necessary code on the **Codes** tab of the **Classifier** window.
2. Select the **Attributes** tab and click the  button. The **Add attribute** window opens.

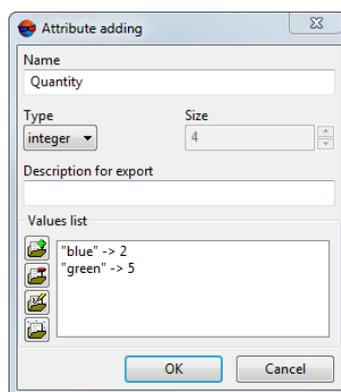


Fig. 54. The “Add attribute” window

3. Define the following parameters:
 - **Name** of attribute;
 - **Type** of attribute:
 - integer – attribute of integer type 4 bytes long;
 - float – attribute of real type 8 bytes long;
 - text – text attribute; text length is determined by its content, but not more than 8 bytes, otherwise – specifies fixed text length in bytes.
 - **Size** (in bytes) – for numeric types of attributes is defined automatically, otherwise, is specified by user (for text attributes, for instance);

- **Description for export** – text field for correct [import/export](#) of attributes to MIF/MID format.

The **Values list** section allows to create list of preset values of *integer* attributes. The toolbar of section contains the following buttons:

-  – allows to add the attributes value;
-  – allows to remove selected attribute value from the list.
-  – allows to edit name and value of attribute value;
-  – allows to clear the attribute values list;



If there is a list of attribute values, it is possible to select values only from this list, otherwise, it is possible to select arbitrary values.

4. Click OK. After that for selected code the attribute with specified parameters is created.

To edit attribute parameters is used the **Edit attribute** window. In order to open the window click the  button of the **Classifier** window.

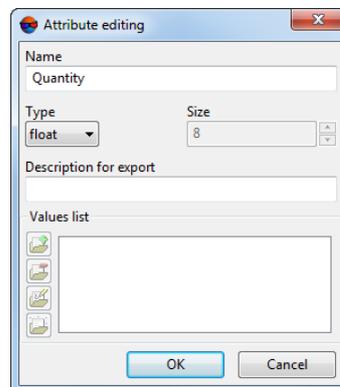


Fig. 55. Editing of object attribute

To delete active field of the attributes table click the  button on the **Attributes** tab of the **Classifier** window.

Toolbar on left part on **Attributes** tab allows to perform the following:

-  – move record to the top position;
-  – move record one position up;
-  – move record one position down;

-  – move record to the bottom position;
-  – rebuild the list of attributes in the reverse order.

In addition to creating the attributes attached to the classifier record, it is possible to create additional attributes, which are unique for the selected object. That means that all objects assigned to some classifier code, have common attributes specified in classifier, and it is possible to assign unique (“additional”) attributes to each of them.



In contrast to conventional attributes of objects, the system does not support the ability to export additional attributes to *.rsc files.

To input attribute values or to create additional attributes perform the following:

1. **Select** a vector object or vector objects group.



When multiple objects with attributes are selected, select only attributes with the same values in the table of **Objects attributes** window. Strings of attributes with different values highlights by red color.

2. Choose the **Window > Object attributes** or click the  button of the **Vectors** additional toolbar. The **Object attributes** window opens.

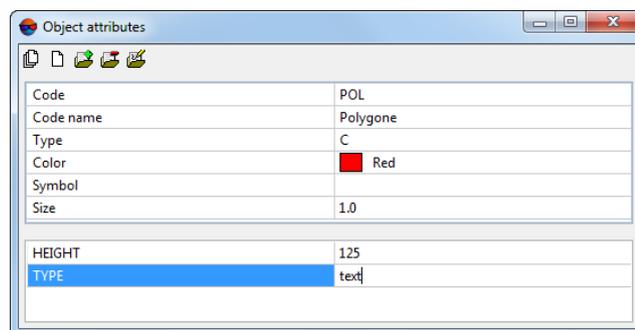


Fig. 56. Additional attributes (layer with Classifier)

The table fields have the same strings described in [Section 7.1.1](#).

The following buttons are used to create and edit additional attributes:

-  – allows to delete all additional attributes of selected objects;
-  – allows to delete additional attributes, common for selected objects;
-  – allows to add a new additional attribute and its parameters;
-  – allows to delete **additional** attribute selected in the table;
-  – allows to edit properties of selected **additional** attribute;

3. [optional] To create additional attribute click the  button and set attribute name and type.
4. Click on the table field in the **Value** column opposite to name of selected attribute. The field becomes editable then.
5. Input attribute value.
6. To complete editing and save changes press **Enter** or pass to the next cell.



To exit without saving changes press **Esc**.

The system provides possibility to copy attributes of point objects and to assign them to polygonal objects. To do this the **Vectors > Attributes > Copy attributes from points to polygons** menu item is used.

7.1.2. Creation attributes in layer without classifier

In addition to creating vector objects attributes attached to a specific code of the classifier, the system has the ability to create attributes of objects in the layer without classifier.

In order to add attributes, that are not attached to classifier code, perform the following actions:

1. Create or **load** vector **layer without classifier**.
2. **Select** a vector object.
3. Choose the **Window > Object attributes** or click the  button of the **Vectors** additional toolbar. The **Object attributes** window opens.

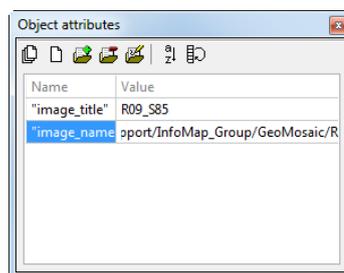


Fig. 57. Vector objects attributes (layer without Classifier)

The table fields have the same parameters described in [Section 7.1.1](#).

The following buttons are used to create and edit attributes:

-  – allows to delete all attributes of selected objects;
 -  – allows to delete common attributes of selected objects;
 -  – allows to add a new attribute and its parameters;
 -  – allows to delete selected attribute;
 -  – is used to edit selected attribute properties;
 -  – allows to sort attributes of selected objects;
 -  – allows to invert attributes of selected objects.
4. Click on the table field in the **Value** column opposite to name of selected attribute. The field becomes editable then.
 5. Input attribute value.
 6. To complete editing and save the input value press **Enter** or pass to the next attribute value cell.



To exit without saving changes press **Esc**.

7.1.3. Adding required attributes of a layer

The system allows to assign required attributes to all layer's objects. These attributes add to all objects, regardless of their classifier type and code.

In order to add required attributes to a layer objects, perform the following actions:

1. Make editable a layer for which to add required attributes.
2. Select **Vectors** › **Attributes** › **Obligatory layer attributes**. The **Required attributes** window opens.

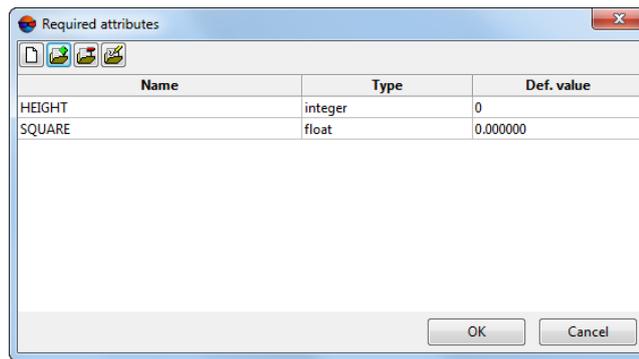


Fig. 58. The “Required attributes” window

The following buttons are used to create and edit additional attributes:

-  – allows to clear the obligatory attribute values list;
-  – allows to add a new attribute and its parameters;
-  – allows to delete attribute selected in the table;
-  – is used to edit selected attribute properties;

3. To add attribute click the  button. The **Edit attribute** window opens.

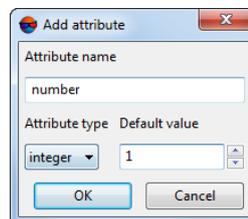


Fig. 59. Attribute parameters

4. Define the following parameters:

- **Attribute name;**
- **Attribute type:**
 - *integer* – attribute of integer type;
 - *float* – attribute of real type;
 - *text* – text attribute; text length is determined by its content, but not more than 8 bytes.

- **Default value** – a value assigned automatically to all objects of selected layer as an attribute.
5. Click OK. Attributes from the list of the **Required attributes** window are assigned to all objects of selected layer.

7.2. Vector objects labels

7.2.1. Labels creation

The system provides possibility to create labels to vector objects both from attribute values and code table fields, and in the form of coordinates.

To create labels to vector objects perform the following actions:

1. Select **Vectors** > **Attributes** > **Set labels**. The **Set label** window opens.

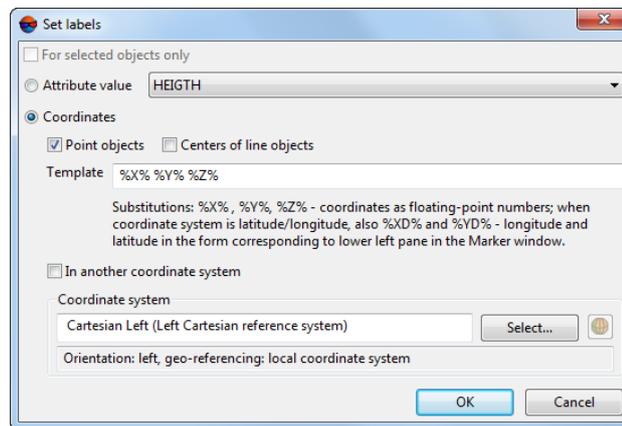


Fig. 60. Labels parameters

2. [optional] To set labels to selected objects, set the **For selected objects only** checkbox on.
3. Select one of options of labels creation:
 - **Attribute value** – labels create from values of selected attribute;
 - **Coordinates** – object coordinates display as labels (depending on object type);
 - **Point object** – display coordinates of points and polygon/polyline vertices;
 - **Centers of line object** – display coordinate of line objects centers;

Coordinates should be created using the **template** %X% %Y% %Z%.

 Set on both objects to display labels for all object types.

 The system allows to create labels in the coordinate system different from project coordinate system. To do this set the **In another coordinate system** checkbox on and [select coordinate system](#) to be displayed.

4. Click OK. After that labels to selected objects are displayed in 2D-window.

 There are hotkeys to hide labels: in active layer – **Ctrl+H**, in all layers – **Ctrl+Shift+H**. Also the **Edit › Active layer › Show/Hide labels in active layer** menu item allows to hide labels.

7.2.2. Labels attributes

The system provides possibility to display labels of vector objects combined from multiple attributes with delimiters.

In order to show combined labels perform the following actions:

1. Select **Vectors › Attributes › Label attributes**. The **Layer label attributes** window opens.

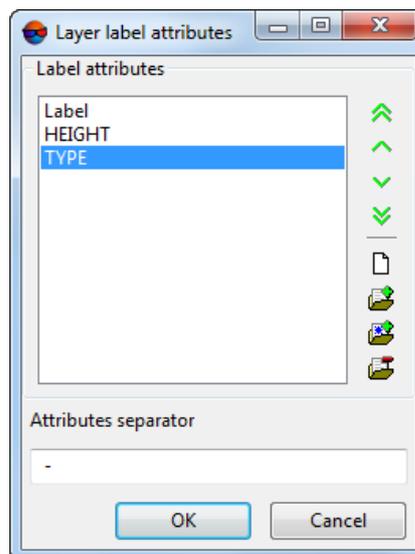


Fig. 61. Layer labels

The window **Layer label attributes** contains the toolbar for the following operations:

-  – moving attribute to the top position;
-  – moving attribute one position up;
-  – moving attribute one position down;

-  – moving attribute to the bottom position;
 -  – allows to clear the attributes list;
 -  – allows to add new attribute;
 -  – allows to add attribute from list of existing layer attributes;
 -  – allows to remove selected attribute.
2. In the **Label attributes** section the list of available attributes with labels is displayed.
 3. In the **Attributes separator** section specify a symbol to be used as a separator of attributes.



The system supports special symbols of *XML* markup language that are used as separators.



Line spacing is set on the **Labels** tab of the **Settings** window (see the “General settings” User Manual).

4. Click OK. As a result, for vector objects vertices having attributes the labels in the form of attribute values with specified delimiter are displayed in 2D-window.



During [automatic polygon attributes assigning](#) or at manual attributes change labels attributes are updated automatically.

7.3. Attributes assigning

7.3.1. Assigning of unique attribute value

Unique values could be assigned to attributes of vector objects. This simplifies combining objects into groups by attribute values and automate the assignment of attribute values to vector objects. This function is used for further work in *3D-Mod program*.

To assign unique attribute value to objects, perform the following actions:

1. [Select](#) a vector object or multiple objects in 2D-window.
2. Select **Vectors** › **Attributes** › **Assign unique attribute value**. The **Assign unique attribute value** window opens.

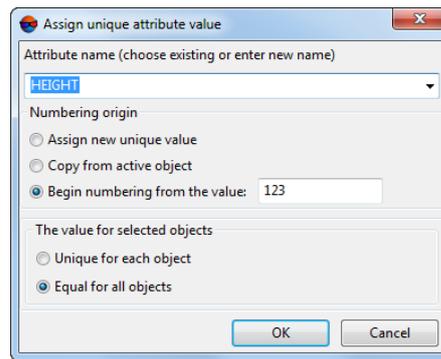


Fig. 62. Parameters of unique attribute values

3. Select attribute in the **Attribute name** field to input unique value or specify a new attribute name.



When you define a new attribute name the system creates an additional attribute of integer type for the selected objects.

4. Select one of the following ways of unique value assigning:
 - **Assign new unique value** – allows to specify new unique value of active object attribute;
 - **Copy from active attribute** – allows to copy a value of selected object attribute;
 - **Begin numbering from the value** – allows to start numbering from arbitrary number specified in this field.
5. Select a way to specify **the value of selected objects**:
 - **unique for each object**;
 - **equal for all objects**.
6. Click OK. Unique attribute value is assigned to selected vector objects.

7.3.2. Save the objects height in the attribute

The system allows to save the objects height in the attribute. Height calculates as difference between the value of the DEM cell and height of the object vertices.



This function may be used to save roof heights over the ground level as attributes.

In order to save the objects height in the attribute perform the following actions:

1. Load a vector layer and a DEM in the project.



For correct work of the function make sure, that only one layer with vector object and only one DEM is opened in the current project.

2. Select **Vectors** > **Attributes** > **Save objects height above DEM to attribute**. The **Layers selection** window opens.

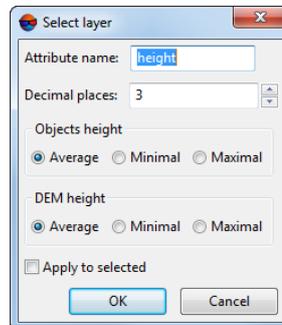


Fig. 63. Parameters of saving the objects height in the attribute

3. Define the following parameters in the window:
 - **Attribute name** – "height" by default;
 - **Decimal places** – allows to specify the number of decimal places (from 0 to 24).
 - **Objects height** – allows to use **average**, **minimal** or **maximal** height of vector object vertices to define difference with DEM;
 - **DEM height** – allows to use **average**, **minimal** or **maximal** value of DEM cells around vector object to define difference with the object.
4. [optional] To assign objects height only to attribute of selected objects, set the **Apply to selected** checkbox on.
5. Click OK. As a result, height difference is assigned to all or selected objects of vector layer as attribute.

7.3.3. Assigning height from attribute

The system allows to set a height of vector objects from attribute.



Given function works correctly if an attribute regardless of its type constitutes a number. Otherwise specified value of vector object height will be equal zero.

To assign a height of vector objects from attribute perform the following actions:

1. [optional] Select vector objects, height of which is necessary to set;

2. Select **Vectors > Attributes > Assign height from attribute**. **Assign height from attribute** window is opened.

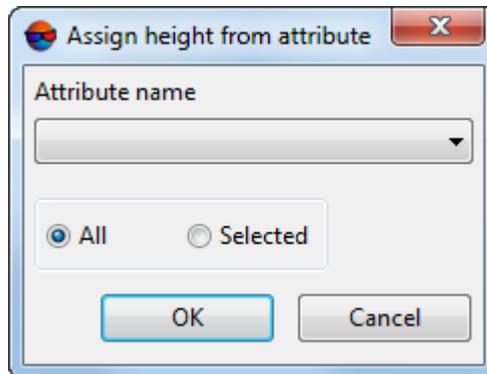


Fig. 64. Settings of assigning object heights to attributes

3. Select from the list an attribute value of which will be set as a height;
4. [optional] Set parameter **Selected** to assign height from attribute to selected objects only;
5. Click OK. As a result the value of attribute selected is assigned as a height to the all or to selected objects of vector layer which have a given attribute.

7.3.4. Automatic filling layer's attributes

The system allows to fill layer's attributes automatically.

Perform the following actions for creating autofilled attributes:

1. Make editable a layer for which to add autofilled attributes.
2. Create **attribute** with *float* type.
3. [optional] To display a value of autofilled attribute in 2D-window specify **labels attributes** for created attribute.



Labels attributes refresh automatically.

4. Choose **Vectors > Attributes > Autofilled layer attributes** or click the  button of the **Vectors** additional toolbar. The **Autofilled attributes** window opens.

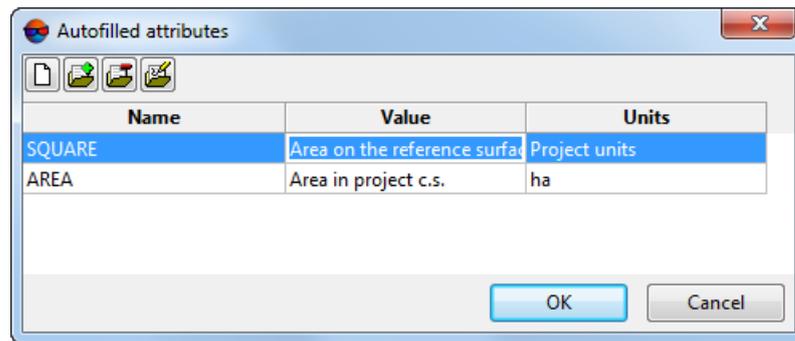


Fig. 65. The “Autofilled attributes” window

The window **Autofilled attributes** contains the toolbar with buttons used to perform the following operations:

-  – is used to clear the attributes list;
-  – is used to add new obligatory attribute;
-  – is used to remove selected attribute.
-  – is used to edit parameters of selected attribute.

5. To add click the  button. The **Edit attribute** window opens.

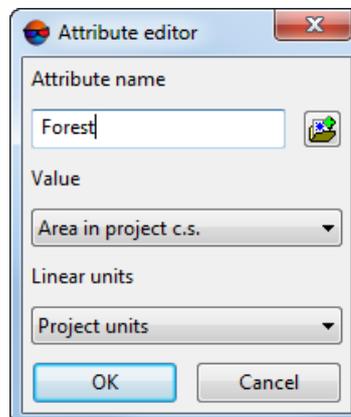


Fig. 66. Attribute editing

6. Click the  button to select attribute from attributes list.

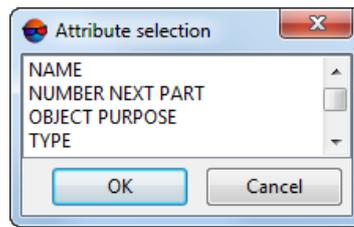


Fig. 67. Selection from list of mandatory attributes



A name of autofilled attribute should be the same as a name of attribute.

- In the **Value** list select a value to be used for autofilling: **Area in project CS** or **Area on the reference surface**.



A value of the area *on the reference surface* is calculated only when using coordinate system matched with WGS-84.

- Select one of the following area measurement units: **project units**, **sq.m**, **ha**, **sq.km**.
- Click OK.
- Choose **Vectors** > **Attributes** > **Automatic attributes filling** or click the  button to automatically calculate area in specified measurement units. The value is displayed in the **Object attributes** window and/or as attributes labels (see [Section 7.2.2](#)).

The polygon square, created or edited *after* setting autofilling attributes, also could be displayed. To do this choose **Vectors** > **Attributes** > **Automatic attributes filling** or click the  button. Attribute value refresh for all polygons in active layer.



If not mandatory attributes are used as autofilling, they are not assigned to a new objects. To display square of a “new” polygons, it is required to create *float* attribute with name, equal to name of autofilling attribute and click the  button.

7.3.5. Objects collation

Objects collation operation is used to search on a vector layer objects closest to the objects of another vector layer.



This operation is a specialized and used to automate search of differences between two versions of the file with exterior orientation parameters, if there is a possibility that one of them contains wrongly compared names and images and projection center coordinates.

Perform the following actions to do collation:

- Select **Vectors** > **Attributes** > **Collate objects**. The **Collate objects** window opens.

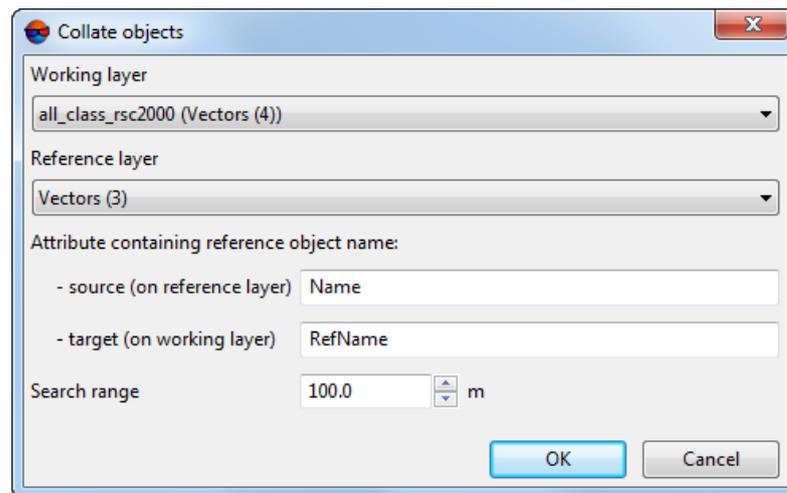


Fig. 68. Parameters of objects collation

2. Select **Working layer**, where it is necessary to perform objects collation.
3. Select **Reference layer**, where to search objects closest to working layer objects.
4. [optional] To perform search for objects with specified attribute name, input the **Attribute containing reference object name** to the **source (on reference layer)** field.
5. [optional] To record the values of found objects attributes of the reference layer to attributes of the working layer objects, input the **Attribute containing reference object name** to the **target (on working layer)** field.
6. Specify the **Search range** value in meters, within which the search is performed.
7. Click OK. After that each object of the working layer contains attribute with the name of closest object of the reference layer.



The working layer is available for export to format which supports tabular format of attributes recording (for example, to DBF) to create match list of one layer objects to another for further analysis.

7.4. Operations with objects using attributes

7.4.1. Merging point objects by attribute

Operation of merging point objects by attribute allows:

- to find all groups of points objects with equal values of defined attribute;
- replace any group of found points objects with one, placed in the center of all group.



This operation is used, for example, to perform generalization of map, where some physical objects are displayed by point objects groups, and in the attributes of each group objects is registered a name of a real object, to which these point objects relate to.



If it is necessary to merge closed polygons groups using the same principle, use the **Convert polygons to points** function in advance.

For transformation perform the following actions:

1. Choose **Vectors › Attributes › Merge point objects by attribute**.

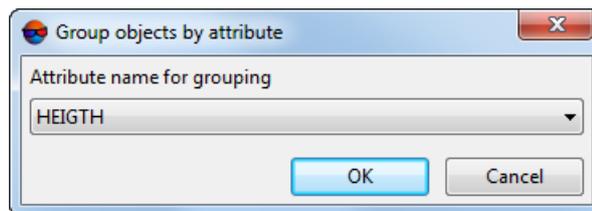


Fig. 69. Attribute name selection

2. Selection attribute name from the list, which values are used for the merging.
3. Click OK. The system performs search of all point objects with specified attribute. Objects found are grouped by attribute value, then in each group all objects are removed, except for the one randomly selected. The remaining object is moved to mass center of the original group.



If in the active vector layer there is no point object that has an attribute with the specified name, the system displays an error message.

7.4.2. Object search using attribute value

The system provides possibility to search objects both by value and by attribute values list.

To search objects using attributes values perform the following actions:

1. Select **Vectors › Attributes › Select by attribute**. The **Search by attribute** window opens.

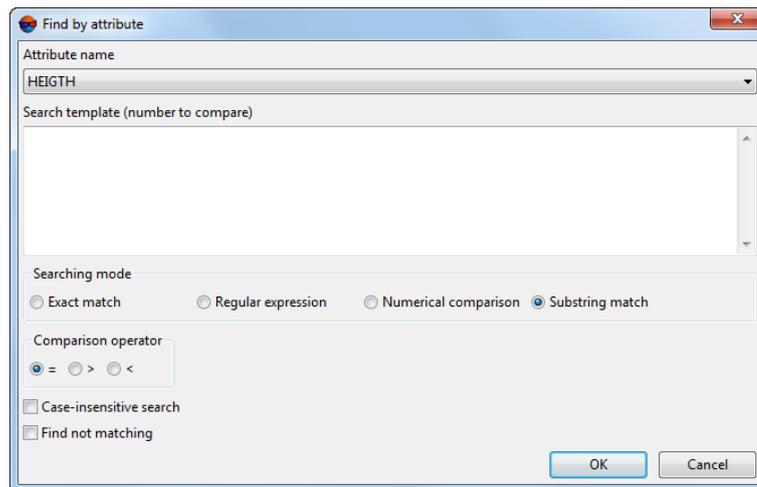


Fig. 70. Search by attribute

2. In the **Attribute name** field select attribute that values will be used to perform the search.
3. In the **Search template** field input text line or number, that will be used to perform the search. The value of this field is interpreted by the system depending on the search mode.
4. Select one the search modes:
 - **Substring match** – the system searches for objects whose attribute value contains the string template;
 - **Exact match** – the system searches for objects whose attribute value is exactly the same as search template;
 - **Regular expression** – the system searches for objects whose attribute value matches the regular expression specified in the **Search template** field;
 - **Numerical comparison** – the system searches for objects, for which the numerical value of the search string is compared with the attribute value using one of the comparison operators=, >, <.
5. [optional] To search for objects using case insensitive search set the **Case insensitive search** checkbox on.
6. [optional] To search for objects that do not have the specified attribute or which value does not satisfy the search condition, set the **Find not matching** checkbox on.
7. Click OK. Found objects are highlighted in 2D-window.



Found objects highlight considering active [group selection mode](#).

To search objects using attributes values perform the following actions:

1. Select **Vectors** › **Attributes** › **Select by attribute list**. The **Search by attribute values list** window opens.

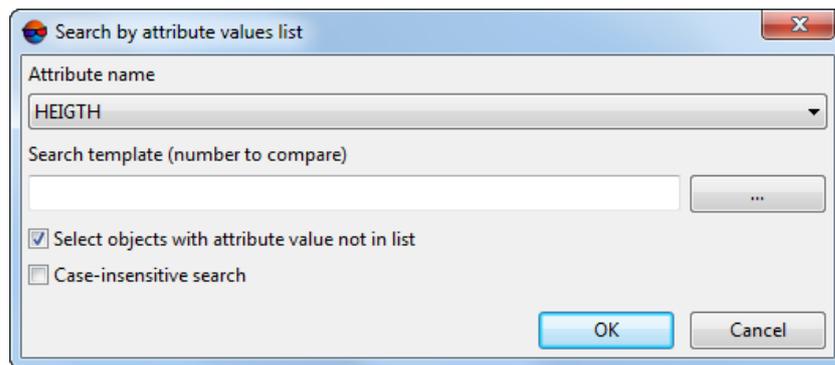


Fig. 71. Search by attributes list

2. In the **Attribute name** field select attribute that values will be used to perform the search.
3. In the **File with values list** field click the **...** button and select a file containing a list of values for search.
4. [optional] Set the **Select objects with attribute value not in list** checkbox on, to found those objects that have no attribute values in the selected list.
5. [optional] To perform search using case insensitive search set the **Case insensitive search** checkbox on.
6. Click OK. Found objects are highlighted in 2D-window.



Found objects highlight considering active [group selection mode](#).

7.4.3. Select by attribute value range

The system provides possibility to search objects by attribute values range.

Perform the following actions to do this:

1. Select **Vectors** › **Attributes** › **Select by attribute value range**. The **Search by attribute values range** window opens.

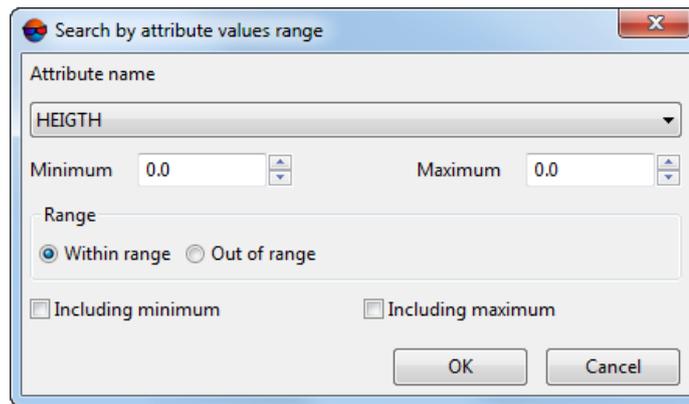


Fig. 72. Search by attribute

2. In the **Attribute name** field select attribute that values will be used to perform the search.
3. In the **Minimum** and **Maximum** fields specify value range for search.
4. Choose the task for processing in the **Range** section:
 - **Within range** – to find attributes with values within specified range;
 - **Out of range** – to find attributes with values out of specified range.
5. [optional] Set the **Including minimum/maximum** checkboxes on to consider min/max values during search.
6. Click OK. Information message about loaded vectors is displayed. Found objects are highlighted in 2D-window.



Found objects highlight considering active [group selection mode](#).

7.4.4. Custom object paint

The system provides possibility to display layer objects by different colors depending on the height, or by selected attribute of numerical type.

In order to change objects coloring on active layer, perform the following actions:

1. Select **Vectors** › **Attributes** › **Color by attribute value**. The **Custom objects paint** window opens.

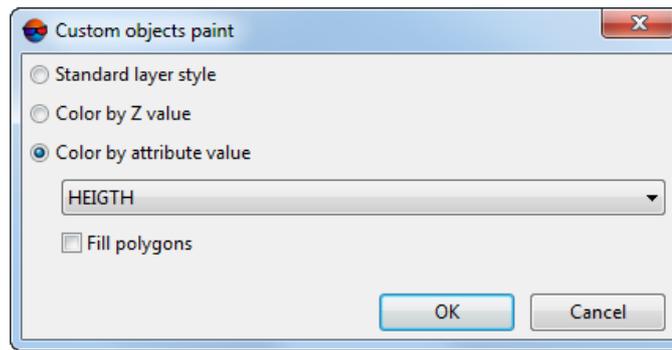


Fig. 73. Parameters of objects paint using attributes

2. Select one of the ways to change the color of layer's objects:
 - **Standard layer style** – vector objects color set in the layer properties;
 - **Color by Z value** – color of vector objects changes by altitude scale depending on object Z-coordinate value;
 - **Color by attribute value** – color of vector objects changes by values of selected attribute.



It is possible to use text attribute if all its values could be converted into number;

3. [optional] To fill the layer's polygons in accordance with values of selected attribute, set the **Fill polygons** checkbox on.
4. Click OK. As a result, the coloring of objects is changed depending on selected options.



Objects that have no selected attribute are displayed in gray.

7.5. Attribute value range

The system allows to display minimal and maximal value of selected attribute.

Perform the following actions to do this:

1. Make vector layer active.
2. Select **Vectors** › **Attributes** › **Attribute value range**.

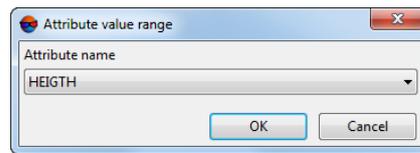


Fig. 74. Attributes value range

3. Choose attribute name to find its maximum and minimum value.
4. Click OK. Information window with the following information about the attribute displays. If the selected attribute has text type or has no values, the system displays an appropriate error message.

7.6. Attributes value interpolation

The system provides possibility to interpolate attribute values. It is used to define images exterior orientation parameters, acquired by unmanned aerial vehicles and having only the data about the time of image acquisition.

To interpolate attributes values, perform the following actions:

1. **Load** a vector layer with classifier.



For vector objects, it is necessary to have at least one code with at least two different attributes.

2. Select **Vectors > Attributes > Interpolate attribute value**.
3. In the **Attribute with function argument** field select attribute name of numeric type that will be used for interpolation as a function argument.
4. In the **Attribute with function value** field select attribute name of numeric type that will be used for interpolation as a function value.
5. Click OK. As a result, an interpolated value of attribute, specified as a function value is assigned to objects that contain only argument attribute.

7.7. Layer's semantics check

The system provides possibility to check layer's semantics. The following parameters is checking:

- type, size and accuracy of selected attribute;
- existence of attribute value;

- uniqueness of attribute values set.

The **Check semantics** window is used to configure parameters of the operation, and it contains the following buttons:

-  – allows to clear the attributes list;
-  – allows to add a new attribute and specify semantics check parameters for it;
-  – is used to add attribute existing in the list of layer attributes;
-  – allows to remove selected attribute from the list;
-  – allows to edit selected attribute properties;
-  – allows to load the attribute template file;
-  – allows to save the attribute list to file for further using as a template.

To perform semantic check, perform the following actions:

1. Select **Vectors** > **Attributes** > **Check layer semantic**. The **Check semantics** window opens.

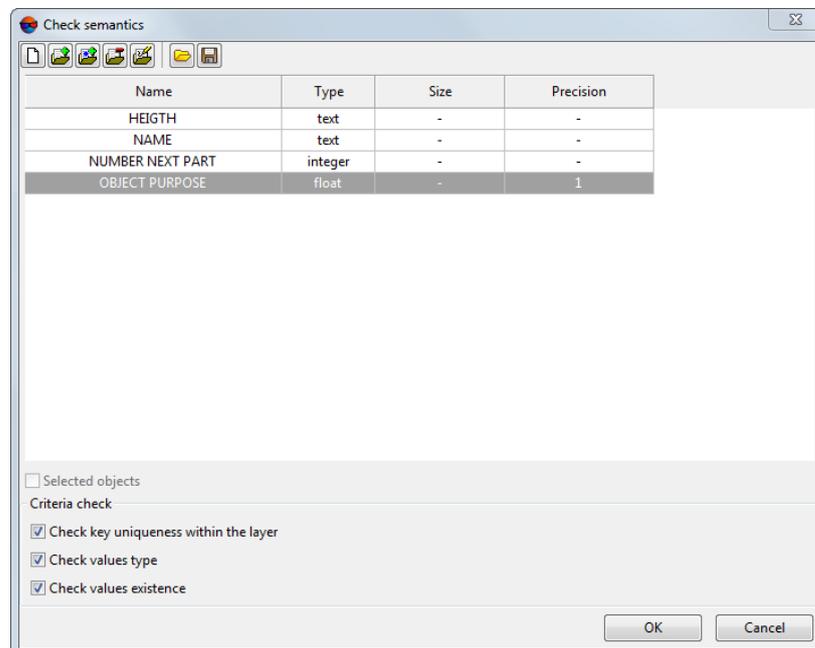


Fig. 75. The “Check semantics” window opens.

2. Prepare attribute list with one of the following way:

- to select existing attribute from the list, click the  button. The **Attributes selection** window opens. Select single or multiple attributes by mouse click and click OK.

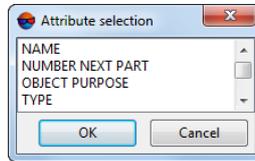


Fig. 76. The window used to select attributes from existing ones

- to add a new attribute click the  button. The **Edit attribute** window opens.

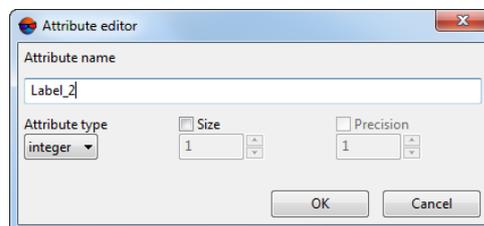


Fig. 77. The “Edit attribute” window

3. [optional] Define attribute parameters. When create a new attribute, the **Edit attribute** window opens automatically. To open window for attribute from the list, double-click on attribute name or click the  button.

Define the following parameters:

- **Attribute name** – arbitrary name;
 - **Type** – attribute type; the system supports the following types:
 - *integer* – attribute of integer type 4 bytes long;
 - *float* – attribute of real type 8 bytes long;
 - *text* – text attribute.
 - **Size** (in bytes) – [for number types of attributes] to check the attributes size;
 - **Precision** – [for number types of attributes] decimal places.
4. [optional] To check semantics of selected objects only, set the **Selected objects** checkbox on, otherwise, the check operation will be performed for all objects.

5. The **Criteria check** section is used to select single or multiple criteria to check layer semantics:



If the specified attribute is absent for object, the system displays error message.

- **Check key uniqueness within the layer** – the system creates a key (a set of consecutive parameters) for values of selected attributes and checks uniqueness of the key value for each object of the layer.
- **Check values type** – for specified attributes of each object of the layer the system checks for the compliance of the attribute value to type, size and accuracy;
- **Check values existence** – for specified attributes of each object of the layer the system checks for the attribute values other than the default.



As default values for attributes of “text” type is provided an empty string, for attributes of “float” and “integer” type – “0” value. If the attribute is **mandatory**, the system also performs check its default value.

6. Click OK. The system starts operation of layer semantics check. If there are some discrepancies the system shows warning and the **Errors in attributes** window opens. It contains the list of errors found:

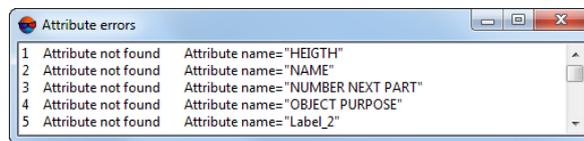


Fig. 78. The “Errors in attributes” window



During check of the key uniqueness the error message informs about number of objects with non-unique attributes.

7. Select a line with error in the list by mouse click. The appropriate object (or objects) select in the layer, marker is moved on a stereopair with the object and is placed to the object center. Error correction is performed manually in the **Objects attributes** window.

7.8. Calculation canopy of forest

The system provides possibility to calculate a value of *canopy* of trees cover (in range from 0 to 1) using measuring grid.

To perform canopy calculation perform the following actions:

1. Open a stereopair with the investigated woodland.

2. Select **Grid > Create**.
3. Select **Grid > Properties** and specify the grid step considering image resolution.

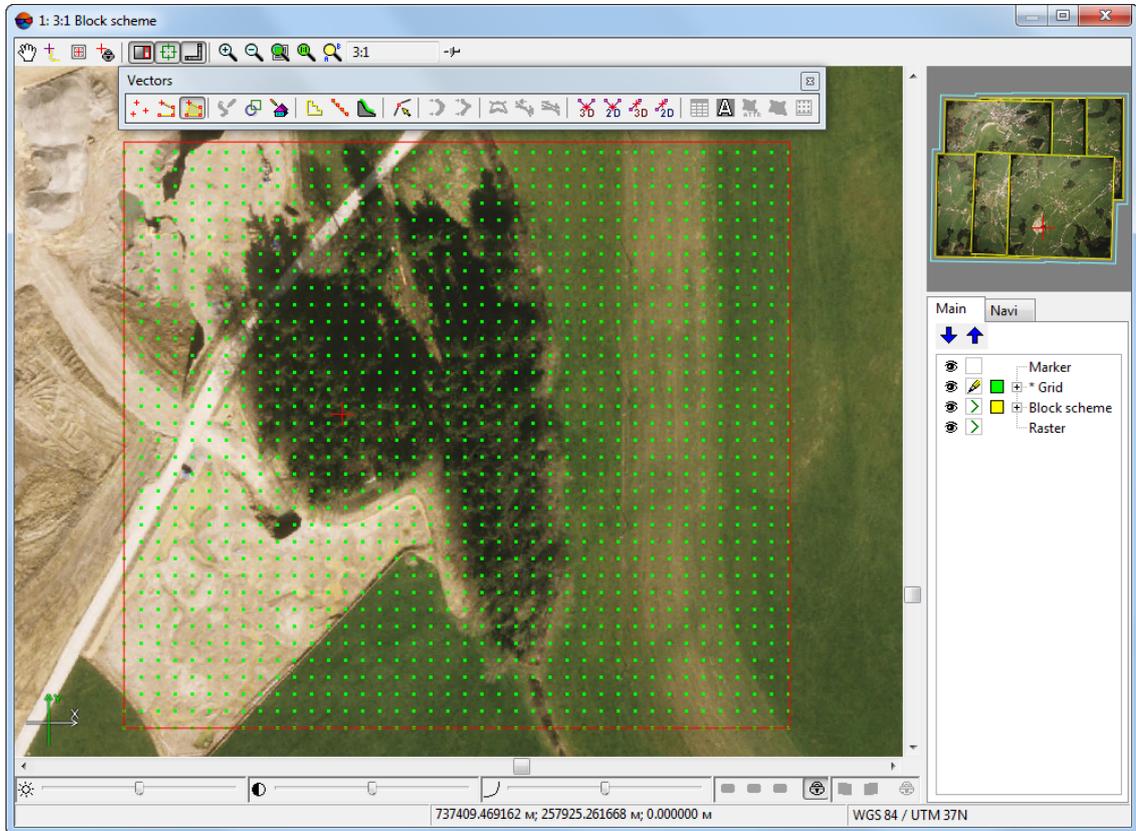


Fig. 79. Measuring grid creation

4. Press and hold the **Shift** key to draw rectangular grid for woodland area.



The grid should extend beyond the woodland area.

5. Choose **Vectors > Create layer** to create a layer without classifier.
6. Create a polygon in such a way that its boundary coincides with woodland boundaries.
7. Select **Grid > Create boundaries from vectors**. After that grid boundary coincides with created polygon.

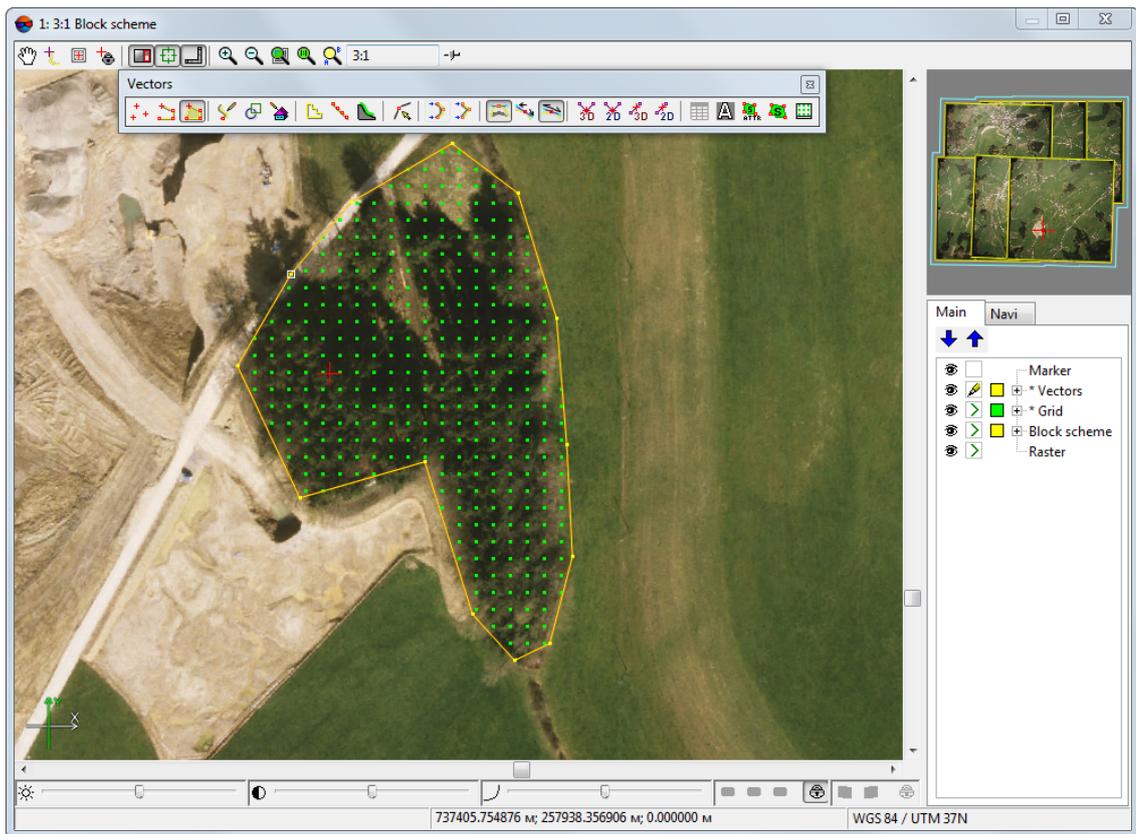


Fig. 80. Measuring grid creation

8. Make active the *Grid* layer in the *Manager*.
9. Choose **Vectors** › **Pathway** › **Activate** or click the  button of the **Pathway mode** additional toolbar (detailed description of Pathway mode see in the “DTM Generation” User Manual). After that marker is placed to the first grid node.
10. If grid node is on the top of tree, press **Enter** to create point in this node. Press **Delete** to skip a grid node. Passing to the next grid node is performed automatically.



To pass to the previous grid node, press the **Backspace** key.

11. After passing of all grid nodes the system displays the “*Pathway complete*” message.



The system also provides possibility to create points on the grid manually in frames of polygon without pathway mode. At that it is necessary to comply with the positioning accuracy of points in XY plane for the grid nodes within 1/3 of the distance between grid nodes.

12. Make active the *Vector* layer in the *Manager*.

13. Choose **Vectors** > **Attributes** > **Calculate canopy of forest** or click the  button of the **Vectors** additional toolbar.

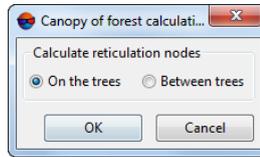


Fig. 81. Parameters of forest cover canopy

14. To calculate canopy value select **Calculate of reticulation nodes – On trees**. To calculate a value inverse to canopy select **Calculate of reticulation nodes – Between trees**.



It is better to create points *between* trees in case of high trees density. In this case choose **Between trees** to calculate cover canopy.

15. Click OK. After that the system displays a message with information about value of forest cover canopy.

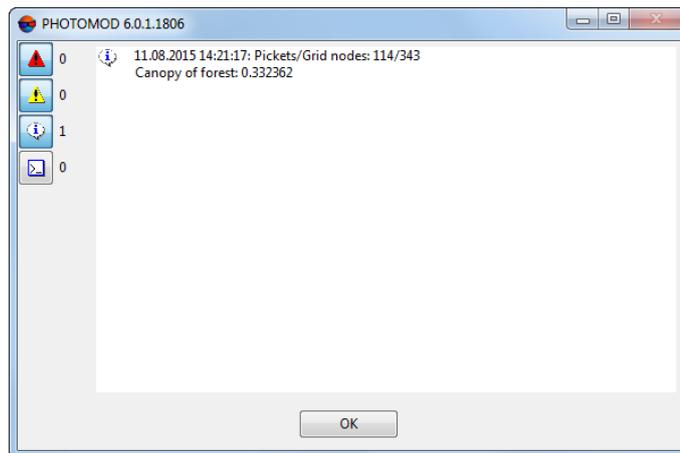


Fig. 82. Forest cover canopy value

8. Operations with vector objects

8.1. The “Edit” menu

The system provides possibility to edit objects in a layer, to change marker position or vectorization and selection modes and other operations of vector layer editing. The **Edit** menu allows to do this.

Table 8. Brief description of the “Edit” menu

Menu items	Function
Group selection	contains menu items to choose mode of vector object selection
Snapping	contains menu items for processing in the snapping mode (see the Section 3.4.6)
Vectors create mode	contains menu items to change mode of vector object creation: points, polyline, polygons, and creating mode of polylines and polygons as smooth lines (see Section 5.3)
Curve transforms	menu items to create and edit smooth curve lines (see Section 8.6)
 Undo (Ctrl+Z)	allows to cancel the last operation of vector objects editing on a layer (see Section 8.7)
 Undo log	allows to open the Undo log containing a list of recent editing operations
 Redo (Ctrl+Shift+Z)	allows to redo the last undone operation (see Section 8.7)
 Points editing mode	allows to move common vertices of objects together (see Section 8.4.1)
 Streamline mode (Y)	allows to enable streamline mode of linear objects input (see Section 3.4.4)
 Snap-to-ground mode (T)	allows to enable snap-to-ground mode
 Orthogonal mode (A)	allows to enable orthogonal mode of linear objects input
 Orthogonal mode in coordinate system	allows to enable orthogonal mode of linear objects input in additional coordinate system
 Add coord system	allows to create additional (user) coordinate system as a helping vectorization tool
Edit coord system	allows to change default axes direction of additional coordinate system
 Delete coord system	allows to delete additional coordinate system
Alignment mode	turns the alignment mode on
Scale when align	allows to scale vector objects during their transformation in the alignment mode
Select vertices when marker moves over them	allows to select a vertex, located in marker area on a distance specified in the Swath field (Service › Settings › Vectors)
Move marker to selected vertex	allows to move marker to the selected vertex automatically (see the “Settings of vector objects display” chapter of the “ General system’s parameters ” User Manual)
Sync markers	allows to turn on/off synchronous marker moving in all opened 2D-windows
 Copy marker to clipboard (Ctrl+Alt+INS)	allows to copy position of marker in 2D-window to clipboard

Menu items	Function
 Paste marker from clipboard (Ctrl+Alt+INS)	allows to move marker to position in 2D-window copied to clipboard
Cancel selection	allows to unselect all objects in active 2D-window (see Section 8.2)
Invert selection	allows to invert objects selection in active 2D-window (see Section 8.2)
Select all (Ctrl+A)	allows to select all objects in active 2D-window (see Section 8.2)
Highlight selected objects	allows to highlight vector objects selected in 2D-window (see Section 8.2)
Fit to window current layer	allows to display the data of the current layer completely. This function is supported by all types of layers (see section "Image scaling in 2D-window" in " General information " User Manual)
Active layer	contains menu items to work with current active layer (see the " General information " User Manual)
Show/hide labels in all layers (Ctrl+Shift+H)	allows to configure curves smoothing (see Section 8.6.6)

8.2. Vector objects selection

8.2.1. Objects selection tools

Objects on active vector layer could be selected both manual and automatically.

To select object manually are used the following tools:

- mouse double click or the **S** key to select single polyline/polygon;
- one mouse click to select point near to marker;
- **rectangle** – select objects inside of rectangle;
- **polygon** – select objects inside of free form polygon.

To highlight objects on active vector layer **inside a rectangle** choose **Edit › Group selection › Rectangle** or click the  button of the **Tools** toolbar. Press and hold the **Shift** key and drag a rectangle by mouse.

To select objects **inside of free form polygon** perform the following:

1. Choose **Edit › Group selection › Polygon** or click the  button of the **Tools** toolbar.

2. Press and hold the **Shift** key. Then make mouse click to create the first polygon vertex and a “rubber line” directed to current cursor position. Input subsequent vertices by mouse clicks.
3. To complete objects selection by polygon use mouse double click. To break off selection, press the **Esc** key.

To select all objects of active vector layer choose **Edit › Select all** or use the **Ctrl+A** hotkeys.

The **Edit › Highlight selected objects** menu item allows to highlight selected objects in 2D-window using additional lighting.



If selected objects have attributes in the table of **Objects attributes** window displays only attributes with the same values. Strings of attributes with different values highlights by red color.

8.2.2. Objects selection modes

To change selecting mode for vector objects the system provides the **Edit › Group selection** menu items:

-  **Rectangle** – to select objects inside a rectangle;
-  **Polygon** – to select objects inside arbitrary polygon;
-  **Normal** – during vector objects selection previously selected objects will be unselected;
-  **Add to selection** – each newly selected object (objects group) is added to a group of selected objects;
-  **Subtract from selection** – allows to unselect selected object (objects group);
-  **Invert selection** – allows to invert selected objects (objects group);
-  **Fully inside** – allows to select objects that hit the selection area;
-  **Partly inside** – allows to select objects in which one or more segments intersects a border of selection area;
-  **At least one point inside** – allows to select objects in which at least one vertices are in the selection area;



The **Tools** panel partially duplicates menu items **Edit › Group selection**.

The **Vectors › Selection** menu contains the following items used to sequentially select vector objects and their vertices:

- **Select previous object (Ctrl+<)** – allows to select an object, previous to selected;
- **Select next object (Ctrl+>)** – allows to select an object, next to selected;
- **Select previous line vertex (<)** – allows to select a polyline vertex located before the selected one; sequence of vertices is displayed when you select a vector object (see [Section 5.3.7](#));
- **Select next line vertex (>)** – allows to select a polyline vertex located after the selected one; sequence of vertices is displayed when you select a vector object (see [Section 5.3.7](#));

To unselect objects press **Esc**.

Table 9. Brief description of the 'Tools' toolbar

Button	Function
	allows to select vector objects inside a rectangle
	allows to select vector objects inside arbitrary polygon
	during vector objects selection previously selected objects will be unselected
	each newly selected object (objects group) is added to a group of selected objects
	allows to unselect selected object (objects group)
	allows to invert selected objects (objects group)
	allows to select objects that hit the selection area
	allows to select objects in which one or more segments intersects a border of selection area
	allows to select objects in which at least one vertices are in the selection area
	turns the alignment mode on
	allows to scale vector objects during their transformation in the alignment mode
	allows to copy position of marker in 2D-window to clipboard
	allows to move marker to position in 2D-window copied to clipboard
	allows to paste vector objects from clipboard to active vector layer into marker position



Vector objects are pasted to the point of marker position at the time of copying objects to the clipboard. If the marker is not moved between the copy and paste operations, objects are located in the same coordinates as the original; otherwise they shift on a vector that connects marker positions during copy and paste operations.

8.2.3. Selecting classifier layer object

During work in a layer with classifier the system provides the following options for automatic objects selection:

- selection of all layer objects – select a layer in the list of the **Classifier** window and click the  button; all objects of selected layer are highlighted in 2D-window (see [Section 6](#)).

- selection of objects with specified code – select necessary code in the codes list of the **Classifier** window and click the  button; all objects with specified code are highlighted in 2D-window (see [Section 6](#)).

8.3. Vector objects copying

The system provides possibility to copy all, highlighted or selected by type objects of vector layer to defined or new vector layer.

To copy objects of vector layer perform the following actions:

1. Make vector layer active.
2. [optional] To copy objects to existing layer, open this vector layer. Vector layer with objects to be copied should be active.
3. Select **Vectors** > **Copy to layer**. The **Copy objects to another layer** window opens.

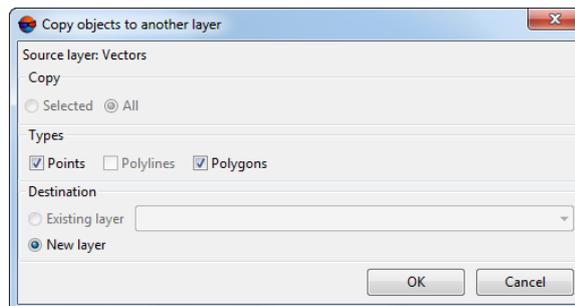


Fig. 83. Parameters of objects copying to layer

4. To copy just selected objects, in the **Copy** section choose **Selected**, otherwise, choose **All** (default setting).
5. In the **Types** section choose one or more object types to copy:
 - **Points**;
 - **Polylines**;
 - **Polygons**.
6. In the **Destination** section choose a layer to copy object:
 - **Existing layer** – choose one from the list of opened layers;
 - **New layer**.
7. Click OK to copy objects.



The system also allows to create several copies of vector object placed at the *same layer* (see [Section 11.4.6](#))

The system also allows using of clipboard for vector layer editing.

The **Vectors › Clipboard › Copy (Ctrl+C)** menu item allows to copy **selected** vector objects to the clipboard.

The **Vectors › Clipboard › Paste (Ctrl+V)** menu item allows to paste vector objects from clipboard to active vector layer.

The **Vectors › Clipboard › Cut (Ctrl+X)** menu item allows to cut vector objects from active layer and copy them to clipboard.

The **Vectors › Clipboard › Paste into marker position (Ctrl+Shift+V)** menu item allows to paste vector objects from clipboard to active vector layer into marker position.



Vector objects are pasted to the point of marker position at the time of copying objects to the clipboard. If the marker is not moved between the copy and paste operations, objects are located in the same coordinates as the original; otherwise they shift on a vector that connects marker positions during copy and paste operations.

8.4. Vector objects editing

8.4.1. Vertices editing

The system provides the following editing operations both for point objects and for polylines/polygons vertices:

- **delete** – to delete selected point/vertex press **Delete**;
- **remove together with adjacent segments** – see [Removing vertices together with adjacent segments](#);
- **move** – to move selected point/vertex press **Ctrl**; In XY-plane point moves with mouse or arrow keys, by Z – with **Page Up**, **Page Down** hotkeys or by rotate mouse wheel;
- **move to marker position**:
 - to move **point/vertices to marker position** is used the **Vectors › Geometry › Move point to marker (J)**;
 - to move **marker to selected vertices** is used the **Vectors › Geometry › Move marker to selected point (~)**;
 - to move **all vertices to marker height** select object and choose **Vectors › Geometry › Move to marker height (K)**.



Marker positioning to necessary position is performed manually (see [Section 3.4](#)) or using the [Markerwindow](#) by input coordinate values from keyboard.

- **line orthogonalization on vertex** – to move polygon or polyline vertex, connected to the selected one, use menu items **Vectors › Geometry › Orthogonalization forward (Ctrl+F)** and **Vectors › Geometry › Orthogonalization backward (Ctrl+B)**. The vertex is moved so that the angle at the selected vertex is a multiple of 90. During orthogonalization forward the system moves a vertex following the selected, and during orthogonalization backward – a vertex preceding the selected. Sequence of vertices is displayed when you select a vector object (see also [Section 5.3.4](#)).



If the **Edit › Point editing mode** parameter is selected, then moving common vertices is performed at the same time (see [Section 11](#)).



If the **Edit › Point editing mode** parameter is selected and some amount of vertices of different objects are “connected”, after that it is possible to edit them simultaneously using snapping to nodes option (see [Section 3.4.6](#)) and the menu item **Vectors › Geometry › Move to marker position**.

8.4.2. Adding vertices to a line segment

The system allows to add vertices into a polyline or polygon segment.

In order to insert a vertex to selected polyline/polygon, place marker to necessary position and press **Insert**.



If the **Edit › Point editing mode** parameter is selected, when inserting a vertex between two connected vertices located on the common border of several polygons, the new vertex is inserted into all of polygons.

8.4.3. Polyline moving

To move [selected polyline/polygon](#) press the **Ctrl** key. Move a polyline in XY plane using mouse or arrow keys. To move it by Z, use **Page Up**, **Page Down** keys or mouse wheel rotation;



If there are selected vertices in polylines, the system moves only these vertices, and not the entire polyline.

8.4.4. Polyline deleting

To delete selected polyline/polygon use the **Delete** key.

If there is selected vertex in selected polyline, this vertex deletes first, and after the next press of the **Delete** key the whole polyline will be deleted.

8.5. Vector objects interpolation

8.5.1. Quick interpolation

Operation of “fast” objects interpolation is used to smooth the angles of linear vector objects and is applied, when the accuracy and quality of results are not significant. The operation consists of replacing vertex of each polyline with the middle of the polyline segment.

To execute fast interpolation perform the following actions:

1. Select **Vectors** › **Interpolate** › **Quick interpolate**. The **Fast interpolation** window opens.

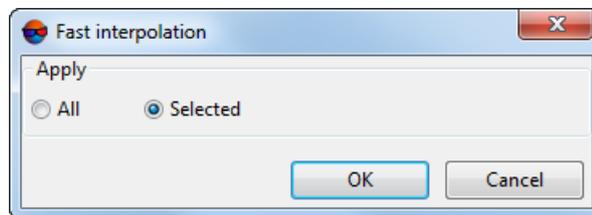


Fig. 84. Quick interpolation parameters

2. [optional] Select **Selected** to interpolate selected objects only, otherwise, select – **All**.
3. Click OK to apply the interpolation.

8.5.2. Corners round off

To perform the round off corners at vertices of linear vector objects perform the following actions:

1. Select **Vectors** › **Interpolate** › **Round off corners**. The **Settings** window opens.

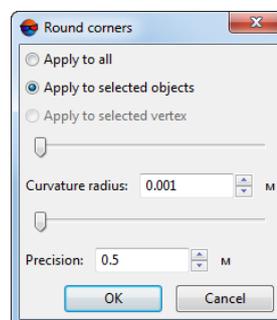


Fig. 85. Parameters of vector objects corners round off

2. Select objects to round off their corners:

- **Apply to all** – allows to round off corners of polylines/polygons;
- **Apply to selected objects** – allows to round off corners of selected polylines/polygons only;
- **Apply to selected vertex** – allows to round off corners of selected polylines/polygons only;



Change the **Curvature radius** and **Precision** values using appropriate sliders to display results of round off operation in real time. That is why the sliders are enabled only when there is a single selected object, in order to avoid start of a long calculation process.

3. Move slider or input the **Curvature radius** for smoothing curve.



The smaller the radius, the closer the smoothing curve to initial polyline vertices.

4. Specify in the input field or using the **Precision** slider the precision parameter – maximal distance from polyline segment to a curve in the area between the two closest vertices.

5. Click OK. After that the corners near vector objects vertices are round off considering specified parameters.

8.5.3. Vertices thinning out

The operation is used to reduce the number of vertices in all or selected linear vector objects.

To perform thinning out vectors vertices perform the following actions:

1. Select **Vectors** › **Interpolate** › **Thin out polylines**. The **Thinning parameters** window opens.

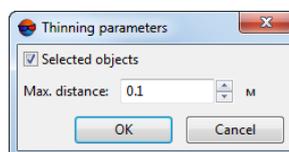


Fig. 86. Parameters of linear objects thinning out

2. [optional] Set the **Selected objects** checkbox on to thin out vertices for selected objects only.

3. In the **Max. distance** field specify distance between two adjacent vertices. If vertices located closer than a specified distance, one of vertices is deleting.
4. Click OK. After that operation the linear objects vertices located closer to each other then the specified distance are removed.

8.5.4. Interpolation

During interpolation polylines/polygons are smoothed by adding additional vertices along calculated Bezier curve.

Perform the following actions to perform interpolation of polylines/polygons:

1. Select **Vectors > Interpolate > Interpolate**. The **Settings** window opens.

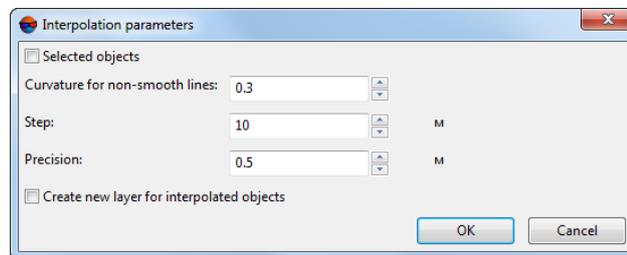


Fig. 87. Parameters of polyline interpolation

2. In the **Curvature for non-smooth lines** field specify the degree of curvature of the Bezier curve.



Recommended values range is from 0.1 to 1.0.

3. In the **Step** field specify the distance between the polyline vertices approximating the Bezier curve.
4. In the **Precision** field specify maximal distance from the Bezier curve to polyline approximating it. At a distance greater than the specified, additional vertices are added to a polyline until the condition is satisfied.
5. [optional] To interpolate selected objects only, set the **Selected objects** checkbox on, otherwise, this operation will be performed for all objects.
6. [optional] To save the interpolation results to a separate layer, set the **Create new layer for interpolated objects** checkbox on.
7. Click OK to perform interpolation of vector object.

8.5.5. Elevations interpolating

When perform vectorization of linear objects on the terrain, which relief uniformly changes, it is possible to use interpolation of polylines/polygons by their elevation.

Perform the following actions to do this:

1. After polyline creation choose **Vectors › Interpolate › Interpolate elevations**.
2. Choose objects for interpolation.
 - **Current** – selected object chosen by double-click; displayed with bold line in a 2D-window;
 - **Selected** in 2D-window objects;
 - **All** objects.
3. Click OK. Elevations of vertices located between the start and end points are interpolated proportional to the distance between the intermediate vertices and the difference in elevation between the start and end vertices.

8.5.6. Convolution smoothing

The system provides possibility to perform convolution smoothing to reduce the probability of the intersections obtained during interpolation of contours generated from TIN.



Convolution is performed for each coordinate axis. Each axis described as a function of the length of the polyline with the kernel specified using “Exponential” or “Gaussian” methods.

To smooth contour lines using convolution, perform the following actions:

1. Select **Vectors › Interpolate › Convolution smoothing**. The **Convolution smoothing** window opens.

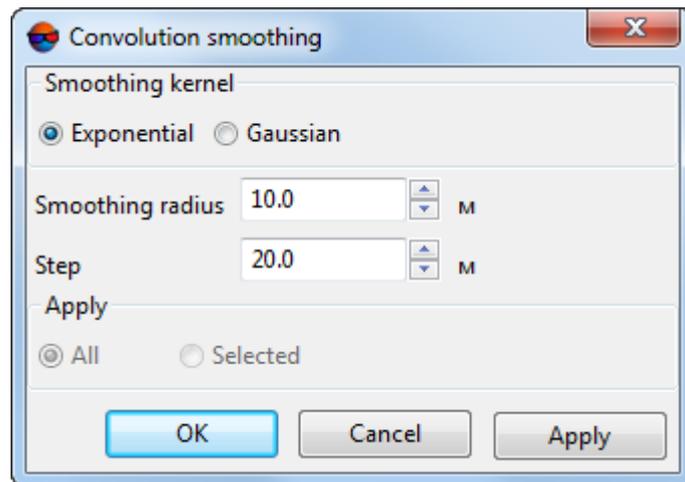


Fig. 88. Parameters of convolution smoothing

2. Select smoothing method: **Exponential** or **Gaussian**.
3. Define the following parameters of smoothing:
 - **Smoothing radius** – allows to specify the characteristic distance of points influence during convolution;
 - **Step** – allows to specify a polyline step.
4. [optional] In the **Apply to** section select **Selected** to smooth selected objects only, otherwise, select – **All** (by default).
5. [optional] Click **Apply** for contour smoothing preview. Change smoothing parameters if needed;
6. Click OK. The system performs smoothing operation.

8.5.7. Smoothing vector objects

To smooth a shape of vector objects, perform the following actions:

1. [optional] **Select** all the vector objects to which it's necessary to applied a smoothing procedure.
2. Choose **Vectors** › **Interpolate** › **Smooth**. The **Smooth objects** window opens.

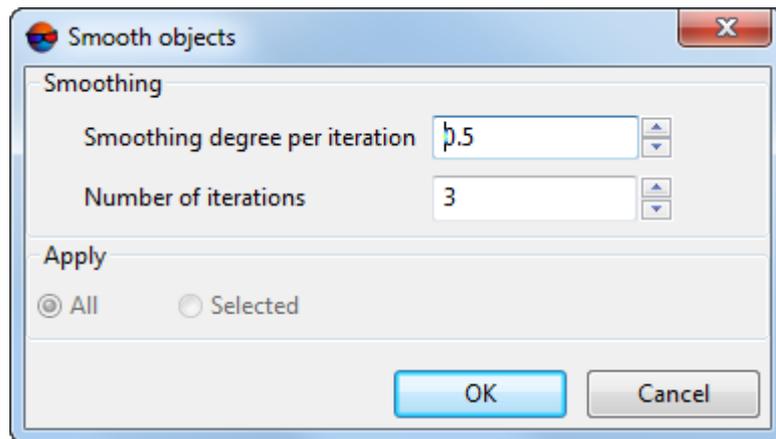


Fig. 89. Parameters of smoothing vector objects

3. In **Smoothing** section set parameters of smoothing vector objects:
 - **Smoothing degree per iteration** – the maximum value of **Smoothing degree per iteration** – 1;
 - **Number of iterations** – the maximum value is 100;
4. In **Apply** section select objects to which a smoothing is applied:
 - **All** – allows to smooth all the vector objects;
 - **Selected** – allows to smooth selected polylines/polygons only;
5. Click OK. As a result vector objects are smoothed with parameters specified.

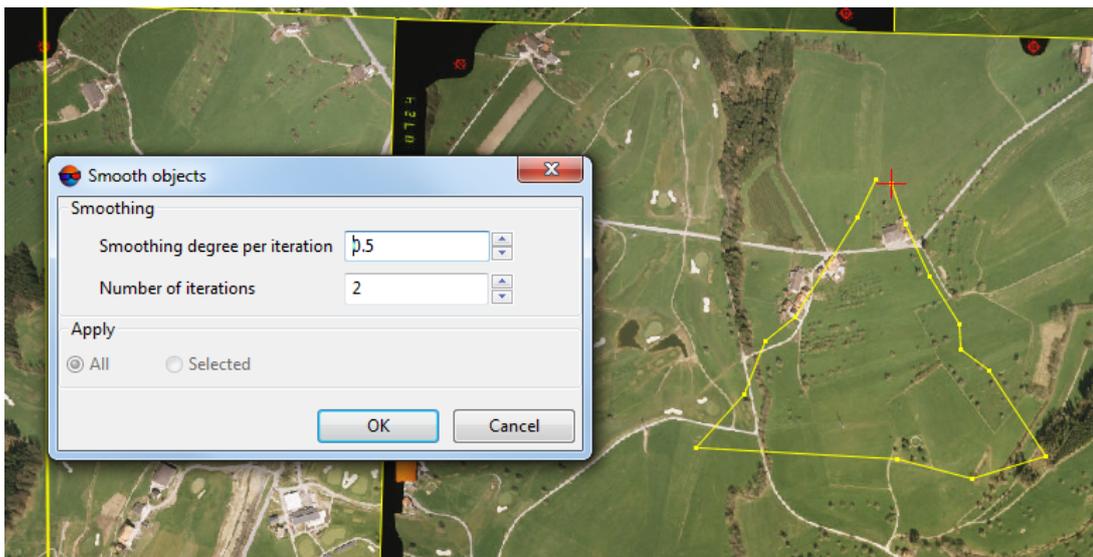


Fig. 90. Input of smoothing vector object parameters



Fig. 91. Vector object after smoothing applied

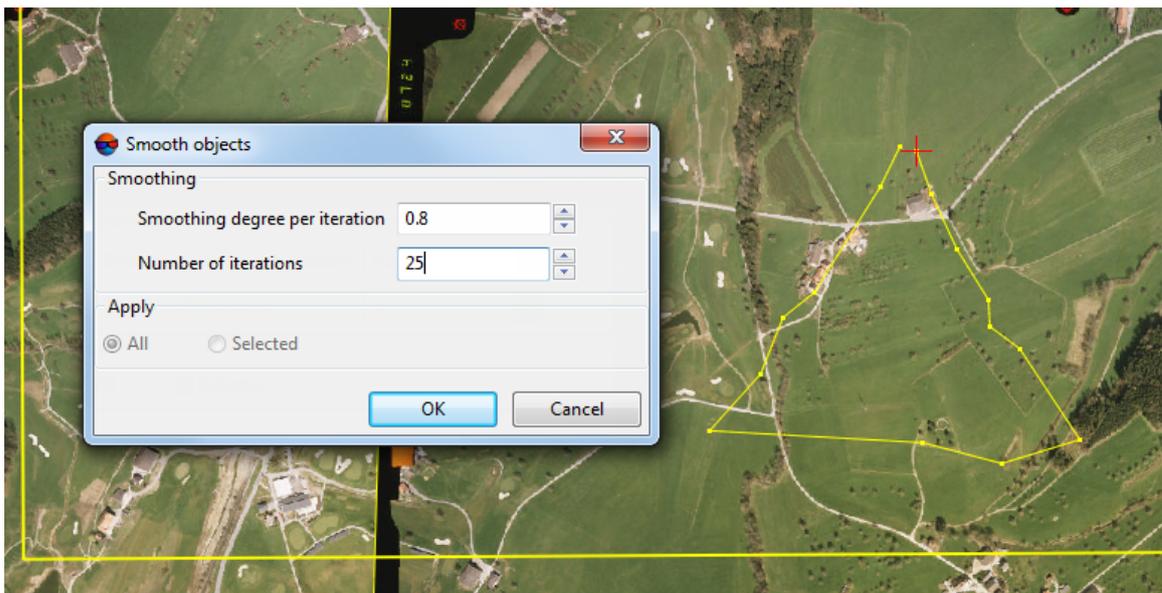


Fig. 92. Input of smoothing vector object parameters



Fig. 93. BVector object after smoothing applied

8.6. Editing of smooth curves

8.6.1. The “Curve transforms” menu

The system allows to create and edit **smooth curve lines**.

To do this there are menu items **Edit > Curve transforms** and buttons of the **Vectors** additional toolbar (see [Section 5.1](#)).

Table 10. Brief description of the “Curve transforms” menu

Menu items	Function
 Convert polygonal chains to curves	allows to convert selected broken lines to smooth ones (see Section 8.6.3)
 Convert curves to polygonal chains	allows to convert selected smooth curves to broken lines (see Section 8.6.3)
 Resmooth on editing	allows to recalculate automatically smoothing of curve line segments during object editing (see Section 8.6.4)
 Edit control nodes	allows to enable curve check points editing (see Section 8.6.5)
 Smooth editing of curve control nodes	allows to preserve smoothing during editing of curve check points (see Section 8.6.5)
Curves smoothing	allows to configure curves smoothing (see Section 8.6.6)

8.6.2. Smooth curves creation mode

The system provides smooth curves creation mode.

To create smooth curves choose **Edit › Vector create mode › Curves** or click the  button of the **Vectors** additional toolbar.

Smooth curves creates as ordinary polylines (see [Section 5](#)). When work with **classifier** object code with L (line) type should be selected.

To perform automatic curve smoothing during its creation select **Edit › Curve transforms › Resmooth on editing** or click the  button of the **Vectors** additional toolbar.

8.6.3. Conversion of smooth curves

The system provides opportunity to convert selected broken lines to smooth curves and vice versa.

To perform conversion of selected broken lines to smooth curves is used the **Edit › Curve transforms › Convert polygonal chains to curves** menu item and the  button of the **Vectors** toolbar.

To convert selected smooth curves to broken lines is used the **Edit › Curve transforms › Convert curves to polygonal chains** menu item and the  button of the **Vectors** toolbar.

8.6.4. Automatic smoothing

The system provides opportunity to automatically change the degree of the curve smoothing, while its creating or editing.

[optional] To do this select **Edit › Curve transforms › Resmooth on editing** or click the  button of the **Vectors** additional toolbar. During any editing of smooth curve vertices using markers of nodes control the smoothness of the curve does not change.

8.6.5. Editing of curve line segments

The system provides possibility to edit curve line segments. To enable such mode select **Edit › Curve transforms › Edit control nodes (X)** or click the  button of the **Vectors** additional toolbar. The position of the segments of created smoothed curves is edited by pressing **Ctrl** key and by right mouse button, using “traction” of markers of polyline vertices control.

To switch the option of angles forming when editing the curve segments, select **Edit › Curve transforms › Smooth editing of curve control nodes** or click the button of the **Vectors** additional toolbar.

8.6.6. Smoothing control

The system provides possibility to smooth existing curves.

To change smoothing degree perform the following actions:

1. Choose **Edit › Curve transforms › Curves smoothing**.

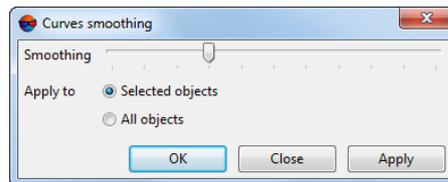


Fig. 94. Curves smoothing degree

2. Set the smoothing degree using the appropriate slider.
3. [optional] Choose objects to transform: to **Selected objects** or to **All objects**.
4. Click **Apply** to show changes in 2D-window. Click OK to complete operation.

8.7. Undo editing operations

The system allows to undo edit operations of vector objects, and also to redo recently undone operations (see the “[General information](#)” User Manual).

To cancel the last operation of vector objects editing, select **Edit › Undo (Ctrl+Z)** or click the  button of the main toolbar. To redo the last undone operation of vector objects editing, select **Edit › Redo (Ctrl+Shift+Z)** or click the  button.

In order to open the recent editing operations list select **Edit › Undo log** or click the  button.

To cancel a group of operations double click in the **Undo log** on line with action to which you want to undo changes. Lines with undone operations are marked by italic font. To redo all undone operations, double click the line with action to which you want to redo changes.

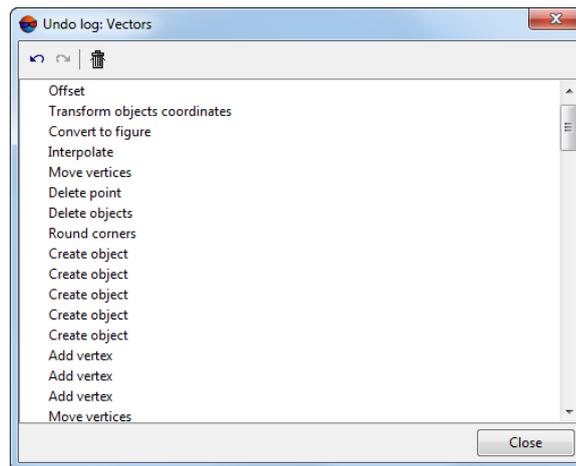


Fig. 95. Undo log

To clear log is used the  button. After that undo and redo actions become unavailable.



List of undo operations is maintained for each layer separately.

The undo log clears automatically in the following cases:

- after exceeding of information volume about operations list;
- when you start the large volume of automatic transformations or calculations (for example, during creation contour lines using large volume data source).

In these cases the system displays a warning that it will be impossible to cancel the transformations.



When working with a fair amount of vector objects using of undo mode slows down editing operations. To increase the performance, disable the undo log creation (see the “[General system's parameters](#)” User Manual).

8.8. Additional coordinate system

The system allows to create additional (user) coordinate system which is used as a helping vectorization tool together with **Snapping to coords** function:

- To create additional (user) coordinate system select **Edit › Add coord system** or click  button in **Vectors toolbar**. Axes direction of the additional coordinate system is shown at the left bottom corner of 2D-window;
- To change default axes direction of additional coordinate system perform the following:
 1. Select **Edit › Edit coord system** or click  button in **Vectors toolbar** to turn on mode of editing user coordinate system;

2. Set X axis direction of the additional coordinate system while using **Polylines (L) mode** (draw one segment line, vertices of which are specified X axis direction). Axes direction of the additional coordinate system will be changed according to the specified one. Edit coord system mode will be turned off automatically.
- To delete additional coordinate system select **Edit › Delete coord system** or click  button in **Vectors** toolbar.

The system allows to add to the marker *guides* in the form of red and green dash lines which are co-directed with the active (main or additional) coordinate axes. The red line is aligned with the X-axis, and the green one is aligned with the Y-axis. The guides enable us to assess mutual alignment of the objects on images.

To add guides to the marker select **Service › Settings**. The **Settings** window opens. On the **Windows** tab of the **Settings** window set the **Coord lines under marker** checkbox.

The system also allows to rotate the marker crosshair according to the additional coordinate system axes (see the “Marker settings” chapter in the “[General system’s parameters](#)” User Manual).

9. Vector objects filtering

To edit vector objects the system provides the following filters:

- **Filter by Z-range** – filtering points and vertices of polylines/polygons, which Z-coordinate is out of specified range;
- **Median Z filter** – filtering points and vertices of polylines/polygons using mask of specified size;
- **Filter adjacent point objects** – filtering of closely located points (located nearer than specified distance);
- **Linear objects filtering** – filtering polylines/polygons, that linear size (coordinates range by one of axes) is more or less of specified value;
- **Surface objects filter** – filtering points, which have fallen on particular tall objects or pits of specific size.

The set of filters used for editing vector objects partially coincides with the instruments for points filtering (**Terrain › Points › Filter** menu, see “Points filtering” section of the “[DTM Generation](#)” User Manual).

9.1. Points filtering by Z-range

The system provides possibility to remove points and vertices of polylines/polygons, which Z-coordinate falls outside specified range.

To perform objects filtering of active vector layer by elevations range, execute the following actions:

1. Select **Vectors** > **Filter** > **Filter by Z-range**. The **Z-range filter** window opens.

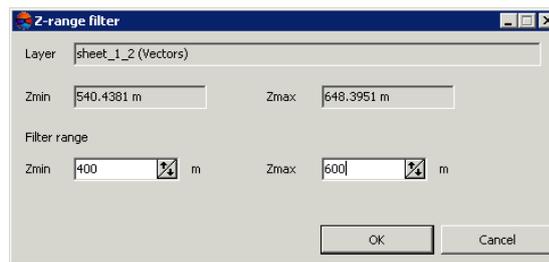


Fig. 96. Parameters of points filtering by Z

The **Layer** field displays a name of selected active vector layer, the **Zmin** and **Zmax** fields show terrain elevation difference in meters, calculated by all layer objects.

2. The **Filter range** section by default shows values of calculated terrain elevation difference. Specify maximal and minimal Z values in meters to consider for points/vertices filtering.
3. Click OK. Filtration removes all points and vertices of polylines/polygons, which Z-coordinate falls outside specified range. When the filtering operation is completed the system displays information message about number of deleted points.

9.2. Median points filtering by Z

The system provides possibility of median filtering to remove single sharp spikes in presence of smooth relief.

The *median filtering* contains the following sequence of actions:

1. Sequential scanning of area with vector objects by window-mask. Scanning step is specified as window-mask halfsize.
2. Deleting points which elevation is out of range.



The range is calculated as average level of vectors elevation that fall into mask. When calculating the range the system considers specified deviation from average level.

To execute median filtering perform the following actions:

1. Select **Vectors** > **Filter** > **Median Z-filter**. The **Median Z filter** window opens.

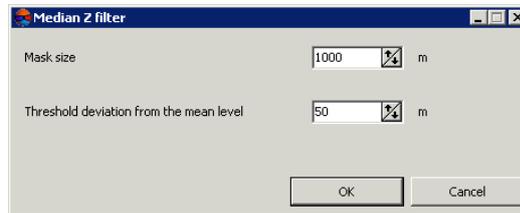


Fig. 97. Parameters of median points filtering

2. In the **Mask size** field specify a side size of scanning square window-mask in meters.
3. In the **Threshold deviation from the mean level** field specify deviation by Z in meters from mean level of objects elevation in the mask.
4. Click OK. Filtration removes all points and vertices of polylines/polygons, which Z-coordinate falls outside specified range. When the filtering operation is completed the system displays information message about number of deleted points.

9.3. Filter of adjacent point objects

Filter of adjacent point objects allows to remove points, in which vicinity there are other objects located closer specified distance.

To filter adjacent points on active layer perform the following actions:

1. Select **Terrain** > **Points** > **Filter** > **Filter adjacent point objects**. The **Filter adjacent point objects** window opens.

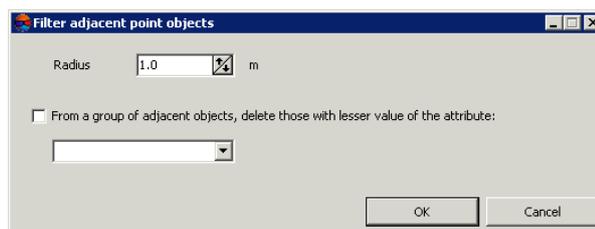


Fig. 98. Parameters of adjacent point objects filter

2. Specify the **Radius** – maximal distance in meters to each point, and if a points falls closer that the radius value, the points is deleted.
3. [optional] In order to delete from two points just one which contains the smallest value of one attribute (for example, if points vector layer was created in automatic points calculation mode with preserving of quality assessment in attributes), set the

From a group of adjacent objects, delete those with lesser value of the attribute checkbox on and select in the list an attribute to be considered during points removal.

4. Click OK. Filtration removes points, between which the distance is less than specified. When the filtering operation is completed the system displays information message about number of deleted points.

9.4. Filtering of linear objects

The system provides the possibility to delete vector object whose length (perimeter) or linear dimension (i.e. the range of coordinates along one of the axes) do not match the specified value.

To use filtering of linear objects perform the following actions:

1. Select **Vectors > Filter > Selective delete objects**. The **Delete lines** window opens;

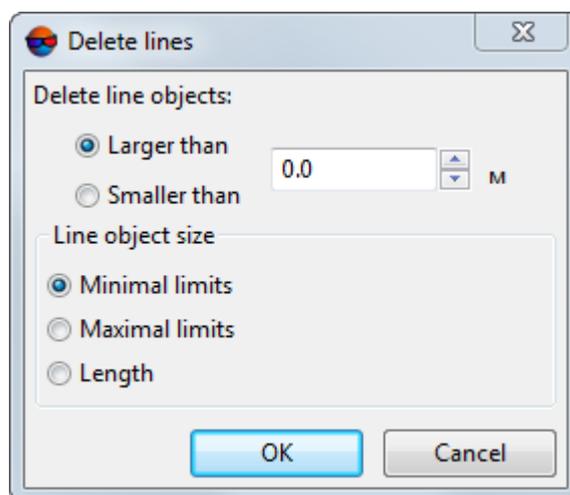


Fig. 99. Parameters of linear objects filtering

2. Set size of objects to be deleted (in meters);
3. Select filtering method:
 - **Larger than** – used to delete objects, size of which exceeds the specified value (in meters);
 - **Smaller than** – used to delete objects, size of which is less than specified value (in meters).
4. In the **Line object size** section select the size calculation method:
 - **Length**;

- **Minimal limits / Maximal limits** – linear size (by one of the axes).
5. Click OK. Filtration removes all linear objects with size that is more or less than specified.

9.5. Surface objects filter

The system provides possibility to correct blunders of correlation, obtained, for example, during automatic points calculation. The **Surface objects filter** allows to delete points located on terrain surface with specified **typical size** by XY and Z.



This filtering type is not used for objects of completely built-up area, forest belts and similar objects.

The principle of filtering is to estimate the location and size of the contours created using TIN, which was generated with help of initial points. A surge is a group of contours that is not greater than specified size by XY and with elevations in specified range.



Surface objects filter is recommended to use to eliminate sharp spikes. For more fine filtering it is recommended to use this filter along with buildings and vegetation filter (see the “[DTM Generation](#)” User Manual).

To apply filter of objects on surface perform the following actions:

1. Select **Vectors** › **Filter** › **Surface objects filter**. The **Surface objects filter** window opens.

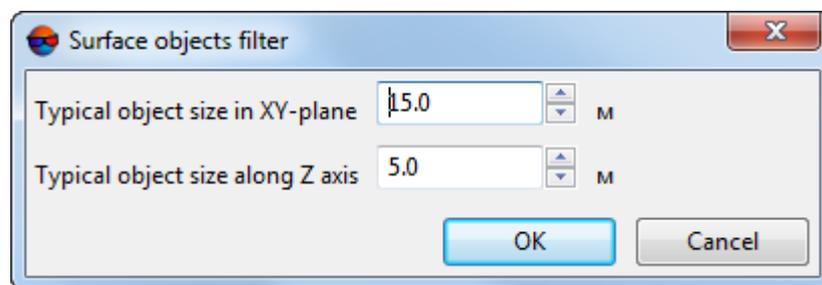


Fig. 100. Parameters of surface objects filter

2. Specify the **Typical object size in XY-plane** and **Typical object size along Z axis** in corresponding fields in meters.
3. Click OK to remove points found.

10. Geometric transformations of vector objects

Table 11. Brief description of the “Geometry” menu

Menu items	Function
Move point to marker	allows to move point/vertices to marker position (see Section 8.4.1)
Move marker to selected point	allows to move marker to selected vertices (see Section 8.4.1)
Delete points around polylines	allows to delete points used for the TIN creation around linear objects (see Section 10.4.1)
Delete points inside polygons	allows to delete points inside polygons. Points and polygons could be located both in one layer and different (see Section 10.4.2)
Swap X <-> Y	allows to swap X and Y coordinates of vector objects (see Section 10.5.1)
Convert coordinate system	provides opportunity of coordinates recalculation from one coordinate system to another for all vertices of current layer (see Section 10.5.2)
Move	provides possibility both to move vector objects by a predetermined vector using X, Y, Z coordinates, and to set a predetermined elevation without vectors movement (see Section 10.1)
Move to marker height	allows to move all vertices of the object to marker height (see Section 8.4.1)
Transform...	allows to perform geometric transformation of vector objects: rotation by the angle and scaling (see Section 10.1.8)
Projective transform...	allows to perform projective transformation of vector objects (see Section 10.1.10)
Convert to figure	provides opportunity to convert arbitrary polygons into standard geometric shapes: ellipse, round, rectangle, square, orthogonal polygon (see Section 10.1.3)
Convert polygons to points	allows to convert all or selected polygons into point objects (see Section 10.1.2)
Cut objects by selected polygons	provides the possibility of cutting vector objects of one layer by the boundaries of polygons of another layer (see Section 10.1.5)
Cut objects around selected	allows to cut vector objects around selected vectors placed at the same layer (see Section 10.1.6)
Convert all vertices to point objects	provides possibility to convert all vertices both of polylines, and polygons to point objects (see Section 10.1.2)
Split into layers by object type	allows to split objects into layer depending on their type (see Section 10.1.7)

Menu items	Function
Buffer zone...	allows to create a <i>buffer zone</i> – a polyline/polygon parallel to selected line and situated at a predetermined distance from it (see Section 10.2.3)
Objects around points...	allows to create circles with defined radius or squares with defined side length around vertices of linear objects (see Section 10.2.4)
Vectors profiles...	provides the function of construction of perpendicular profiles through the group of linear vector objects (see Section 10.2.5)
Correct by residuals...	allows to perform operation of vector layer correction using residuals vectors is intended to clarify the position of vector objects (see Section 10.1.4)
Elevation Profile	allows to create an elevation profile of a linear object (in the form of chart, whose vertices are the vertices of a polyline, see Section 10.7)
Add intersection points	provides the ability to automatically add a vertex at the intersection of vector objects (see Section 10.2.1)
Symmetric objects	contains menu items to to create symmetrical lengthy objects both linear and areal (see Section 10.2.2)
Orthogonalization forward / Orthogonalization backward	allows to move polygon or polyline vertex, connected to the selected one (see Section 8.4.1)
Project on stereomodel	provides possibility to project vector objects on relief of active stereopair (see Section 10.3)
Project on TIN	allows to project vector objects on TIN (see Section 10.3.2)
Project on DEM...	allows automatically assign elevation marks to points with known XY coordinates from loaded DEM (see Section 10.3.3)
Cut CSV file by rectangle edges	allows to delete from CSV-file points out of defined boundaries (see Section 10.6)
Cut CSV file by selected polygons	allows to cut CSV file by selected polygons (see Section 10.6)
Check orthogonality	provides possibility to check orthogonality of polygons corners (see Section 10.2.6)

10.1. Transformation of vector objects

10.1.1. Vector objects moving

The system provides possibility both to move vector objects by a predetermined vector using X, Y, Z coordinates, and to set a predetermined elevation without vectors movement.

In order to move vector objects perform the following actions:

1. Select **Vectors > Geometry > Move**. The **Move objects** window opens.



Fig. 101. Parameters of objects moving

2. Select one of the following ways of moving:
 - **By given vector** – specify X, Y, Z values (in meters), that define a size of moving vector;
 - **Set Z** – set Z value (in meters) to move objects to specified elevation.



To set zero value double-click on selected field.

3. [optional] Select **Selected** in the **Apply** section, to move selected objects only, otherwise, select **All**.
4. Click OK. After that vector objects are moved to specified distance or elevation.

10.1.2. Converting polygons to points

The function polygons to points conversion is intended for conversion of all or selected polygons into point objects.



The code with P (points) type should be selected to perform operation in the vector layer with classifier. Otherwise conversion couldn't be performed.

To perform the conversion, select **Vectors > Geometry > Convert polygons to points**. If there is selected objects in the layer, both all and only selected objects could be converted.

As a result of the operation the polygons are replaced by point objects. These points are placed in the mass centers of the boundaries of the original polygons. In the layer with classifier selected code is assigned to new point objects and all attributes of source linear objects.

The system also provides possibility to convert all vertices both of polylines, and polygons to point objects. To perform the conversion, select **Vectors › Geometry › Convert all vertices to point objects**. The new vector layer containing point objects is created.

10.1.3. Conversion of vector object to geometric shape

The system provides opportunity to convert arbitrary polygons into standard geometric shapes:

- ellipse;
- round;
- rectangle;
- square;
- orthogonal polygon.

In order to convert active layer polygons into geometric shapes perform the following actions:

1. Make vector layer active.
2. Select **Vectors › Geometry › Convert to figure**. The **Parameters** window opens.

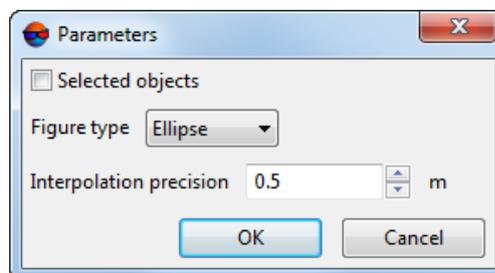


Fig. 102. Parameters of vector object conversion into geometric shape

3. [optional] Set the **Selected objects** checkbox on to convert only to selected polygons. Otherwise, all polygons are converting.
4. Define the following parameters:
 - **Figure** for conversion;
 - **Precision** for conversion.



The system allows to approximate vector objects presented in the form of curves by broken lines. This approximation precision, that is maximal distance from the broken

line segment to the curve between two closest vertices, is specified by user. This parameters default value is 0.5 in measurement units of current project (usually in meters).

5. Click OK. Polygons convert to selected geometric shape with specified approximation precision.

10.1.4. Correcting by residuals vectors

The operation of vector layer correction using residuals vectors is intended to clarify the position of vector objects.

To perform vector layer correction using residuals vectors, execute the following actions:

1. Open the layer with residuals vectors (linear objects).



Residuals vector layer should be create, for example, by [measuring](#) of residuals on points manually. To create a new vector layer set the **Save measurements in layer** checkbox on in the **Measurement** window.

2. Open the layer to be corrected.
3. Select **Vectors > Geometry > Correct by residuals**. The **Settings** window opens.

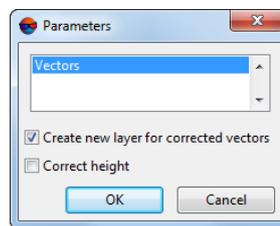


Fig. 103. Parameters of correcting by residuals vectors

4. Select a layer with residuals vectors in the list.
5. [optional] To correct objects in active layer, set the **Create new layer for corrected vectors** checkbox off. Otherwise new vector layer creates.
6. [optional] To change not only XY coordinates, but also the height, set the **Correct height** checkbox on.
7. Click OK. The new vector layer containing corrected vectors is created.

10.1.5. Cut vectors by selected polygons

The system provides the possibility of cutting vector objects of one layer by the boundaries of polygons of another layer. Perform the following actions to do this:

1. Open a layer with polygons to be used as borders, or make this layer editable.
2. **Select** polygons to be used as boundaries.
3. Select **Vectors > Geometry > Cut objects by selected polygons**.

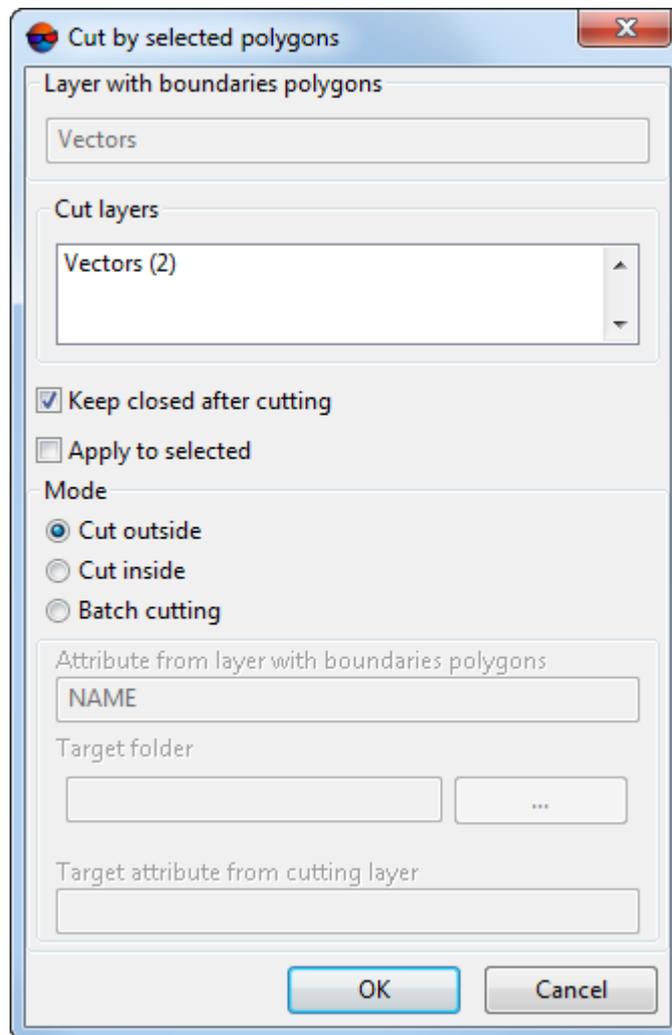


Fig. 104. Parameters of cutting by boundaries

4. In the **Cut layers** list select a layer with objects to be cut.
5. [optional] In order to not to close the polylines after cutting automatically, set the **Keep closed after cutting** checkbox off.
6. [optional] To apply the operation to selected objects only, set the **Apply to selected** checkbox on.
7. Select **mode**:

- **Cut outside** – to cut vector objects located out of selected polygons;
 - **Cut inside** – to cut vector objects located inside the selected polygons;
 - **Batch cutting**.
8. Click OK. After that the system removes all objects of the layer specified, that are located outside the selected boundary.

Batch vector cutting by selected polygons

The system allows for batch cutting of vector objects within one layer by polygon boundaries within other layer.

The batch cutting results in creation of new vector layers each of which contains objects cut by the internal boundary of one of enclosing polygons. The initial layer containing the objects to be cut remains unchanged.

This function can be used e.g. to cut notation sheets by the image block scheme. To do this, perform the following:

1. Choose **Block > Create vector layers from block layout** in order to create a *Block scheme* vector layer that displays image boundaries (see more details in the “Creating vector layers from block layout” chapter of the “Creating project” User Manual).

The polygons located in the *Block scheme* vector layer have the following automatically specified attributes:

- **Name** of attribute – *Label*;
- **Type** of attribute – *text*;
- Attribute **value** – *Image_name*.



If polygons used as boundaries have no attributes, [create](#) attributes before batch cutting.

2. Create a separate vector layer with [notation sheets](#).

Notation sheets created by generators of splitting into sheets have the following automatically specified attributes:

- **Name** of attribute – *Name*;
- **Type** of attribute – *text*;
- Attribute **value** – *Sheet_name*.



If vector objects for batch cutting have no attributes, [create](#) attributes before batch cutting.

3. Make the layer with polygons to be used as boundaries editable;



In given case this is the *Block Scheme* layer.

4. Select polygons to be used as boundaries;
5. Choose **Vectors** > **Geometry** > **Cut objects by selected polygons**;

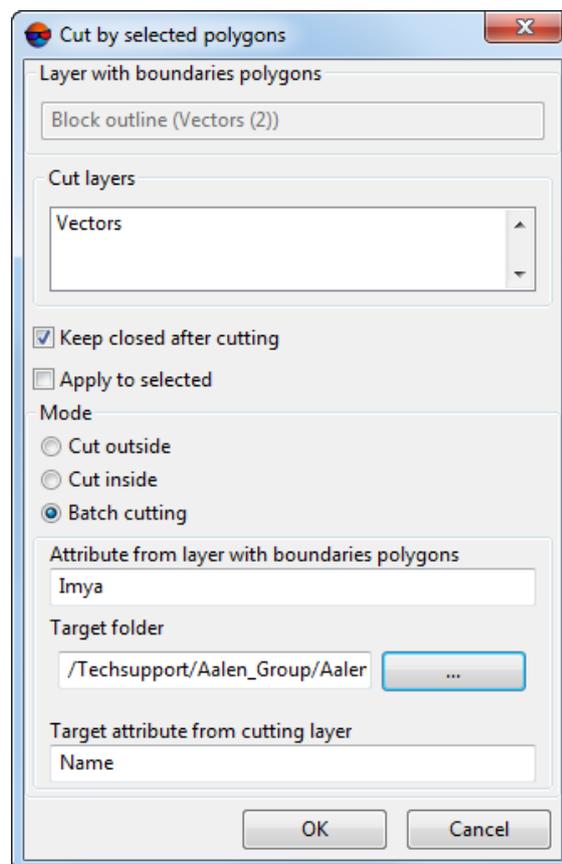


Fig. 105. Parameters of batch cutting by polygons

6. [optional] In order not to close cut notation sheets with image boundaries, clear the **Keep closed after cutting** checkbox;
7. Select the **mode - Batch cutting**;
8. Input the **Attribute from layer with boundaries polygons**;



In given case this is the name of the attributes of polygons displaying image boundaries – *Label*.

9. In the **Target folder** field, click the button and select the folder in the active profile resources where the output vector layers are to be saved.



In given case, these are cut notation sheets as separate layers for each image boundary.

Names of output vector layers are to be set automatically from the object attribute values used as boundaries for cutting.



In given case, it is the *Label* attribute value, i.e. names of the images on the borders of which the cutting takes place.

10. Input the **Target attribute from cutting layer**;



In given case, this is the name of the attributes of polygons displaying notation sheets – *Name*.

11. Select a layer with objects to be cut in the **Cut layers** section and press Ok.



If a layer with objects to be cut was created but not previously saved, a window opens where the system suggests to save it before operation execution.

В целевой папке создаются выходные векторные слои, содержащие (в данном примере) обрезанные номенклатурные листы, замкнутые границами изображений, в случае если флажок **Keep closed after cutting** не был снят.

Output vector layers that contain (in given case) cut notation sheets are created in the target folder. The cut notation sheets are closed by image boundaries if the **Keep closed after cutting** checkbox was not cleared.

Cut notation sheets have automatically specified attributes, as follows:

- **Name** of attribute – *Name*;
- **Type** of attribute – *text*;
- Attribute **value** – Image_name_Sheet_name.



Cut notation sheets keep their attributes only if they are polygons (i.e. the **Keep closed after cutting** checkbox was not cleared).

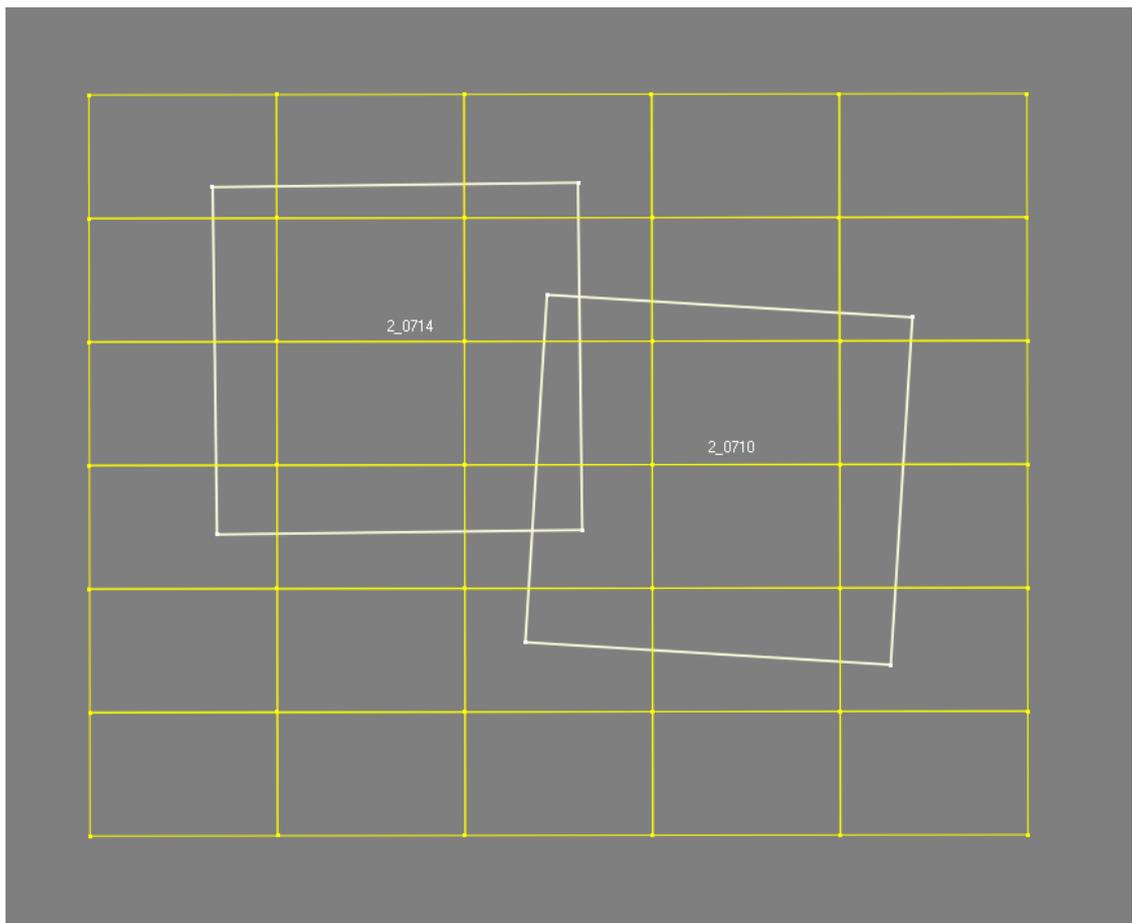


Fig. 106. Image boundaries (highlighted) and notation sheets

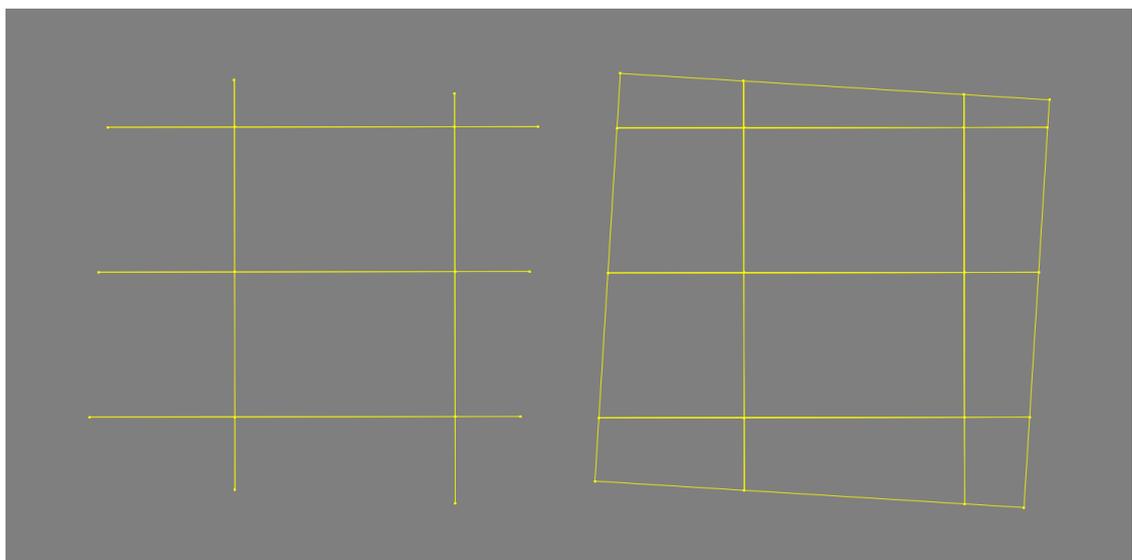


Fig. 107. Open (left) and closed (right) cut notation sheets

10.1.6. Cutting objects around selected vectors

The system allows to cut vector objects around selected vectors placed at the same layer. To do this, perform the following:

 The function is available for all types of vector objects.

1. Load or create a layer with vector objects;
2. **Select** vector objects around which it's necessary to cut all the other vector objects of the given layer.
3. Выберите **Vectors** › **Geometry** › **Cut objects around selected**.

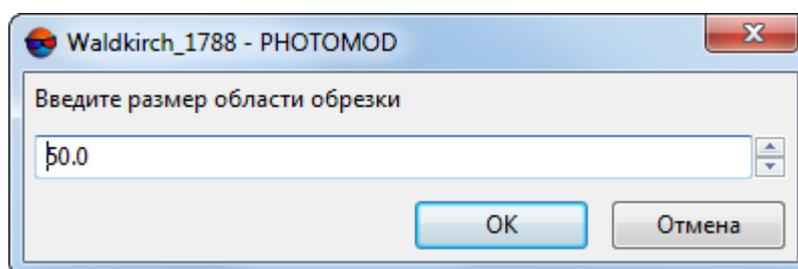


Fig. 108. Parameters of cutting objects around selected ones

4. Set a **cutting offset** around vertices and segments of the selected objects in meters.
5. Click OK. As a result, in the current vector layer all the point object and segments of polylines/polygons placed inside a cutting offset are deleted.

 In case of cutting vector objects around polygon, a cutting offset is placed both out of polygon and in it.

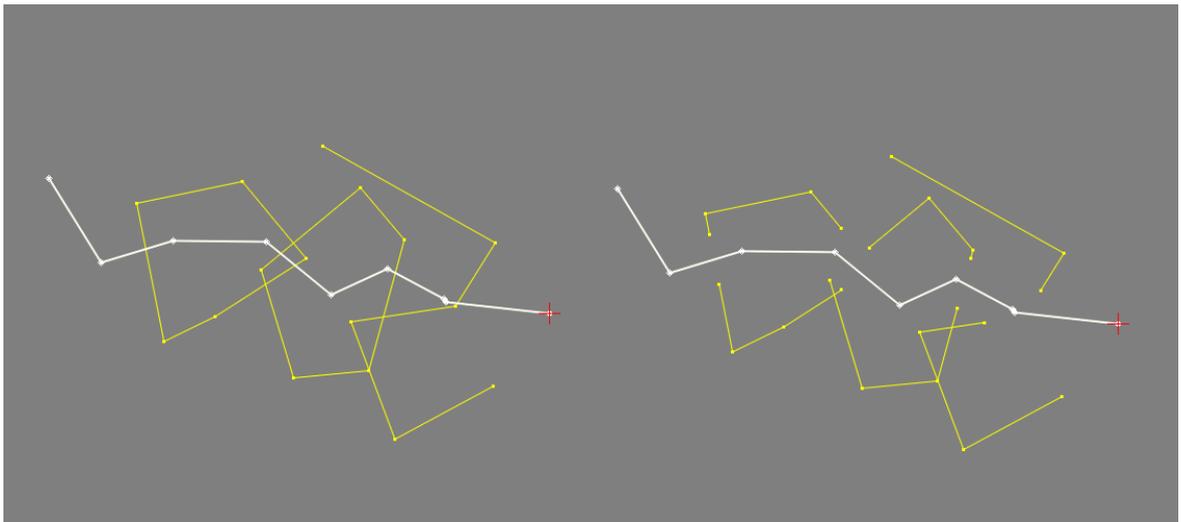


Fig. 109. Cutting vector objects around selected object

10.1.7. Splitting objects into layers depending on type

The system allows to split objects into layer depending on their [type](#).

The **Vectors › Geometry › Split into layers by object type** menu item is used for that. If the layer contains only one type, the system displays an appropriate message. In other cases two or three new layers are created, each of which contains only one type of objects.

10.1.8. Vector objects transformation

The system allows to perform geometric transformation of vector objects: rotation by the angle and scaling.



The system also allows to perform geometric transformation of vector objects in [alignment mode](#).

To do such transformation perform the following actions:

1. [Select](#) objects to be transformed.
2. Select **Vectors › Geometry › Transform › Transform....** The **Geometrical transform of selected objects** window opens.

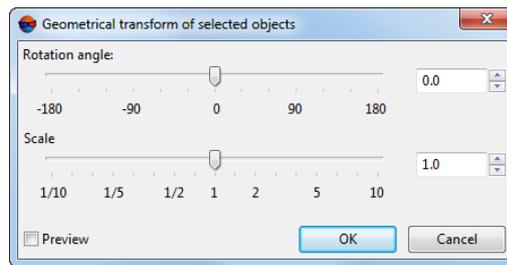


Fig. 110. Parameters of geometric objects transformation

3. Move sliders to set the following parameters:
 - **Rotation angle** – the value is set in degrees, in range from -180 to 180;
 - **Scale** – is changed from 1/10 to 10 times.
4. [optional] To disable preview mode of transformation in real time, set the **Preview** checkbox off. It is recommended to set it off when working with a large number of vector objects to increase the system performance.
5. Click OK. After that all selected vector objects are transformed in accordance with selected parameters without change of elevation value.

To rotate vector objects *manually* in *arbitrary* angle, perform the following:

1. **Select** objects to be transformed.
2. Select **Vectors › Geometry › Transform › Rotate**.
3. Press and hold **Ctrl** key and move *mouse cursor* to the point considered as a possible rotation center of the object. *No moving a cursor* press and hold **left mouse button**. Keeping **Ctrl** key and **left mouse button** rotate vector object with moving mouse.
4. Turn off parameter **Vectors › Geometry › Transform › Rotate**.



The system allows to rotate a specific vertex of the object. To do it, perform actions similar to the actions mentioned above with selecting an object vertex.



The system allows to rotate specific segments of the object. To do it perform actions similar to the actions mentioned above with preliminary selecting parameter **Edit › Point editing mode** and choosing vertices to which specific segments of the object adjoin.

To scale vector objects manually, perform the following:

1. **Select** objects to be transformed.
2. Choose **Vectors › Geometry › Transform › Scaling**.

3. Press and hold **Ctrl** key and move *mouse cursor* to the point considered as a possible scaling center of the object. *No moving a cursor* press and hold **left mouse button**. Keeping **Ctrl** key and **left mouse button** perform scaling vector object with moving mouse.
4. Turn off parameter **Vectors › Geometry › Transform › Scaling**.



Performing this function to the object selected vertex will provide a scaling of the object part which includes a vertex selected and segments adjoining to it.



To scale specific segments of the object, perform actions similar to the actions mentioned above with preliminary selecting parameter **Edit › Point editing mode** and choosing vertices to which specific segments of the object adjoin.

10.1.9. Alignment mode

The system enables for geometric transformations of objects in the alignment mode. The **alignment mode** allows to perform simultaneously the following operations with vector objects:

- rotate and scale one vector object relative to another;
- moving (connecting) vector objects on the plane and heightwise.



Connecting is the process of vector object moving so that at least one vertex of one object completely coincide on the plane with another object's vertex (see also the "Contours connecting" section of the "DTM Generation" User Manual).

To perform geometric transformation of vector objects in the alignment mode, do the following:

1. **Create** or open a layer containing at least two vector objects;
2. In order to enable the **Alignment mode**, select **Edit › Alignment mode** or click the  button of the **Tools** toolbar;
3. [optional] To scale vector objects during their transformation in the alignment mode, select **Edit › Scale when align** or click the  button of the **Tools** toolbar;
4. [optional] To connect vector object both on the plane and heightwise, select **Service › Settings › Vectors** and set the **Change Z of aligned object** checkbox;
5. Select *two* vertices of the object chosen for geometric transformation using the **left mouse button** (labels 1 and 2 will appear in the vicinity of the selected vertices).

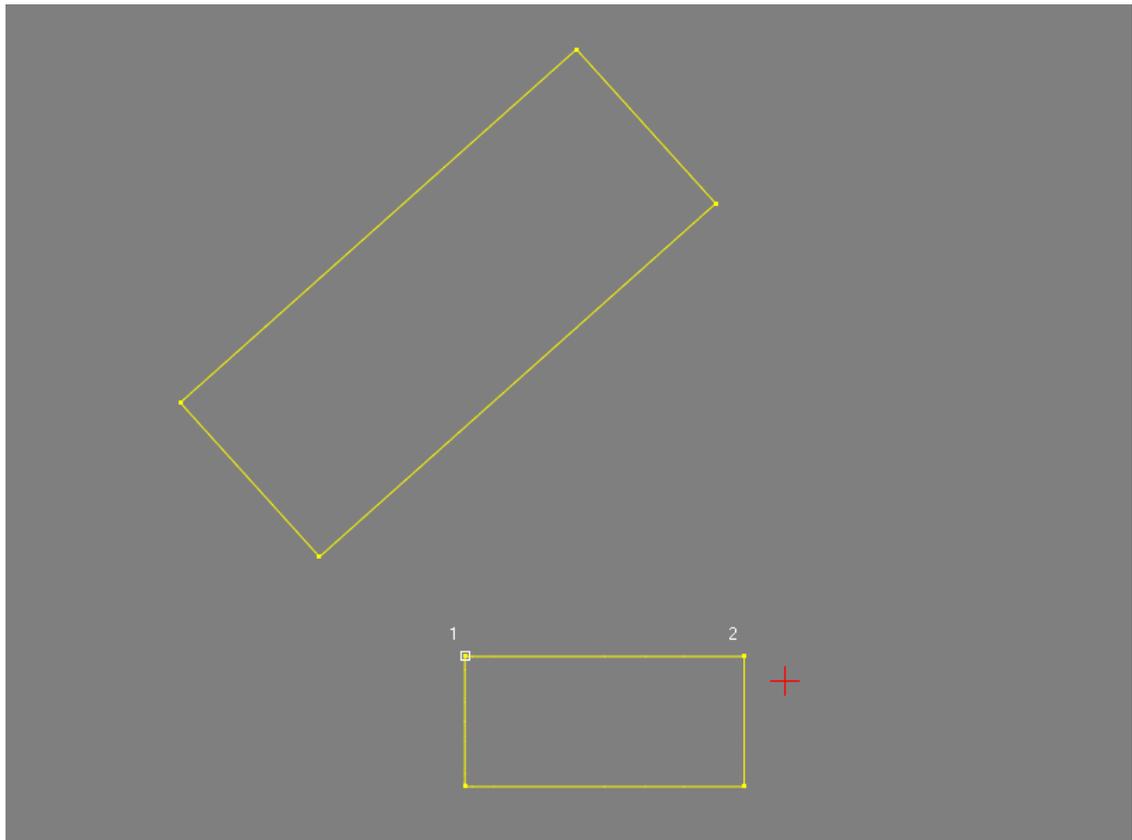


Fig. 111. Selecting vertices of the object chosen for geometric transformation.



The selected vertices need not be always adjacent.



To cancel the selection, press **Esc**.

- Using the **left mouse button**, select two vertices of the object, relative to which the transformation will be performed. Labels 1' and 2' will appear in the vicinity of the selected vertices.

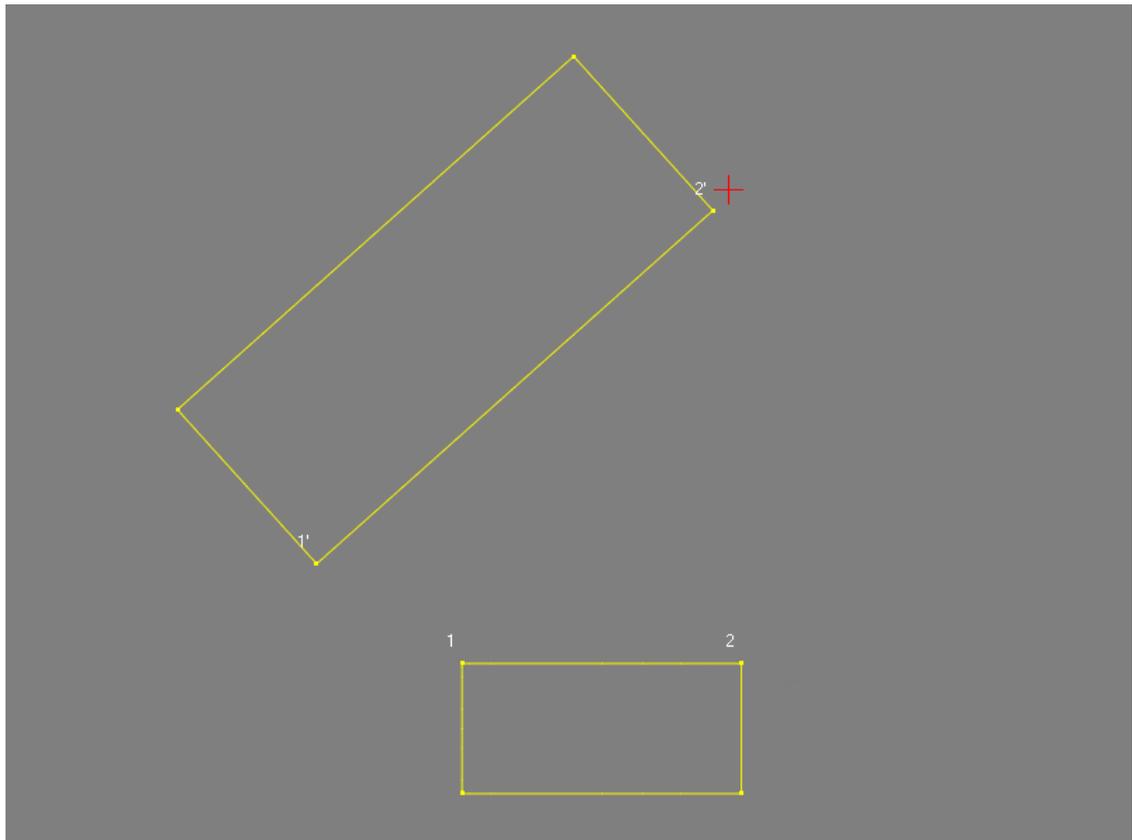


Fig. 112. Selecting vertices of the object, relative to which the transformation will be performed.

7. Press **Enter**.

The vector object, chosen for transformation, is rotated and moved on the plane as follows:

- Vertices 1 and 1' coincide on the plane;
- The vertex 2 is located on the straight line between vertices 1' and 2'.

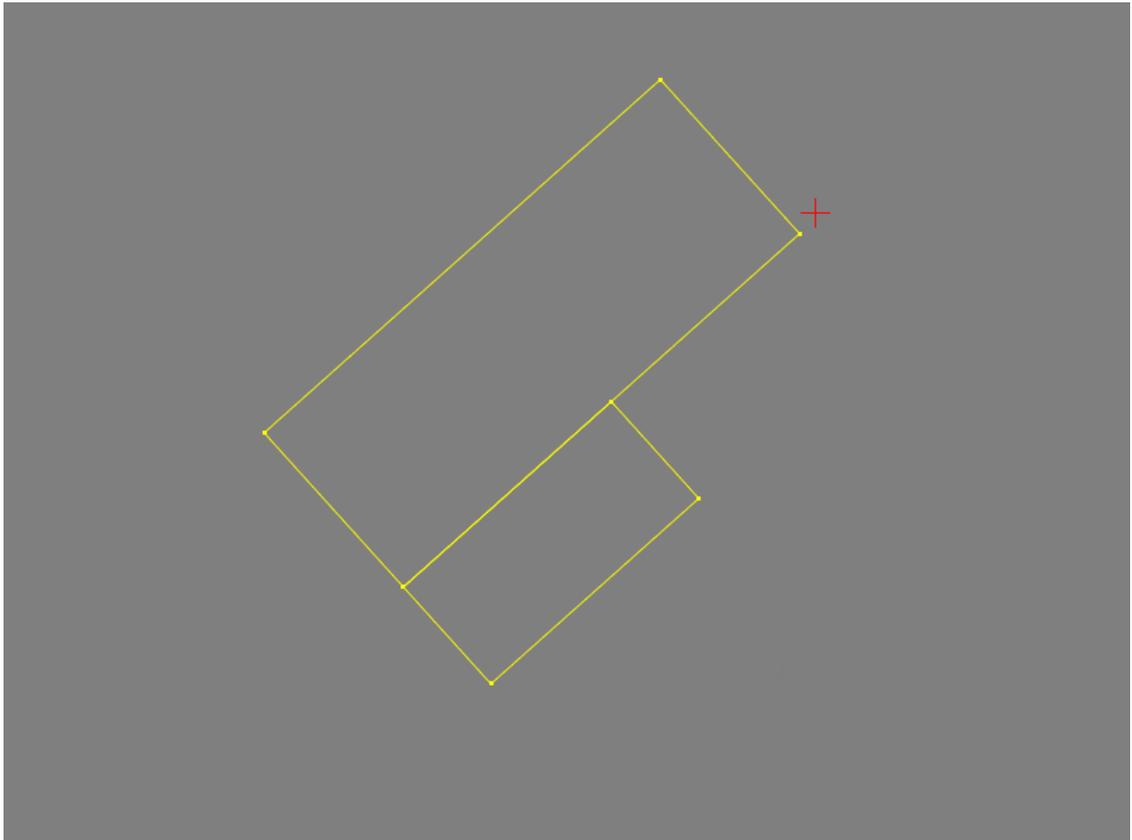


Fig. 113. Connected vector objects.

If the **Scale when align** function was also enabled, the vector object under transformation is scaled after connecting in the way that the length of the segment (distance) between vertices 1 and 2 would be equal to the length of the segment (distance) between vertices 1' and 2'.

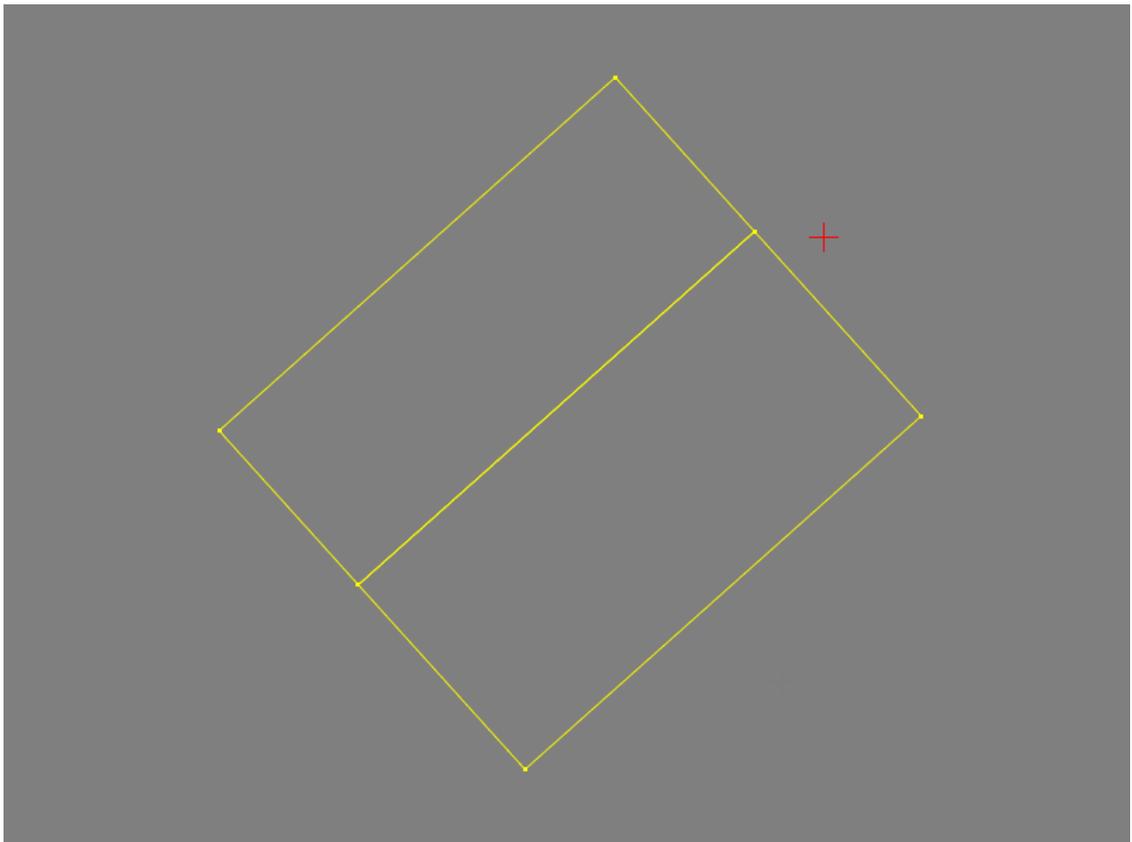


Fig. 114. Connected and scaled vector objects.

If the **Change Z of aligned object** checkbox was set in the **Vectors** tab of the **Settings** window (**Service > Settings > Vectors**), the height of the object under transformation after connection will coincide with the height of the object relative to which the transformation is performed.



The system allows for geometric transformation of several objects at once in alignment mode, for example in case of **roofs**. To do this, **select** several vector objects before choosing vertices.

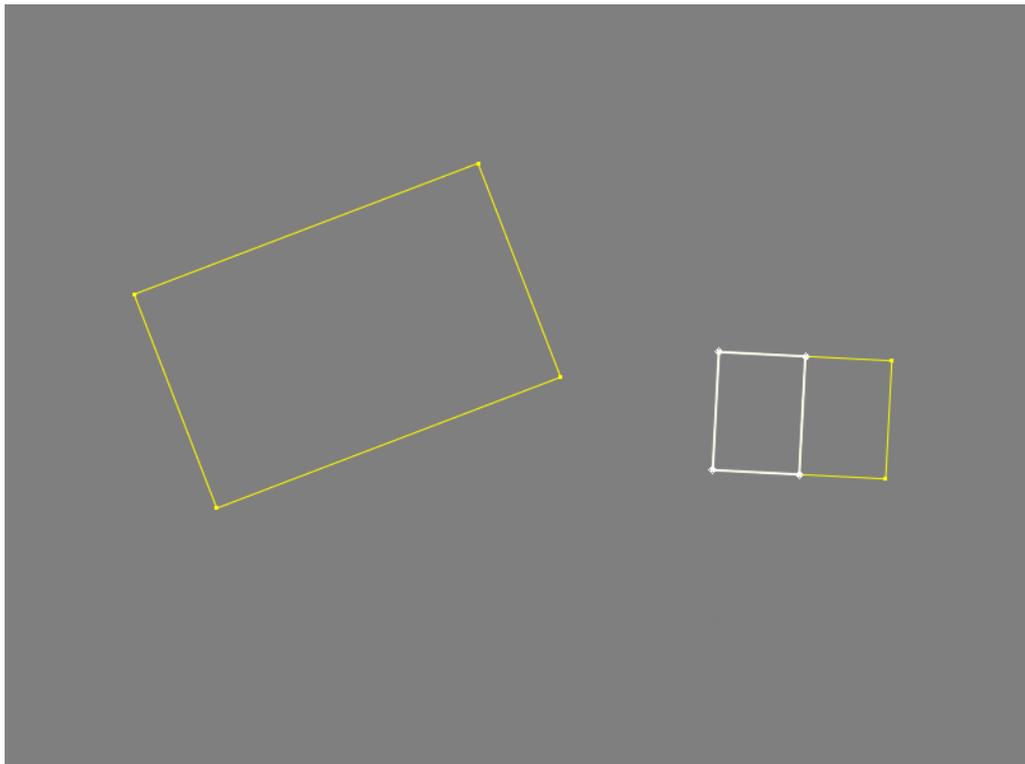


Fig. 115. A gable roof consisting of two vector objects (the left pitch is selected).

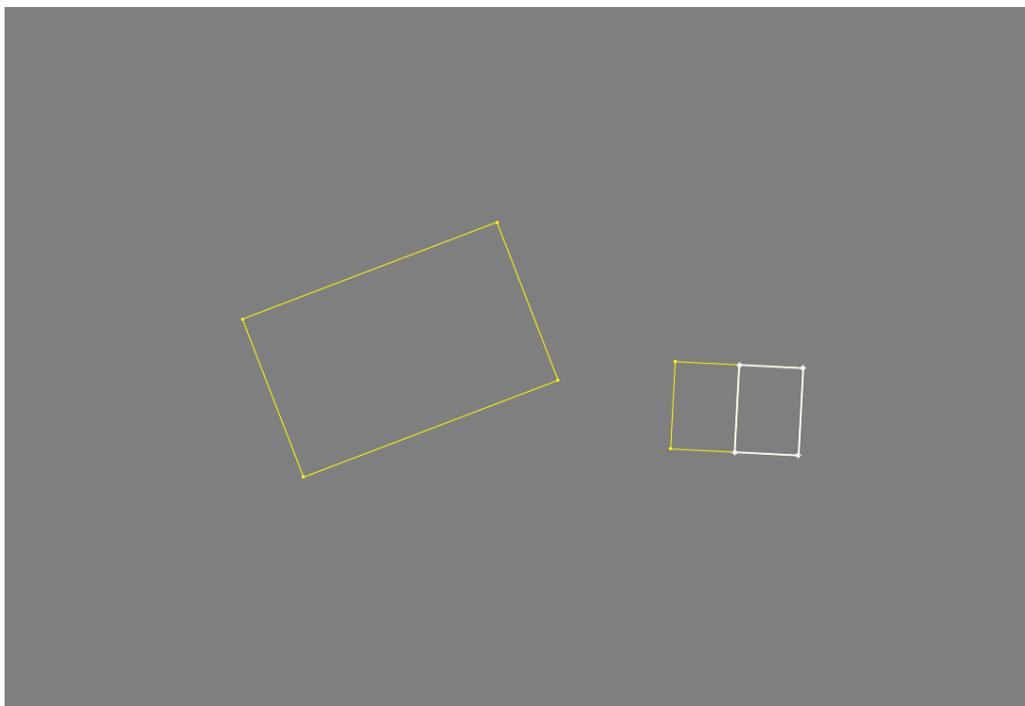


Fig. 116. A gable roof consisting of two vector objects (the right pitch is selected).

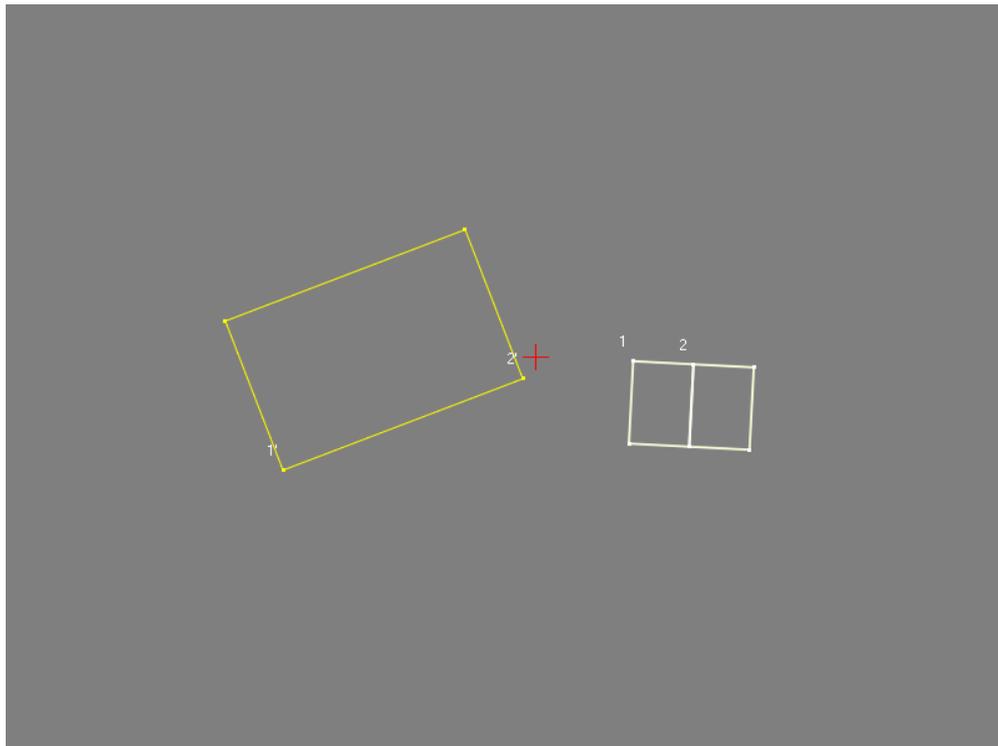


Fig. 117. Geometric transformation of a roof consisting of two polygons, in the alignment mode (Option 1). The scaling mode is enabled.

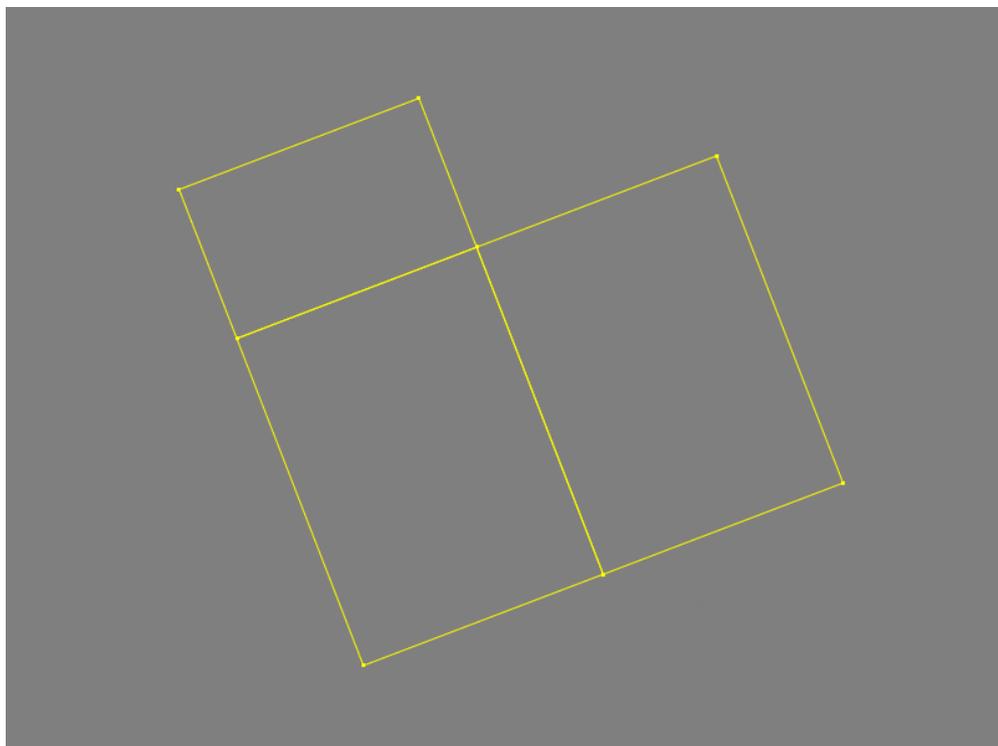


Fig. 118. Geometric transformation of a roof consisting of two polygons, in the alignment mode (Option 1). The scaling mode is enabled.

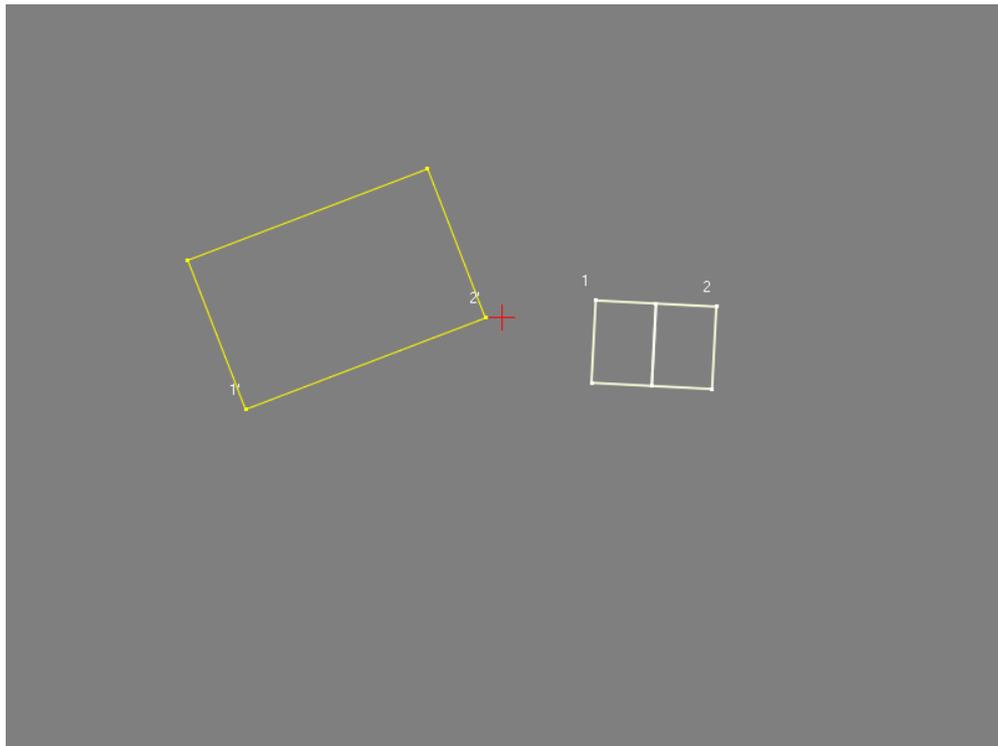


Fig. 119. Geometric transformation of a roof consisting of two polygons, in the alignment mode (Option 2). The scaling mode is enabled.

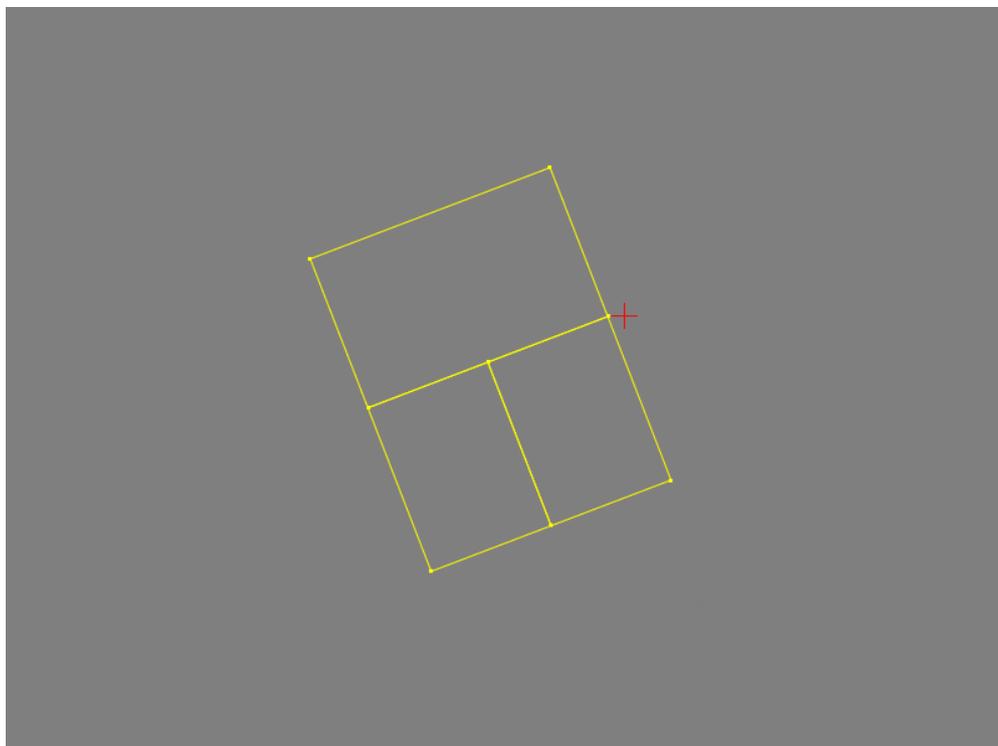


Fig. 120. Geometric transformation of a roof consisting of two polygons, in the alignment mode (Option 2). The scaling mode is enabled.

10.1.10. Projective transform

The system allows to perform projective transformation of vector objects.

Perform the following actions to do this:

1. Select **Vectors** > **Geometry** > **Projective transform**. The **Apply projective transform** window opens.

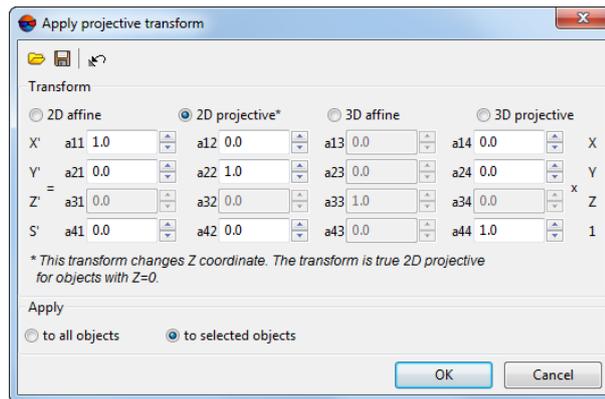


Fig. 121. Parameters of projective transform

2. Select one of the following transformation types:

- **2D affine** – the system performs transformation by rotation matrix and parallel displacement;
- **2D projective** – the system performs transformation by rotation matrix, parallel displacement and scaling;



This type of transformation leads to change Z coordinate!

- **3D affine** – the system performs transformation by rotation matrix and parallel displacement, including transformation by Z;
- **3D projective** – the system performs transformation by rotation matrix, parallel displacement and scaling;

3. Specify transformation coefficients depending from selected transformation type.



The  button allows to save coefficients to a CSV-file. The  button allows to load coefficients from a CSV-file.

To reset coefficients to default values click the  button.

4. [optional] In the **Apply** section choose objects to transform:
 - **All objects**;
 - **Selected objects**.
5. Click OK. After that all or selected vectors of active layer are transformed according to specified parameters.

10.2. Creation of additional vector objects

10.2.1. Adding intersection points

The system provides the ability to automatically add a vertex at the intersection of vector objects. Perform the following actions to do this:

1. Select **Vectors** › **Geometry** › **Add intersection points**. The **Layers selection** window opens.

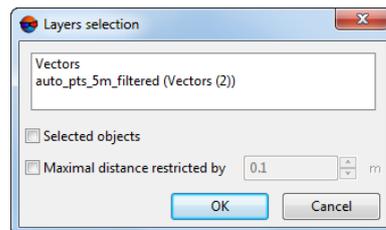


Fig. 122. Parameters of intersection points adding

2. Select in the list one or several layers where to search for vector objects intersections.
3. [optional] To apply the operation to selected objects only, set the **Selected objects** checkbox on.
4. [optional] To apply the operation only to objects, the distance between which is less than a predetermined value, set the **Maximal distance restricted by** checkbox on and specify distance between the objects.
5. Click OK. After that the system adds points at the intersection of polylines/polygons in accordance with the specified parameters.



Intersection points are added on both intersected objects.

10.2.2. Creating a symmetric objects

The system provides possibility to create symmetrical lengthy objects both linear and areal. The functions of the **Symmetric objects** menu are used to automate creation of conditionally symmetrical objects, such as roads, water bodies, etc.

Perform the following actions for creating a symmetric object (polyline):

1. Create the polyline (draw one side of an extended object, e.g., river bank).
2. Highlight the polyline for symmetrical reflection.
3. Place marker on another side of the object on image (for example, the opposite bank of the river).
4. Choose **Vectors** › **Geometry** › **Symmetric objects** › **Polyline**. As a result, a highlighted polyline is symmetrically copied to the marker position.



A correctness of the function to be performed depends on mutual position of marker and polyline selected.



Fig. 123. Steps for creation of the symmetric polylines

To create quasi-symmetric polygon object, perform the following:

1. Choose **Vectors** › **Geometry** › **Symmetric objects** › **Polygon**;
2. Start to draw a polygon;

-  A distance between the second parallel line and initial segments of the creating polygon is defined with a distance between the first and the second vertices of given polygon (see figures).
-  A position of the second parallel line regarding initial segments of the creating polygon (on the left or on the right respectively drawing direction) is defined with an angle between the first and the second segments of given polygon (see figures).



Fig. 124. Initial stage of creating “symmetric” polygon object. Selecting distance between parallel lines and their mutual position

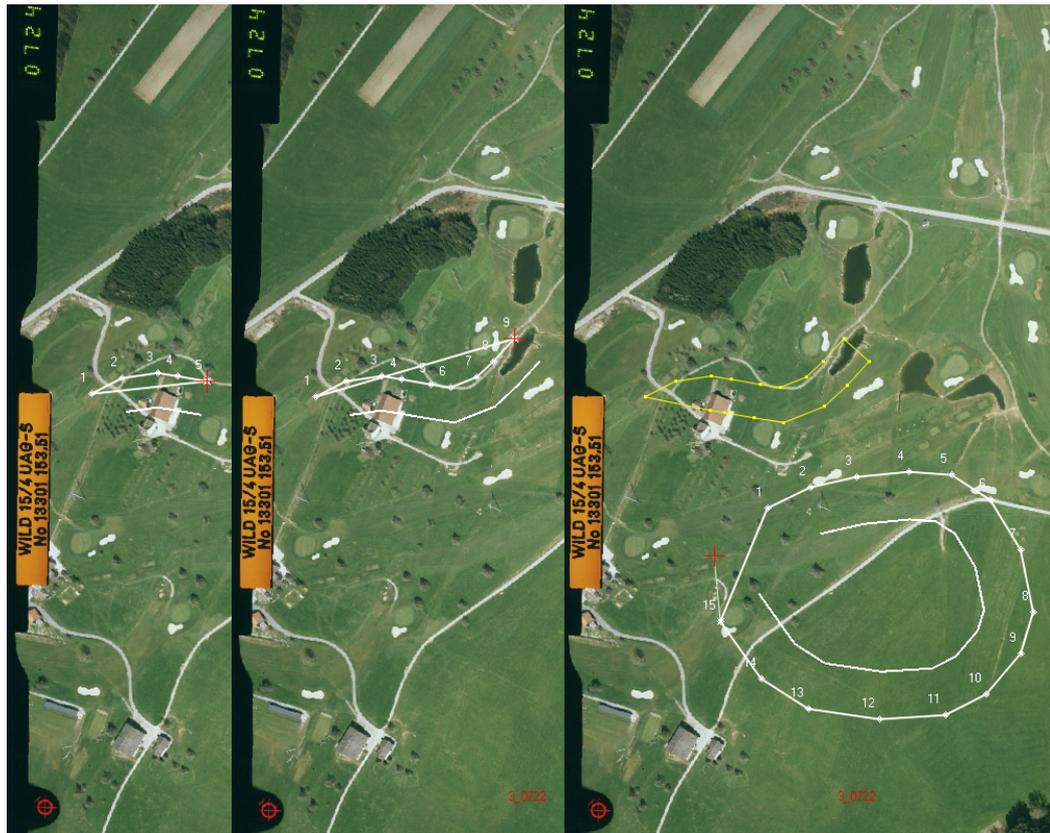


Fig. 125. Creating “symmetric” polygon objects

3. Complete polygon creation;
4. Turn off mode **Vectors** › **Geometry** › **Symmetric objects** › **Polygon**.



A correctness of the function to be performed depends on the shape of polygon created.



Given function does not allow to create ring-shaped polygons. To create ring-shaped polygons see “[Cut out area from polygon](#)” chapter.



A split segment of the ring-shaped polygon (see figures) is a segment which is placed between the first and ending vertices of creating polygon. The system allows to create quasi-symmetric ring-shaped polygons with a function as below.



Fig. 126. “Symmetric” polygon objects created with function **Vectors** › **Geometry** › **Symmetric objects** › **Polygon**

To create quasi-symmetric ring-shaped polygon, perform the following:

1. Load or create polygon;
2. Select polygon;
3. Place marker inside or out of polygon;
4. Choose **Vectors** › **Geometry** › **Symmetric objects** › **Polyline**. As a result a quasi-symmetric ring-shaped polygon is created. Its outer or inner boundary (depending on marker position – inside or out of polygon) corresponds to initial polygon boundary.



A correctness of the function to be performed depends on mutual position of the marker and selected polygon.



Given function does not allow to create ring-shaped polygons. To create ring-shaped polygons see “[Cut out area from polygon](#)” chapter.



A split segment of the ring-shaped polygon is a segment which is placed between the first and ending vertices of initial polygon. The system allows to create quasi-symmetric ring-shaped polygons with a function mentioned above as well.

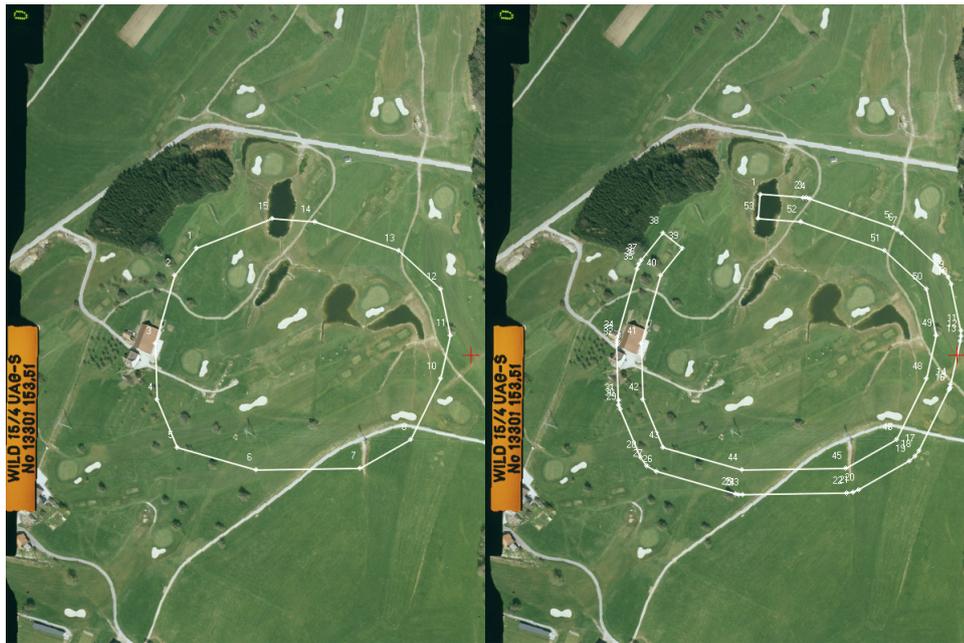


Fig. 127. Creating “symmetric” polygon objects

The system also allows to create mirror symmetry objects based both on polygons and polylines (resulted object is a polygon anyway). To create these objects perform the following:

1. Load or create polyline/polygon;
2. Select given object;
3. Turn on **point editing mode** in **Vectors** toolbar. Turn on **add to selection** mode in **Tools** toolbar.
4. Select any *two* vertices of the object like to set a *symmetry axis* of creating object;
5. Выберите **Vectors** › **Geometry** › **Symmetric objects** › **Mirror object**. As a result selected object will be transformed around specified symmetry axis into polygon object.



Shape of the resulted object depends on symmetry axis specified (i.e. mutual position of two selected vertices).



It is necessary to take into account that a segment placed between the initial and ending vertices of the polygon will be deleted (in some cases while specifying symmetry axis of the creating object it is recommended to select these vertices directly).

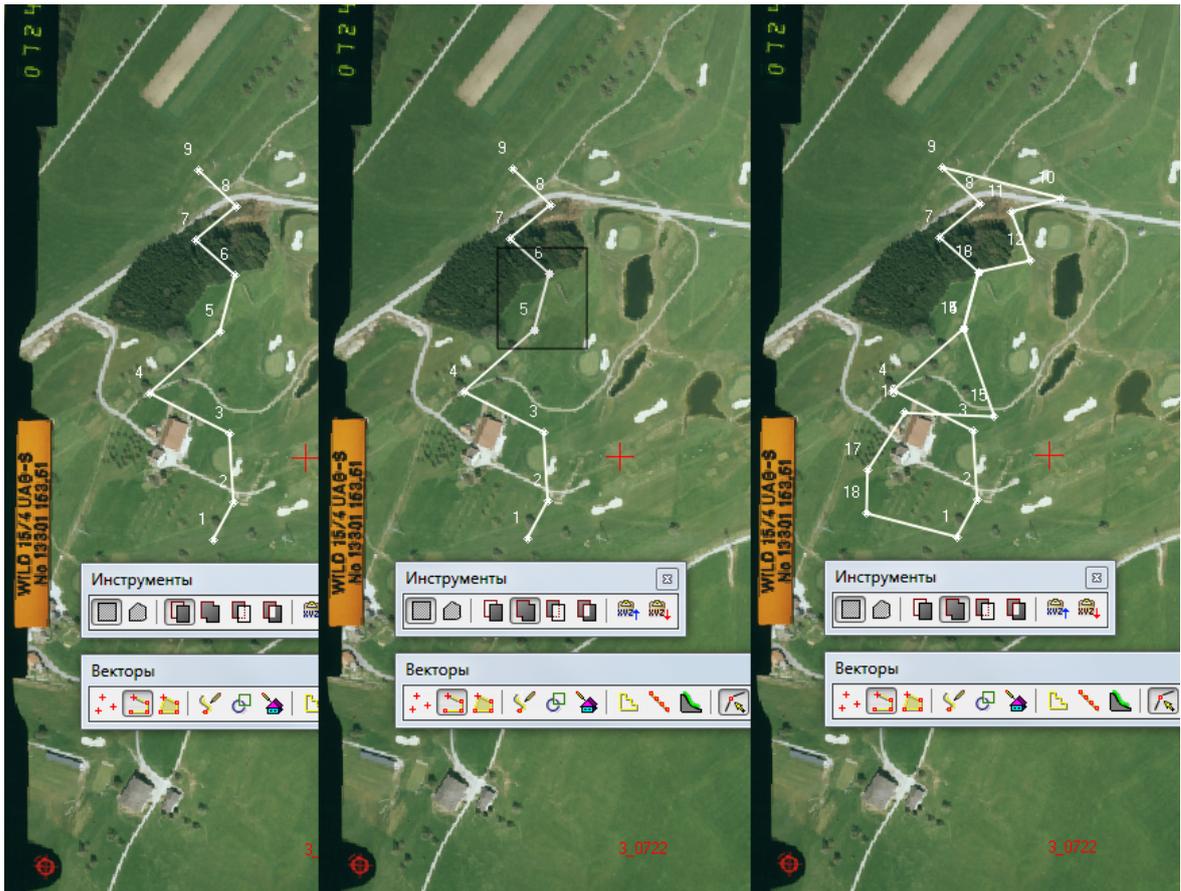


Fig. 128. Creating mirror symmetry polygon objects from polyline

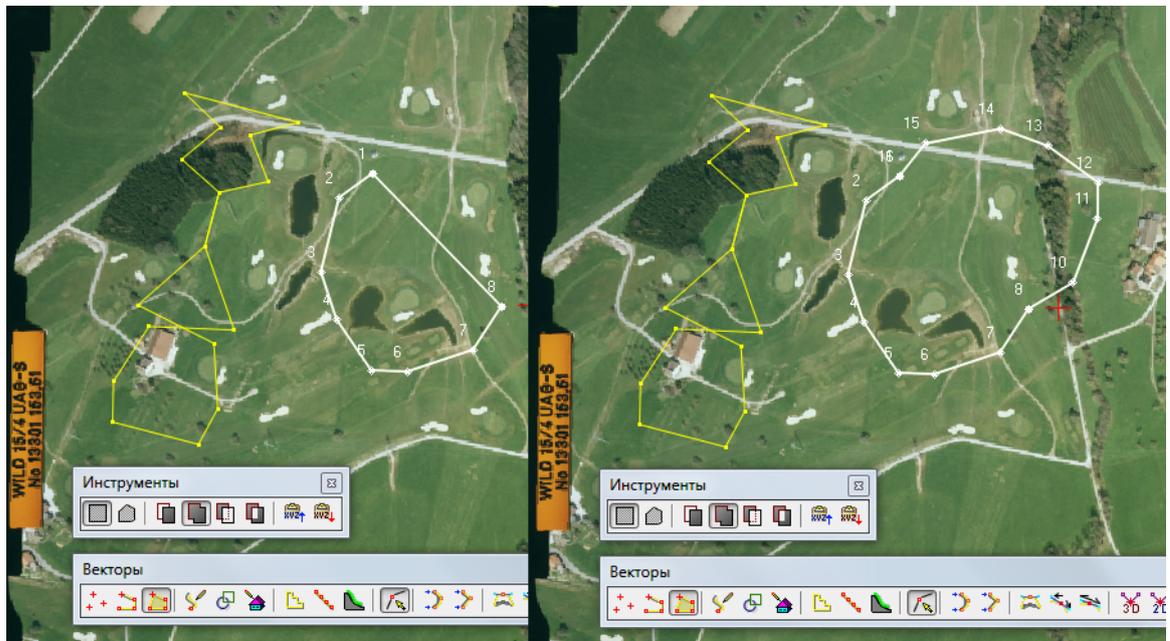


Fig. 129. Creating mirror symmetry polygon objects from polygon



Fig. 130. ПMirror symmetry polygon objects created with function **Vectors** > **Geometry** > **Symmetric objects** > **Mirror object**



Points selected while specifying a symmetry axis are duplicated as well.

10.2.3. Building buffer zone

Building of the buffer zone means to create a polyline/polygon parallel to selected line and situated at a predetermined distance from it.

To create buffer zone perform the following actions:

1. Select vector objects in 2D-window and choose **Vectors** > **Geometry** > **Buffer zone**. After that the window of buffer zone parameters is opened.



Buffer zone could be created both around linear, and areal objects.

If in 2D-window select only one type of objects, automatically set on the **Poly-lines/Polygons** checkbox depending on type of selected objects.

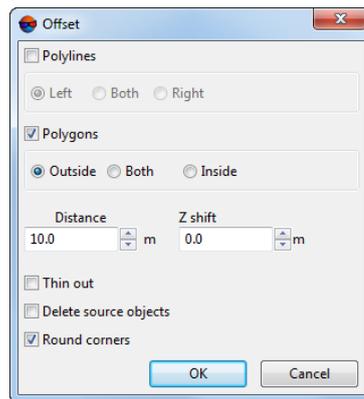


Fig. 131. Window of buffer zone parameters

2. [optional] Buffer zone could be created for objects of only one type, if needed. If selected both polylines and polygons, remove one of checkboxes.
3. Define location of buffer zone in regard to selected object.

For **polyline** the system provides the following ways of buffer zone location:

- **Left** – to the “left” of the active object in accordance with the numbering of its vertices;
- **Right** – to the “right” of the active object in accordance with the numbering of its vertices;
- **Both** – on both sides of the selected object.

For **Polygon** the system provides the following ways of buffer zone location:

- **Outside** – outside of source polygon;
- **Inside** – inside of source polygon;
- **Both** – on both sides of the selected object.

4. Depend parameters of buffer zone creation:

- **Distance** – a distance from selected object in meters (buffer zone width);
- **Z shift** – shift of buffer zone polyline vertices on specified height;
- **Thin out** – allows to thin out vertices of selected objects during buffer zone creation;
- **Delete source object** – allows to delete source object during buffer zone creation;

- **Round corners** – allows to round the corners of the outer edge of the buffer zone.

5. Click OK to create buffer zone for selected vector objects.

10.2.4. Geometric figures around objects vertices

The system allows to create circles with defined radius or squares with defined side length around vertices of linear objects.

Perform the following actions to do this:

1. **Select** a vector objects.
2. Choose **Vectors** › **Geometry** › **Objects around points**. The **Settings** window opens.

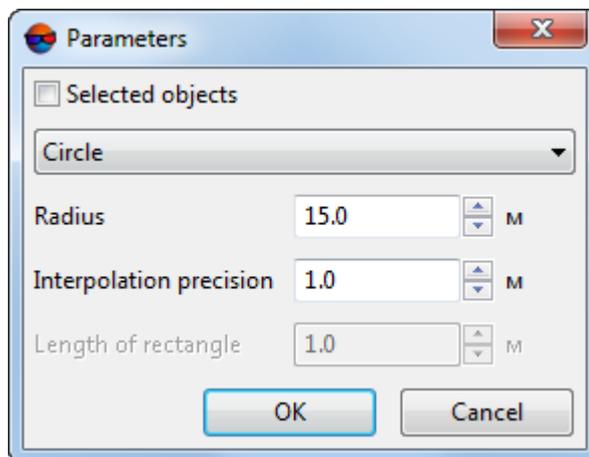


Fig. 132. Parameters of circles creation around objects vertices

3. Specify the following parameters:
 - [optional] **Selected objects** – geometric figures creates only around vertices of *selected* objects, otherwise – around vertices of all objects in current layer;
 - select a geometric figure type: **circle** or **rectangle**;
 - [optional] **Circle radius** – allows to specify circle radius in meters;
 - [optional] **Interpolation precision** – allows to specify maximal discrepancy between segments of polyline that replaces a circle and the circle itself;
 - [optional] **Length of rectangle** – allows to specify square's side length.
4. Click OK.

10.2.5. Creation of profiles through selected objects

The system provides the function of construction of perpendicular profiles through the group of linear vector objects. The resulting processing profiles (linear or point vector objects) attached to the selected codes in the classifier and are used to solve a variety of applied tasks.



This function is used, for example, to describe a dam “consisting” of two lines on both sides of its base, and two lines on its surface.

Perform the following actions to create profile:

1. **Selects** one object by double-click.
2. Do not unselect object and select the rest objects from the group.
3. Select **Vectors** › **Geometry** › **Vectors profiles**. The **Vectors profiles** window opens.

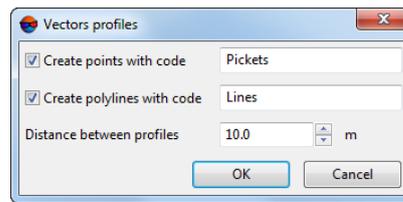


Fig. 133. Generation profile by vectors

4. In the **Distance between profiles** field specify a step of profile lines creation (in meters) to generate profiles approximately perpendicular to the selected vector object.
5. [optional] To save points of profiles intersection with selected objects as points codes, set the **Create points with code** checkbox on and specify the code name.
6. [optional] To save lines of profiles with selected objects as polylines codes, set the **Create polylines with code** checkbox on and specify the code name.



Points and polylines are assigned to classifier as codes of linear (L) and point (P) objects and are placed to the root layer of the classifier table.

7. Click OK. After that the system creates perpendicular profiles through selected vector objects.

10.2.6. Checking orthogonality of polygons corners

The system provides possibility to check orthogonality of polygons corners. A search of errors of deviation from the right angle between the vertices of the object or the distance between the leg and then the apex of the object.

In order to find these errors, perform the following actions:

1. [optional] To check orthogonality for selected objects, select them on the layer.
2. Check **Vectors** › **Geometry** › **Check orthogonality**. The **Check orthogonality** window opens.

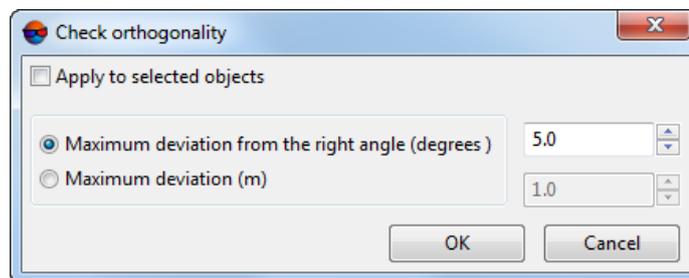


Fig. 134. Checking orthogonality of corners

3. [optional] In order to verify orthogonality of only selected objects, set the **Apply to selected** checkbox on.
4. Select one of the following ways of moving:

- **Maximum deviation from the right angle (degrees)** – maximum angle deviation between two sequence vertices, from 90 degrees.



Input maximum value of deviation on degrees.

- **Maximum deviation (m)** – maximum deviation of distance between vertex of triangle leg (that conditionally completed between two sequence vertices) and the next vertex of objects.



The right angle of triangle is between conditional leg vertex and the first vertex, from which is calculates the angle.



Input maximum value of deviation on meters.

5. Click OK. Information message with number of orthogonality errors is displayed. The *Orthogonality* layer creates. It contains vertices of object with deviations.

10.3. Vector objects projecting

10.3.1. Projecting onto relief

The system provides possibility to project vector objects on relief of active stereopair.

Perform the following actions to do this:

1. Open a stereopair and [load](#) a layer with vector objects.
2. Select **Vectors** > **Geometry** > **Project on stereomodel**. The **Parameters** window opens.

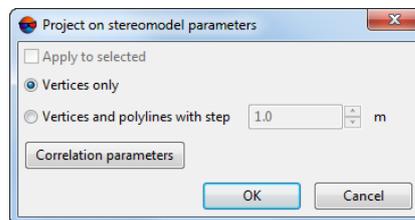


Fig. 135. Parameters of vectors projecting on relief

3. Define the following parameters:
 - **Apply to selected** – allows to project only selected vector objects;
 - **Vertices only** – allows to project only points or vertices of all/selected vector objects;
 - **Vertices and polylines with step** – allows to simultaneously break the linear objects into broken lines fragments at a predetermined step and project intermediate vertices.
4. [optional] To configure correlator's parameters click the **Correlation parameters** button (see the "[General system's parameters](#)" User Manual).
5. Click OK. All or selected vector objects are projected on relief of active stereopair.

10.3.2. Vectors projecting on a TIN

The system allows to project vector objects on TIN.

Perform the following actions to do this:

1. [Load](#) vector layer.
2. Load TIN layer, on which it is necessary to project vectors.

3. Select **Vectors** › **Geometry** › **Project on TIN**. The **Settings** window opens.

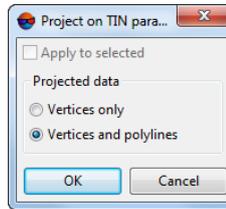


Fig. 136. Parameters of vectors projecting on a TIN

4. Select one the projecting modes:
 - **Vertices only** – only linear objects vertices and points are projected on a TIN;
 - **Vertices and lines** – simultaneously with vertices projection the system performs intersection linear objects by TIN edges and intermediate vertices projecting.
5. [optional] To apply the operation to selected objects only, set the **Apply to selected** checkbox on.
6. Click OK. After that vector objects elevations are replaced by elevations taken from TIN.

10.3.3. Vectors projecting on a DEM

The system allows to project vector objects on DEM (automatically assign elevations (Z) to points/vertices of vector objects from loaded DEM). Perform the following actions to do this:

1. **Load** or create vector layer;
2. Load DEM, on which it is necessary to project vector objects;
3. Select **Vectors** › **Geometry** › **Project on DEM**. The **Project objects on DEM** window opens:



Fig. 137. Parameters of vectors projecting on a DEM

4. [optional] Choose **Selected**, to move selected objects only, otherwise, select **All**.
5. In **Project on NULL cells** section select one of following options:
 - **Keep previous elevation** of vector object vertices;
 - **Interpolate using neighbours** (use DEM cells neighboring to null cells);
 - **Delete vertices** “falling” in null cells;
6. Click OK. After that vector objects elevations are replaced by Z coordinate taken from DEM.

10.4. Deleting point objects using a parameter

10.4.1. Delete points around linear objects

Automatic deleting points around linear objects allows to “filter” points used to the TIN creation. It is used if points, located near to linear objects, are conflict with these linear objects.

In order to delete points perform the following actions:

1. Select **Vectors** > **Geometry** > **Delete points around polylines**. The **Delete points around polylines** window opens.

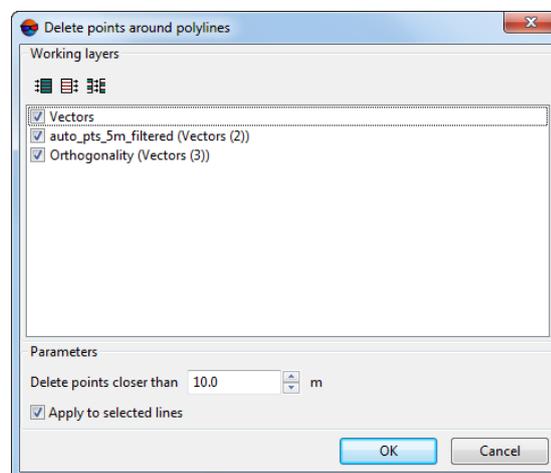


Fig. 138. Parameters of deleting points around linear objects

2. Select **Working layers**. By default the following layer are available:
 - if the TIN layer is active – base vector layers;
 - vector layer, if it is active;

- all vector layers in all other cases.
3. In the **Delete points closer than** field define maximal distance from linear object to a point in meters.
 4. [optional] Set the **Apply to selected lines** checkbox on, to delete points only around selected lines, otherwise – around all.
 5. Click OK. Processing is performed on all selected layers together, that is, for each linear object of each layer are removed point objects that are closer specified distance.

10.4.2. Deleting points inside polygons

The system provides possibility to deleting points inside polygons. Points and polygons could be located both in one layer and different.

In order to delete points inside polygons perform the following actions:

1. [Load](#) a vector layer with points.
2. [optional] If points and polygons are located in different layers, load a layer with polygons.
3. Choose **Vectors** › **Geometry** › **Delete points inside polygons**.

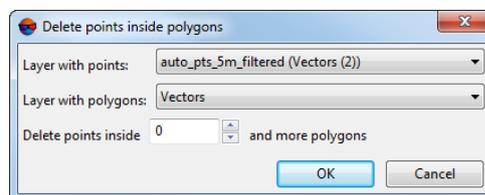


Fig. 139. Parameters of deleting points inside polygons

4. Select layer with points and layer with polygons in appropriate fields.
5. Specify minimal amount of polygons in the **Delete points inside .. and more polygons** field.
6. Click OK. After that all points located inside specified number of polygons will be deleted.

10.5. Transformation of objects coordinates

10.5.1. Swap of X and Y coordinates

The system allows to swap X and Y coordinates of vector objects. This function is used, for example, to correct wrongly specified coordinates during [objects import](#) and allows to re-calculate the coordinates from the left-handed coordinate system to the right-handed one and vice versa.

The **Vectors > Geometry > Swap X <-> Y** menu item is used for this. At that the coordinate system of project do not change.

10.5.2. Change objects coordinate system

The system provides opportunity of coordinates recalculation from one coordinate system to another for all vertices of current layer.

Perform the following actions to do this:

1. Select **Vectors > Geometry > Convert coordinate system**. The **Convert coordinate system** window opens.

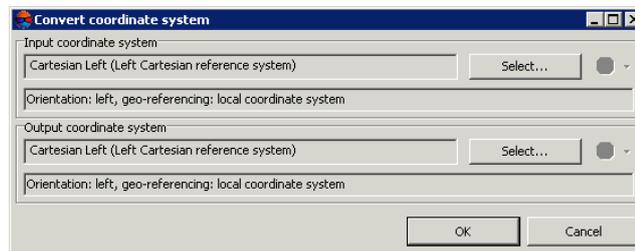


Fig. 140. The “Convert coordinate system” window

2. Click the **Select** button to specify initial coordinate system.

Coordinate system is specified using one of the following ways:

- **From DB** – from international or Russian coordinate system database (see “Coordinate systems databases” in the [“Creating project”](#) User Manual);
- **From file** – allows to select coordinate system from *.x-ref-system files, located *out* of active profile resources;
- **From resource** – from files with *.x-ref-system extension, located in active profile resources, for example, to select coordinate system from another project of active profile.



The system also allows to select coordinate system from a list of recently used coordinate systems.

- [optional] When choosing coordinate system from database the **Coordinate system database** opens, which contains the list of coordinate systems. To perform fast search for coordinate system in the list, input the whole coordinate system name or its part to the **Find** input field.

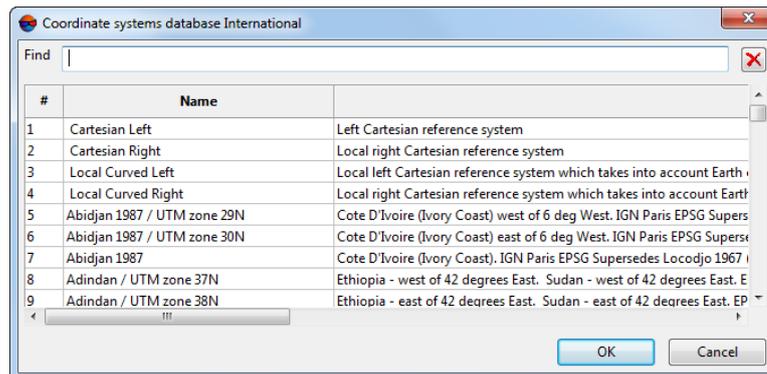
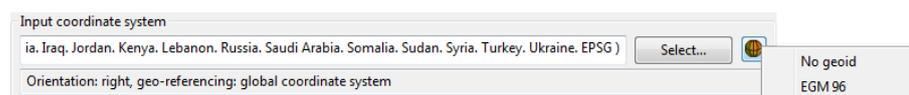


Fig. 141. Coordinate systems database window

- [optional] To choose geoid, click the  button. Select proper type of geoid usage:
 - **No geoid;**
 - **EGM 96.**



The system allows to use the EGM2008 geoid. See installation instruction in the User Manual. After installation the geoid is displayed in the list.



Output coordinate system is specified in the same way.



When working with the project by default as input and output coordinate system is used the project coordinate system. When working without project both coordinate systems should be specified by user.

10.6. Transformation of CSV file

The system allows to delete from CSV-file points out of defined boundaries. The **Cut CSV file** function is used for this with one of parameters:

- by rectangle edge;

- by selected polygons.

In order to cut CSV file by rectangle edges perform the following actions:

1. Choose **Vectors** › **Geometry** › **Cut CSV file by rectangle edges**. The **Settings** window opens.

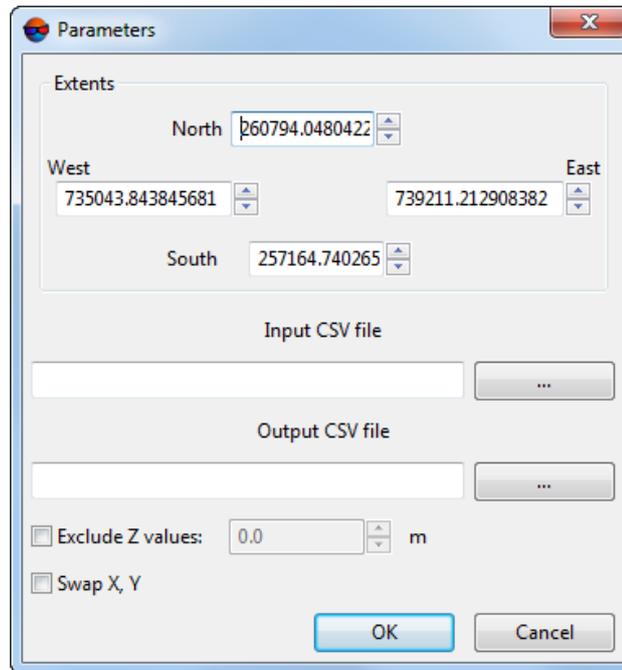


Fig. 142. Parameters of CSV file cutting by rectangle boundaries

2. Enter coordinates of rectangular area in project coordinate system into the **North**, **West**, **East** and **South** fields correspondingly.
3. In the **Output file** section click the **...** button, to select input CSV-file with *.csv or *.txt extension.
4. In the **Output CSV file** field specify output file name and path to save CSV-file.
5. [optional] In order not to consider points with specified elevation from CSV-file, set the **Exclude Z values** checkbox on and specify Z value in meters.
6. [optional] To swap X and Y coordinates in CSV-file, set the **Swap X Y** checkbox.
7. Click OK. After that the system creates CSV-file, containing information only about vector objects in frames of specified boundaries.

In order to cut CSV file by selected polygons perform the following actions:

1. To specify borders to cut CSV-file, [select](#) polygons.

2. Select **Vectors** › **Geometry** › **Cut CSV file by selected polygons**. The **Settings** window opens.

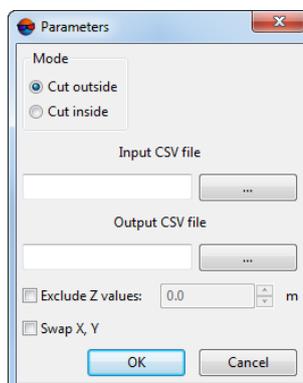


Fig. 143. Parameters of CSV file cutting by selected polygons

3. Choose the file **cutting** mode:
 - **Cut outside** – from CSV-file is deleting points located out of selected polygons;
 - **Cut inside** – from CSV-file is deleting points located inside of selected polygons;
4. In the **Output file** section click the **...** button, to select input CSV-file with *.csv or *.txt extension.
5. In the **Output CSV file** field specify output file name and path to save CSV-file.
6. [optional] In order not to consider points with specified elevation from CSV-file, set the **Exclude Z values** checkbox on and specify Z value in meters.
7. [optional] To swap X and Y coordinates in CSV-file, set the **Swap X Y** checkbox.
8. Click OK. After that the system creates CSV-file, containing information only about vector objects in frames of specified boundaries.

10.7. Elevation profile of a linear object

The system allows to create an elevation profile of a linear object (in the form of chart, whose vertices are the vertices of a polyline). To create an elevation profile select **one** linear object and choose **Vectors** › **Geometry** › **Elevation Profile**.

A window displaying elevation profile of the selected object opens. Z axis shows polyline's vertices elevations, and L axis shows horizontal distances between polyline vertices. On the right hand side of the **Elevation profile** window there is the slider, used to change profile scale by Z axis (the lower limit of the scroll bar is the chart minimum by Z axis).

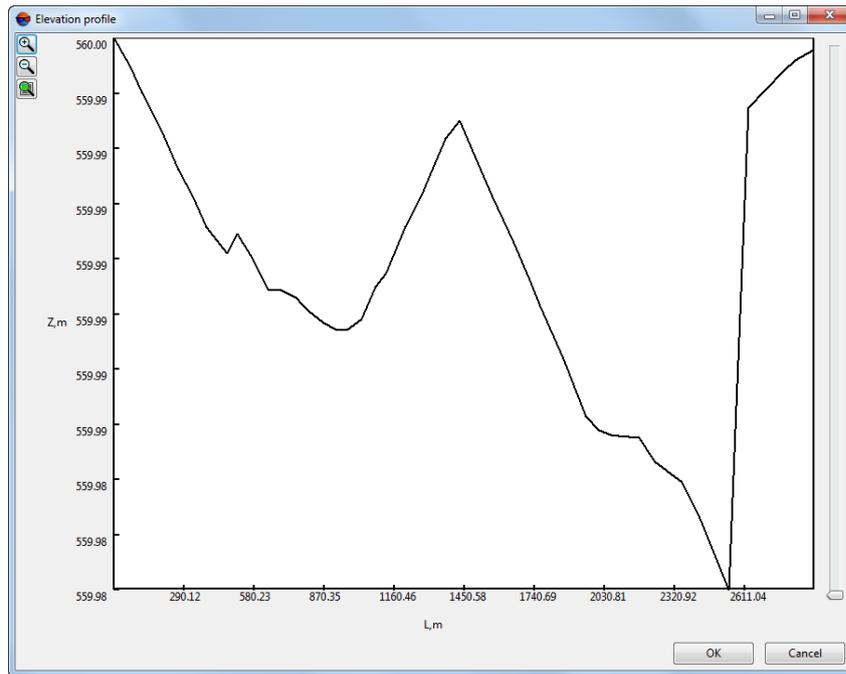


Fig. 144. Elevation profile window

Table 12. Functions provided by the “Elevation profile” window

Menu items	Functions
Zoom in	allows to zoom in by Z axis
Zoom out	allows to zoom out by Z axis
1:1 scale	allows to set 1:1 scale

11. Topological operations

11.1. About topology

The *topology* concept is one of the key terms used during quality assessment of created maps. Throughout this documentation, the *topology* is referred to as set of functions and operations, that define mutual location of vector objects and are used to create topologically correct vector data. The system provides the possibility of eliminating typical topological errors, such as:

- self-intersection of polylines/polygons;
- intersections of polylines/polygons without the formation of a common node (vertex at the intersection point);
- polygons overlapping;
- gaps or voids between polygons when a map is covered by polygons, such as woodlands polygons.



Topology – a branch of mathematics that studies the phenomenon of continuity in the most general form, in particular, the properties of space, which remain unchanged under continuous deformations, for example, the connectivity.

11.2. The “Topology” menu

For quick access to functions of vector objects editing, and also to change topological modes the system provides the **Topology** additional toolbar, which buttons partly duplicated in the **Topology** menu.

In order to show the **Topology**, toolbar, choose **Window > Toolbars > Topology**.

Table 13. Brief description of the “Topology” menu

Menu items	Function
Topological connectivity mode	allows to automatically set the objects vertices connected for objects created on a vector layer (see Section 11.3.1)
Joint points editing mode	allows to automatically set the objects vertices (located closer than a specified distance) connecting during to a vector object (see Section 11.3.2)
Close selected polylines (Shift+C)	allows to convert polyline to polygon (close polyline, see Section 11.4.1)
Unclose selected polygons (Shift+B)	allows to convert polygon to polyline (enclose polyline, see Section 11.4.2)
Merge two polylines (Shift+P)	allows to merge selected polylines into a single one by adding a segment between two last vertices of merging polylines (see Section 11.4.3)
Merge polygons (Shift+G)	allows to merge selected polygons that have overlap or common border (see Section 11.4.3)
Split polyline (Shift+X)	allows to split a polyline into two ones in the closest to marker vertex (see Section 11.4.4)
Split polygons/polylines (Shift+I)	allows to split several polygons and polylines using “cutting” polyline (see Section 11.4.4)
Delete segment (Shift+D)	allows to remove a segment connecting two vertices of polyline/polygon (see Section 11.6.3)
Delete selected vertices (Ctrl+D)	allows to delete vertices along with adjacent segments (see Section 11.6.5)
Cut out area from polygon	allows to cut an area out from a polygon, and to create a ring-shaped polygon (see Section 11.4.5)
Duplicate object	allows to create several copies of vector objects which are placed in the same layer (see Section 11.4.6)
Select nearest vertex (Shift+S)	allows to select polyline/polygon vertex closest to marker position (see Section 11.5)
Connect to point (Shift+V)	allows to connect creating line to existed one in a closest to marker vertex (see Section 11.5)

Menu items	Function
 Connect to line (Shift+L)	allows to connect creating line to existed one in arbitrary place of segment (см. Section 11.5)
Start from line (Shift+N)	allows to continue construction of the previously created polyline (see Section 11.5)
Object fragment	allows to edit a fragment of polyline/polygon (see Section 11.6).
Continue along polyline	allows to continue creating polyline along existed one to the marker position, to the nearest common vertex, or to selected vertex (see Section 11.7.1)
 Auto-close along polyline(Shift+M)	allows to draw a border of one polygon along a border of another one (see Section 11.7.2)
 Make vertices of selected objects linked	allows to link vertices of selected polylines/polygons (see Section 11.3.2)
 Make vertices of selected objects un-linked	allows to un-link vertices of selected polylines/polygons (see Section 11.3.2)
 Topology verifying	allows to check vectors topology for errors and correct topology errors (see Section 11.8.1)
Subtract one polygon layer from another	allows to subtract inactive polygon layer from the active one (see Section 11.9.2)
Intersect one polygon layer with another	allows to avoid waste space between the layers (see Section 11.9.1)
Find polygons relative position errors	allows to find and analyse errors of polygons relative position (see Section 11.8.2)
Find polygons with one coinciding point	allows to find polygons having common points. Search results are displayed on a new layer as points. (see Section 11.8.3)

11.3. Vertices connection

11.3.1. Topological connectivity mode

The system provides the ability to set some vertices connected for created vector objects. The **Topological connectivity mode** is used for that.



Such need arises, for example, in the case of using the **Vectors** › **Topology** › **Continue along polyline** › **To selected vertex** operation.

To make vertices of created vector objects connected, set **Vectors** › **Topology** › **Topological connectivity mode** checkbox or click the  button of the **Topology** toolbar.

To disable mode of creation connected vertices set the **Vectors** › **Topology** › **Topological connectivity mode** checkbox off or click the  button of the **Topology** toolbar. Continue create vectors in an ordinary mode.



The **Topological connectivity mode** only affects new vertices of created vector objects.

To make vertices of object, created in ordinary mode, perform the following:

1. Select objects with vertices to make them connected.
2. Choose **Vectors › Topology › Make vertices of selected objects linked** or click the  button of the **Topology** toolbar.

11.3.2. Joint points editing mode

The system provides the ability to set some vertices connected, that is used for co-editing of two vector objects. The *Joint points editing mode* is used for that.



Such need arises, for example, in the case of complex roofs editing.

Connected vertices are called the vertices, which are considered a common vertex and are edited simultaneously.

To make connected objects vertices located on specified distance, perform the following actions:

1. Choose **Vectors › Topology › Joint points editing mode** or click the  button of the **Topology** toolbar.
2. [optional] Distance, closer which vertices are considered one common vertex and edited simultaneously, is set in the general settings of the system. To change distance perform the following:
 1. Choose **Service › Settings (Ctrl+Alt+P)**. The **Settings** window opens.
 2. On the **Vectors** tab set the **Points joint swath for topological operations** – minimal distance between vertices those are not consider as common vertices.
3. Connect creating polyline to existed one (see [Section 11.5](#)).
4. Click OK. After that all vertices located at a distance less than the predetermined, are considered connected.

In order to make connected selected objects vertices, perform the following actions:

1. **Select** vector objects in 2D-window.
2. Choose **Vectors › Topology › Make vertices of selected objects linked** or click the  button of the **Topology** toolbar. After that the vertices of selected objects become linked.

To edit connected vertices, perform the following actions:

1. Choose **Vectors › Topology › Joint points editing mode** or click the  button of the **Topology** toolbar.
2. Choose **Edit › Point editing mode** or click the  button of the **Vectors** toolbar.
3. Select one of connected vertices.
4. Press and hold the **Ctrl** key, and press mouse button to move connected vertices.
5. [optional] To remove connected vertices, select one of them and press **Delete**. Connected vertices are deleting together.

In order to unlink selected objects vertices, perform the following actions:

- set the **Vectors › Topology › Joint points editing mode** off or click the  button of the **Topology** toolbar. Objects vertices become unlinked and could be edited separately from each other.
- define which linked vertices should become unlinked:
 1. **Select** a vector object or several objects in 2D-window;
 2. Choose **Vectors › Topology › Make vertices of selected objects un-linked** or click the  button of the **Topology** toolbar. After that the vertices of selected objects become un-linked.

11.4. Object editing

11.4.1. Polylines closing

The system allows to convert polylines to polygons – to close polylines.

In order to close single or multiple polylines, perform the following actions:

1. **Select** polylines in 2D-window.
2. Choose **Vectors › Topology › Close selected polylines (Shift+C)** or click the  button of the **Topology** toolbar. After that selected polylines become closed and converted to polygons.

In order to close a polyline in classifier layer, perform the following actions:

1. **Select** polyline in 2D-window.
2. In the **Classifier** window select a code with P type – polygon.



To check vertices for duplicates in first or end points, in the **Settings** window on the **Vectors** tab set the **Delete/add duplicate vertices while objects closing/unclosing** checkbox
As a result:

- when closing polylines the system checks for duplicates of the first and last vertices, the last vertex is deleted if necessary;
- when closing polygons the first vertex will be added to the end of polyline.

3. Choose **Vectors** › **Topology** › **Close selected polylines (Shift+C)** or click the  button of the **Topology** toolbar. After that the polyline becomes closed and converted to polygon (see [Section 6.7](#)). Selected classifier code is assigned to this polyline.

11.4.2. Polygons unclosing

In order to unclose single or multiple polygons, perform the following actions:

1. **Select** polygons in 2D-window.
2. [optional] When work in layer with **classifier** in the **Classifier** window choose code with the L type (polyline).



To check vertices for duplicates in first or end points, in the **Settings** window on the **Vectors** tab set the **Delete/add duplicate vertices while objects closing/unclosing** checkbox.
As a result:

- when closing polylines the system checks for duplicates of the first and last vertices, the last vertex is deleted if necessary;
- when closing polygons the first vertex will be added to the end of polyline.

3. Choose **Vectors** › **Topology** › **Unclose selected polygons (Shift+B)** or click the  button of the **Topology** toolbar. After that a polygon is converted to a polyline and polygon's segment connecting the first and last vertices. When work with classifier, selected code assign to a new object.

11.4.3. Merging of polylines/polygons

The system provides possibility to merge polylines/polygons, spaced apart from each other or having a common border or overlaps.

To merge two polylines perform the following actions:

1. **Select** two polylines in 2D-window.



The system provides possibility to merge only *two* polylines.

2. [optional] When work with classifier, select in the classifier window code that should be assigned to a new object (see [Section 6](#)).
3. Choose **Vectors › Topology › Merge two polylines (Shift+P)** or click the  button of the **Topology** toolbar.

Selected polylines merge in one, for this a segment adds between two edge vertices of merging polylines.

To merge two or more polygons that share a border or overlap with each other, perform the following actions:

1. **Select** in 2D-window polygons to be merged.
2. [optional] When work with classifier, select in the classifier window code that should be assigned to a new object (see [Section 6](#)).
3. Choose **Vectors › Topology › Merge polygons (Shift+G)** or click the  button of the **Topology** toolbar.

Selected polygons merging to one with the following way: intersection points became to a vertices of a new polygon, overlapped segments deleting after intersection points.



If the polygons have attributes with the same names and mandatory attributes, new polygon is assigned a value of an attribute whose type is the same type as the mandatory attribute.



If merging polygons have attributes with the same names, but does not have mandatory attributes, new polygon is assigned a value of an attribute of the polygon, which attribute type is *text*. Otherwise, new polygon is assigned a value of an attribute of the polygon, which attribute type is – *float*, otherwise – *integer*.

11.4.4. Splitting polylines/polygons

The system provides the following splitting operations of vector objects of active vector layer:

- cutting polyline into two in an arbitrary vertex;
- cutting multiple polygons/polylines of a layer simultaneously using “cutting” polyline.
- cutting polygon located in a layer with classifier using “cutting” polyline.

To split polyline into two ones, perform the following actions:

1. **Select** polyline in 2D-window.
2. Specify by marker an arbitrary vertex of polyline segment.

3. Choose **Vectors › Topology › Split polyline (Shift+X)** or click the  button of the **Topology** toolbar. After the splitting one polyline is divided into two ones in the vertex closest to marker.

In order to cut several polylines/polygons of the same layer at once using “cutting” polyline, perform the following actions:

1. Create the “cutting” polyline, that intersects objects to be cut.



In order to cut a polyline in several places, cross the polyline as many times as needed.



In order to cut a polygon, cross this polygon through *two* points, otherwise the operation will fail.

2. Select the “cutting polyline”.



The system allows to change attribute values of objects, involving to cutting or merging polylines. To do this in the **Settings** window on **Vectors** tab set the **Set attributes to default value while objects merging/splitting** checkbox on. Source attributes change with the following values: *text* – blank string, *float* – 0.0, *integer* – 0. If an object has obligatory attribute with the same name, its value is used as default value.

3. Choose **Vectors › Topology › Split polygons/polylines (Shift+I)** or click the  button of the **Topology** toolbar.

After that the “cutting” polyline cuts crossed vector objects by several objects of the same type. In points of “cutting” polyline crossing the system creates new segments. After completing the operation the “cutting” polyline is removed.

To cut a polygon using “cutting” polyline in a layer with classifier, perform the following actions:

1. Create “cutting” polyline which intersects a polygon.



In order to cut a polygon, “cutting” polyline should intersect the polygon in *two* points only, otherwise the operation will fail.

2. Select “cutting polyline”.

3. Choose **Vectors › Topology › Split polygons/polylines (Shift+I)** or click the  button of the **Topology** toolbar.

As a result “cutting” polyline splits the polygon at two ones, that have the same code as the original polygon. Once the operation is completed, the polyline is removed.

11.4.5. Cut out area from polygon

The system provides opportunity to generate a ring-shaped polygons. To create such a polygon, do the following:

1. **Create** two polygons, which will be used as internal and external borders of the final polygon.



Both polygons, internal and external should be in the same layer.

2. Turn the **points editing mode** on in the **Vectors** toolbar. Turn the **add to selection** mode on in the **Tools** toolbar.
3. Select one vertex both on internal and external polygon.
4. Choose **Vectors** > **Topology** > **Cut out area from polygon**. An area corresponding to internal polygon is subtracted from the main polygon, that allows to create a resulting ring-shaped polygon. The **Question** window opens.

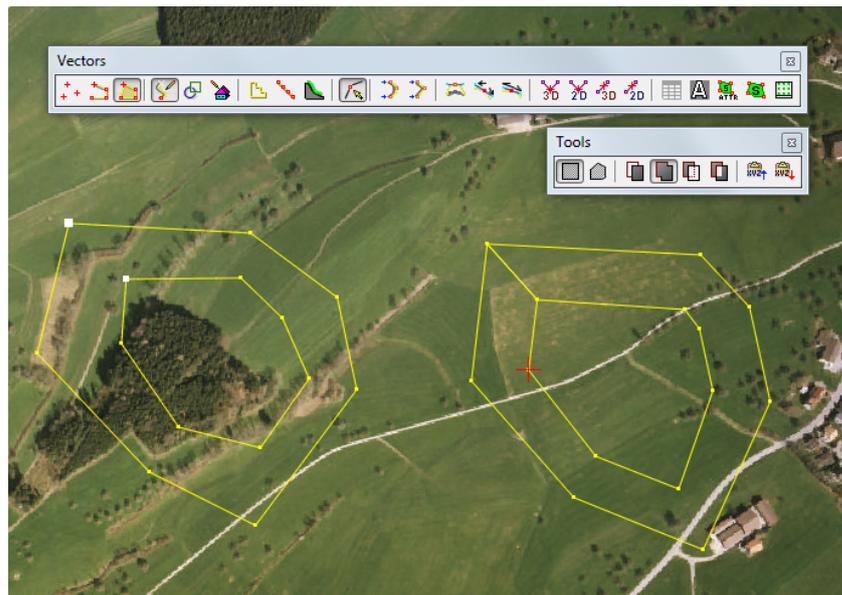


Fig. 145. Cut out area from polygon



Additional segment that is necessary for the system to recognise the resulting polygon as ring-shaped, is located between two vertices, selected prior to subtracting an area from initial polygon.

5.

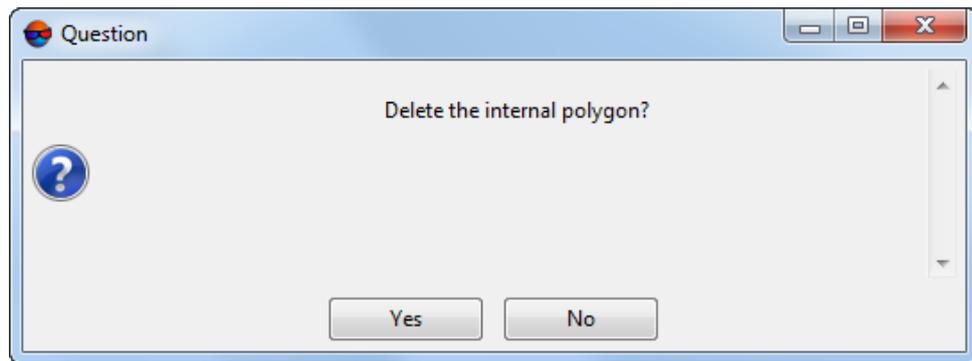


Fig. 146. The “Question” window

- Click **Yes**, to delete the internal polygon.
- Click **No**, to leave the internal polygon as a separate vector object.



Fig. 147. The resulting ring-shaped polygon and the internal polygon as a separate vector object



If the location of an additional segment between the particular selected vertices is not significant, the system allows us to subtract an area from the polygon by a simplified method.

To do this, leaving out paragraphs 2 and 3 select both created polygons and choose **Vectors > Topology > Cut out area from polygon**. Hence, the system will automatically determine the location of the additional segment.

11.4.6. Duplication of vector objects

The system allows to create several copies of vector objects which are placed in the same layer. To do it perform the following:

1. Turn on **point editing mode** in **Vectors** toolbar.

2. Select *one* vertex of the vector object.
3. Move marker in arbitrary distance to set a position of object copies regarding a parent object (i.e. a vertex of the first object copy corresponding to the selected vertex of the parent object will be placed in marker position, next object copy will be shifted at the same distance at the same direction etc.).

If marker is not moved a position of object copies will be identical to position of the parent object.



The system allows to [select](#) identical objects *one by one*. With double click of mouse or clicking **S** key **Rectangle selection mode** helps to select all the objects.

4. Choose **Vectors** › **Topology** › **Duplicate object**. The **Duplicate object** window opens.

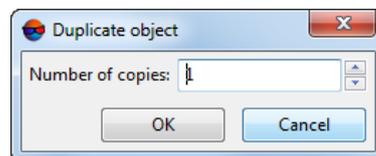


Fig. 148. The “Duplicate object” window

5. Set **Number of copies** and click OK. In the current layer a specified number of object copies is created. These copies are placed in accordance with marker position or identically to the parent object if the marker was not moved.

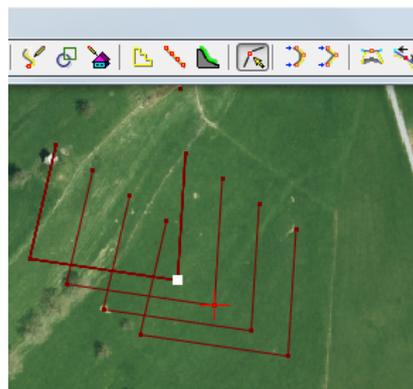


Fig. 149. Object duplication

6. Turn off Point editing mode.



Copying **several** vector objects into existing or new layer is described in “[Vector object copying](#)” chapter.

11.4.7. Filling the attributes after topological operations

Polygons attributes after [topological operations](#) assign to all objects involving in the operation. Thus attributes could be both filling with default values and left unchanged.

The **Set attributes to default value while objects merging/splitting** checkbox in the **Settings** window on **Vectors** tab is use to fill attributes with default values (**Service** › **Settings** menu item (**Ctrl+Alt+P**)).

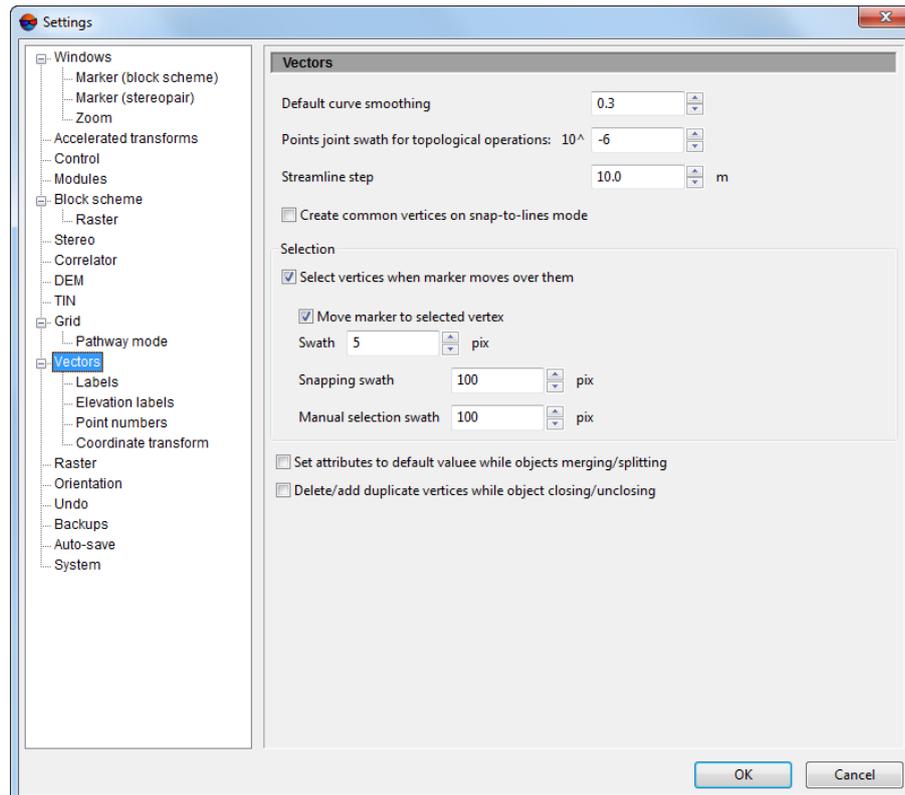


Fig. 150. Vector displaying parameters

Source attributes change with the following values: *text* – blank string, *float* – 0.0, *integer* – 0. If an object has [obligatory attribute](#) with the same name, its value is used as default value.

Also the system provides possibility to automatic recalculate square of polygons after editing. To do this use the **Vectors** › **Attributes** › **Automatic filling layer's attributes** menu item and the  button of the **Vectors** toolbar.



To perform automatic value recalculation the attribute should has the *float* type.

11.5. Connecting to an object

The system provides possibility to connect to creating vector object to other vector objects.

To connect creating vector object to existing one, execute the following actions:

1. Start to create a vector object (see [Section 5.3](#)).
2. Place marker to vicinity of the existing object vertex.
3. Choose **Vectors › Topology › Select nearest vertex (Shift+S)**. The closest to marker vertex is selected.
4. Press **Insert** to create common vertex.
5. Add more vertices to continue creation of vector object.

In order to select nearest vertex of vector object, place marker in vicinity of the object's vertex and select **Vectors › Topology › Select nearest vertex (Shift+S)**. The closest to marker vertex is selected.

To connect creating polyline to existing one, place marker in vicinity of vertex of existing polyline and select **Vectors › Topology › Connect to point (Shift+V)** or click the  button of the **Topology** toolbar. After that both polylines will have common vertex, which editing leads to change of both polylines at the same time (see [Section 8.4.1](#)).

To connect creating polyline to existing one in arbitrary vertex of polyline segment, place marker in vicinity of vertex of existing polyline and select **Vectors › Topology › Connect to point (Shift+V)** or click the  button of the **Topology** toolbar. After that a new vertex is created at the intersection of the continuation of the polyline created and existing polyline segment. Vertex editing results in change of both polylines at the same time (see [Section 8.4.1](#)).

In order to continue of created polyline, select this polyline in 2D-window and select **Vectors › Topology › Start from line (Shift+N)**. After that both polylines will have common vertex, which editing leads to change of both polylines at the same time.

11.6. Editing of object fragment

11.6.1. Adding/deleting object fragment

The system allows to edit polyline/polygon fragment (see fragment definition in [Section 2.1](#)).

To add vertices to existing polyline/polygon fragment, perform the following actions:

1. **Select** polyline/polygon in 2D-window.
2. Place marker in vicinity of vertex of polyline/polygon fragment beginning, to which it is necessary to add new vertices.
3. Choose **Vectors › Topology › Object fragment › Select start point of fragment (Alt+S)**.
4. Add more vertices to continue creation of polyline/polygon fragment.
5. Press **Esc** to complete polyline/polygon fragment editing.

Perform the following actions to delete a fragment of polyline/polygon:

1. **Select** polyline/polygon.
2. Place marker in vicinity of fragment starting vertex and choose **Vectors › Topology › Object fragment › Select start point of fragment (Alt+S)**.
3. Place marker in vicinity of fragment end vertex and choose **Vectors › Topology › Select nearest vertex (Shift+S)**.
4. Choose **Vectors › Topology › Object fragment › Delete line fragment (Alt+D)**. After that a polyline/polygon fragment is deleted.

11.6.2. Fragment replacing

Perform the following actions to replace a fragment of existing polyline/polygon:

1. Place marker to vicinity of base polyline/polygon vertex, that will be used as the start vertex of fragment to be replaced.
2. Create a new polyline or polygon to replace base fragment. In the process of creating specify direction of created polyline/polygon, which coincides with the direction of the fragment to be replaced.
3. The last vertex of the new polyline enter to vicinity of vertex of the base polyline/polygon, which is the end of the new fragment.
4. Choose **Vectors › Topology › Object fragment › Replace fragment (Shift+R)** or click the  button of the **Topology** toolbar. As a result, a new fragment became a part of base line, all old vertices of base line is deleting.

11.6.3. Segment deleting

Perform the following actions to delete a segment of polyline/polygon:

1. **Select** vector object in 2D-window.

2. Place marker in the vicinity of the vectorization object.
3. [optional] To delete segment from polygon in a layer with classifier, select in the classifier window the L code type (polyline) (see [Section 6](#)).
4. Choose **Vectors › Topology › Delete segment (Shift+D)** or click the  button of the **Topology** toolbar. Selected segment is deleted and selected polyline is divided to a two separate polylines. When segment is deleted from polygon, it convert to a polyline.



If marker is located in the vicinity of the last polyline segment, after deleting remains a polyline and a separate vertex.



When segment is deleted from polygon, it converts to a polyline. In this case when working with classifier also changes the object code.

11.6.4. Reverting vertices order

To change vertices order in polylines or polygons select **Vectors › Topology › Object fragment › Reverse vertices order in line objects**. As a result vertices order of selected polyline/polygon is inverted.



This operation is necessary during replacing a polyline/polygon fragment to define necessary area.

11.6.5. Removing vertices together with adjacent segments

To remove vertex or multiple vertices together with the adjacent segments perform the following actions:

1. Turn the [points editing mode](#) on.
2. Select single or multiple vertices of a polyline or polygon.
3. Choose **Vectors › Topology › Delete selected vertices** or press **Ctrl+D**. Selected vertices are removed together with adjacent segments, and edited polyline is divided into several separate polylines. When vertices with adjacent segments are removed from a polygon, it is converted into a polyline.

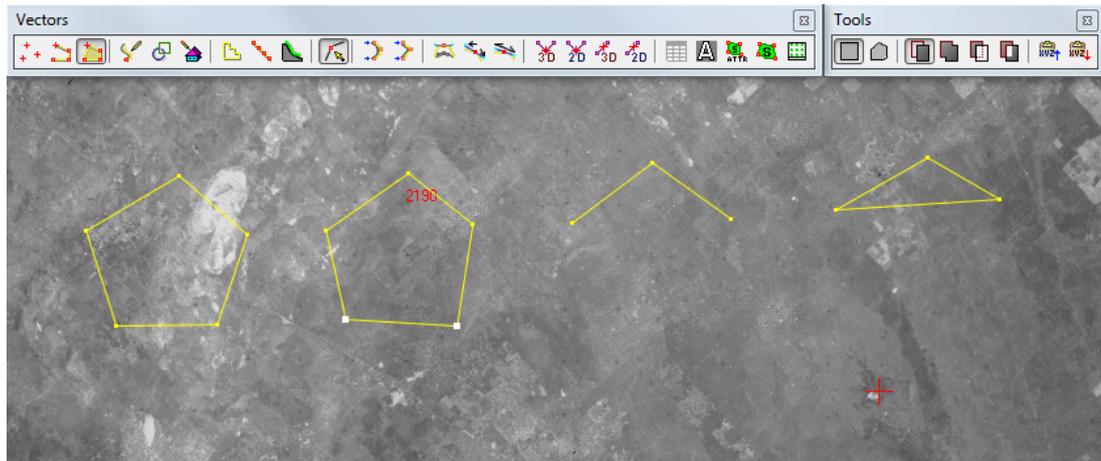


Fig. 151. Removing vertices (right vector object) and removing vertices together with adjacent segments (left vector object)



To select multiple vertices use **objects group selection** or turn the **add to selection** mode on in the **Tools** toolbar.



In order to remove just polygon/polyline vertex, select the vertex and press **Delete** (see **points editing mode**).

11.7. Creating common border

11.7.1. Continuing along polyline

The system allows to create objects common border using the following ways:

- to marker position;
- to closest common vertex;
- to selected vertex.

To create polyline along another polyline up to marker position, perform the following actions:

1. Start to create a polyline (see [Section 5.3.2](#)).
2. Place marker to the arbitrary point close to an existing polyline.
3. Choose **Vectors** > **Topology** > **Continue along polyline** > **To marker position** (**Shift+A**) or click the  button of the **Topology** toolbar.

After that the last common vertex of two polylines is created in intersection point of existing polyline and projection of marker position on this polyline.



If marker is located “far” from a polyline segment, the system creates additional segment of a new polyline, which is continued to the closest vertex.

4. Press **Enter** to complete polyline creation. After that a new and existing polylines have common border with coinciding vertices between the first and the last selected vertices.

To continue creating polyline along another polyline up to vertex, perform the following actions:

1. Start to create a polyline (see [Section 5.3.2](#)).
2. Place marker to the vicinity of an existing polyline vertex.
3. Choose **Vectors › Topology › Select nearest vertex (Shift+S)**. The closest to marker vertex is selected.
4. Choose **Vectors › Topology › Continue along polyline › To nearest joint vertex (Shift+F)** or click the  button of the **Topology** toolbar. The system creates common part of new and existing polylines.

To continue creating polyline/polygon along other vector objects up to necessary vertex, perform the following actions:



Prior to perform the operation set the **Vectors › Topology › Topological connectivity mode** checkbox on or click the  button of the **Topology** toolbar (see [Section 11.3.1](#)), otherwise, the operation is performed incorrectly.

1. Start to create a vector object (see [Section 5.3](#)).
2. Place marker to the arbitrary point close to an existing polyline.
3. To connect creating polyline to existing one select one the following ways:
 - choose **Vectors › Topology › Connect to point (Shift+V)** or click the  button of the **Topology** toolbar; both polylines/polygons have common vertex;
 - choose **Vectors › Topology › Connect to line (Shift+L)** or click the  button of the **Topology** toolbar; a new vertex is created at the intersection of the continuation of the polyline created and existing polyline segment.
4. Place marker in vicinity of the last common vertex and choose **Vectors › Topology › Select nearest vertex (Shift+S)**.
5. Choose **Vectors › Topology › Continue along polyline › To selected vertex (Shift+Z)** or click the  button of the **Topology** additional toolbar. After that a new and existing polylines/polygons have common external border with coinciding vertices.

11.7.2. Auto-close along polyline

The system provides a possibility to draw part of one polygon along the other. The function is used when common fragments of two vectorization objects coincide precisely (for example, land plots borders).

In order to draw part of one polygon along the other perform the following actions:

1. Place marker in vicinity of vertex of existing polygon, to which it is necessary to draw a fragment of other polygon.
2. Press **Insert** to create the first vertex of new polygon. Add vertices to continue polygon creation.
3. Place marker to the right of vertex of existing polygon, from which it is necessary to draw a fragment of other polygon.
4. Press **Insert** to add the last fragment vertex.
5. Choose **Vectors › Topology › Auto-close along polyline (Shift+M)** or click the  button of the **Topology** toolbar. After that a new polygon fragment is drawn along the existing one in boundaries specified by user.
6. Press **Enter** to complete polygon editing.

11.8. Topology control

11.8.1. Topology verifying

In some cases during vectorization there could be mistakes in the topology of vector objects. In order to check for errors and fix them, the system provides the opportunity to find and fix the topology of vector objects.

In order to find and correct topology errors, perform the following actions:

1. Choose **Vectors › Topology › Verify topology** or click the  button of the **Topology** additional toolbar. The **Parameters** window opens.

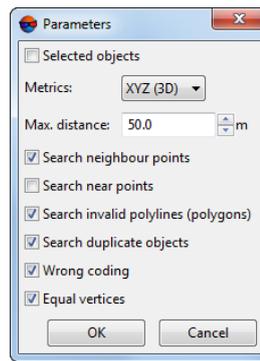


Fig. 152. Parameters of topology check

2. [optional] In order to verify topology of just selected objects, set the **Selected objects** checkbox.
3. In the **Metrics** list specify whether space is used to search for topology errors: XY (2D) or XYZ (3D).
4. Set one or several checkboxes to define the following parameters of topology errors search:
 - **Search neighbour points** – is used to search for coinciding adjacent vertices of object, the distance between them is less than the **Max. distance** value;
 - **Search near points** – is used to search for coinciding vertices, located on different polylines/polygons or points on objects vertices, the distance between them is less than the **Max. distance** value;
 - **Search invalid polylines (polygons)** – is used to search for polylines with the number of vertices less than two and polygons with the number of vertices less than three;
 - **Search duplicate objects** – is used to search for coinciding polylines/polygons or point objects, which vertices completely coincide;
 - **Wrong coding** – is used to search for vector objects, incorrectly linked to a classifier code.



Searching of **Wrong coding** objects is applied only for vector layers with classifier.

- **Equal vertices** – allows to find vertices of objects that consider to vertices of other objects.

5. Click OK. The system starts operation of topology verifying. In the case of error detection the system opens the **Errors correction** window. Each line of the list contains the error name and XY coordinates of the error.

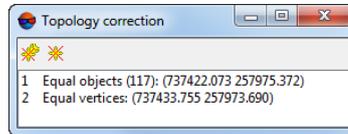


Fig. 153. Correction of topology errors

6. To pass to the point in 2D-window select the vertex in the list by mouse double click.
7. To correct errors perform one of the following actions:
 - “link” vertices using **snapping**;
 - to correct topological errors of any types click the  button;
 - to correct errors only for selected points click the  button.



Equal vertices could be edited only manually.

After correction of vector objects topology errors the erroneous vertices are joined into a single vertex with average coordinates value.

11.8.2. Check polygons relative position errors

The system provides possibility to search and analyse errors of polygons position (crossings, intersections and presence of “holes”). To find such errors select **Vectors › Topology › Find polygons relative position errors**.

If errors are found the system displays the window with information about total amount of polygons and amount of each error type. For each error type the system creates the layer – *Intersections*, *Self-intersections* or “*Holes*”– in which polygons are located at the intersection of initial layer polygons or “holes”.

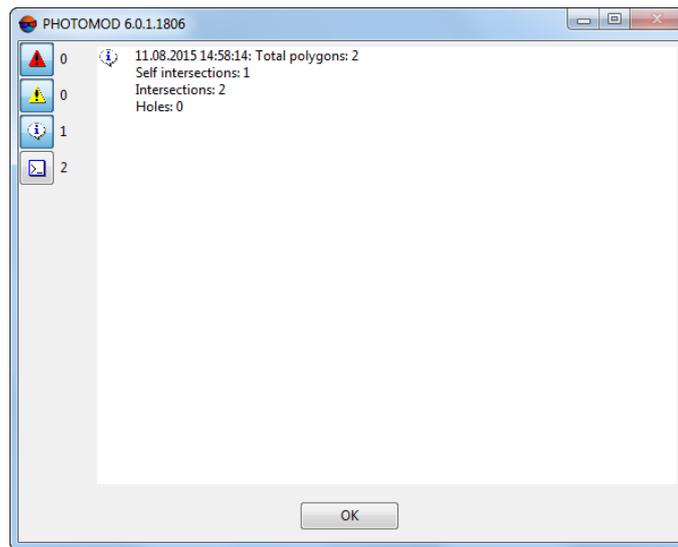


Fig. 154. Information window about topology errors

11.8.3. Polygons with coinciding points

The system provides possibility to search for polygons having common points. To find such points make polygon layer editable and choose **Vectors** › **Topology** › **Find polygons with one coinciding point**.

The system opens informational window indicating total number of points found (equals 0 if there are no points found). When the search is complete the system creates a new layer (copy of original polygons layer), containing *just common* points in the form of points (but not polygons themselves).

A new layer has a name like – *Common points (Vectors(2))*, where “*Vectors*” - is a name of initial layer which contains polygons being investigated, and “2” number means that the layer is a copy of “*Vectors*” layer. After next searches (for example, after adding new polygons to “*Vectors*” layer) resulting layers will have indexes “3”, “4”, etc.



Fig. 155. Information window with the search results

11.9. Editing of polygonal layer

11.9.1. Layers intersection

The system allows to intersect two layers with only polygons. At that polygons and its parts placed out of polygons of selected layer is deleted from the active vector layer.



It is used, for example, to edit overlap areas of specified sheets images during processing satellite images, when polygons created by images edges.



It is recommended to perform operation of layers intersection prior to operation of layers subtracting.

To intersect a polygonal layer with another one, perform the following actions:

1. Make active the image boundaries layer in the Manager.
2. Select **Vectors** › **Topology** › **Intersect one polygon layer with another**. The **Intersect with polygon layer** window opens.

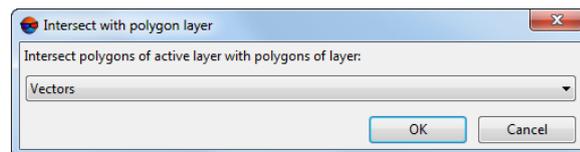


Fig. 156. Intersection of one polygon layer with another

3. Select the layer you want to cross with the active layer.
4. Click OK. After that is deleted polygons from active layer placed out of inactive polygon layers.

11.9.2. Layers subtraction

The system allows to subtract one polygonal layer from the other. At that polygons and its parts placed inside of polygons of selected layer is deleted from the active vector layer.

Perform the following actions to do this:

1. In Manager make active a source layer, from which you want to subtract the other layer of polygons.
2. Select **Vectors** › **Topology** › **Subtract one polygon layer from another**. The **Subtract polygon layer** window opens.

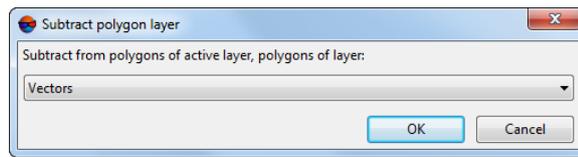


Fig. 157. Subtracting one polygon layer from another

3. Select a layer to be subtracted from an active layer.
4. Click OK. As a result, from polygons of active layer remove area inside of polygons on active layer. Polygon edge of active layer creates by polygon edge of selected layer.

12. Vector data editing using x-mdata file

12.1. Vector data conversion to x-mdata

The system provides possibility to edit big volumes of vector data using separate file with the *.x-mdata extension. Data processing is performed step by step in each area containing points. After the processing is used to build TIN and DEM.

To create vector data file with the *.x-mdata extension, perform the following actions:

1. Select **Vectors** > **Convert objects to x-mdata**. The **Parameters of conversion to x-mdata** window opens.

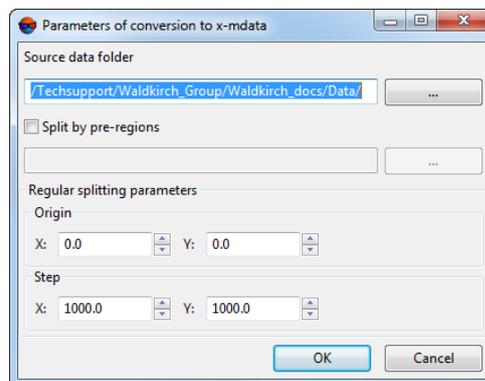


Fig. 158. Vector data conversion to x-mdata

2. In the **Source data folder** field select source folder, where to perform vector data search.
3. [optional] To edit vector data in stereopairs overlap area, set the **Split by pre-regions** checkbox and select file with pre-regions file in the project.

4. [optional] To change coordinates of grid's origin, in the **Regular splitting parameters** section, in the **Origin** sub-section input necessary origin coordinates.
5. [optional] To change grid's step in the **Regular splitting parameters** section, in the **Step** sub-section input grid step value.
6. Click OK. The **Save** window opens.
7. To the **Resource name** field input a name of new file with *.x-mdata extension.
8. Click the **Save** button to complete creation of vector data file.

12.2. x-mdata editing

The system provides possibility to process vector data by selected grid sheets or by stereopairs overlap areas, that contain points.

The **Edit x-mdata** toolbar is used to edit points.

The toolbar contains the following buttons:

-  – allows to open a layer containing data from file with *.x-mdata extension;
-  – allows to close a layer containing data from file with *.x-mdata extension;
-  – allows to open for editing a layer with data from selected grid sheet;
-  – allows to open for editing a layer with data from a grid sheet, where the marker is located;
-  – allows to open for editing a layer with data from all linear objects, located on images;
-  – allows to save changes on selected grid sheet;
-  – allows to close selected grid sheet;

To edit vector data file with the *.x-mdata extension, perform the following actions.

1. Select **Vectors > x-mdata editor**. The **Edit x-mdata** toolbar shows.
2. Click the  button of the **Edit x-mdata** toolbar to open a layer containing data from file with *.x-mdata extension.
3. Select a grid sheet for further editing of vector data using one of the following ways:
 - by mouse click with pressed the **Shift** key select one of the grid sheets by mouse and click the  button of the **Edit x-mdata** toolbar.

- place the marker to vicinity of a grid sheet and click the  button of the **Edit x-mdata** toolbar.
 - 4. [optional] To edit linear objects located on images click the  button of the **Edit x-mdata** toolbar.
 - 5. Click the  button of the **Vectors** toolbar to enable point objects input mode.
 - 6. Edit consistently points on selected grid sheet.
-  If point is input or moved out of the selected grid sheet area, it is automatically saved in the location where it was input.
7. Click the  to save changes on a layer with data of selected grid sheet.
 8. Click the  to close a layer with data of selected grid sheet;
 9. Continue to edit other grid sheets.
 10. To end process file click the  button or close the **Edit x-mdata** toolbar.

13. Import of vector objects

13.1. Import from ASCII

The system provides possibility to import vector objects from the ASCII format. In the ASCII format each vector object is marked as sequence of points with three-dimensional coordinates.

Files of this format has the *.txt extension. The file contains a sequence of records delimited by the * symbol. Each entry describes an object that is a point or polyline/polygon. The record consists of object code and a series of lines with three-dimensional coordinates of vertices separated by a comma. Example of ASCII-file contents:

Road

L 1234 67.4567 67.565 453

L 1245 6.7439 570.860 958

*

Point

L 1257 85.2198 76.459 56

*

In order to import vector objects from the ASCII format perform the following actions:



If the layer with the classifier was created earlier, when you import the file from ASCII format layer attributes are preserved.

1. Choose **Vectors** > **Import** > **ASCII**. The **Import from ASCII format** window opens.

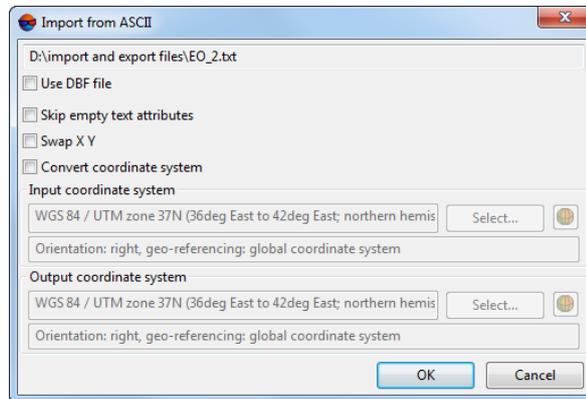


Fig. 159. Import from ASCII

2. [optional] In order to define standard parameters set the **Use DBF file**, **Swap X Y** and **Convert coordinate system** checkboxes on (see [Section 10.5](#)). If all checkboxes are set on, then when importing first XY-coordinates of points are swapped, then the system recalculates the coordinates.



If the **Swap X Y** checkbox is cleared, the vector objects will be imported in the right coordinate system. Otherwise, in the left one.

3. [optional] To prevent creating text attributes without value during import, set the **Do not create empty text attributes** checkbox on.



When the **Do not create empty text attributes** checkbox is on, in some cases a data loss may occur.

4. Click OK to complete the import operation.

13.2. Import from ASCII-A

The system provides possibility of vector objects import from ASCII-A format. ASCII-A format contains information about coordinates of vector objects vertices, as well as information about object type, layer number, attributes name and value.

Files of this format has the *.txt extension. Unlike ASCII, in ASCII-A format object description contains first lines that describe object type and attributes.

Example of ASCII-A file content:

L 101 1 13 4

OBJECT_NAME=Railway

OBJECT_COLOR=3

OBJECT_SYMBOL=R

OBJECT_SIZE=5.5

545566.505,473671.817,77.850

545715.103,473656.072,78.310

545782.001,473567.393,78.156

545860.428,473463.139,77.974

545847.506,473339.305,77.380

545795.032,473249.288,76.795

545517.126,473365.500,76.318

545269.605,473463.426,75.869

*

The first line of each section has the following structure:

Type, code, layer, N1, N2, where:

- Type is a symbol defined object type (L, P, C);
- Code is an object code;
- Layer is a number of layer;
- N1 – the total number of lines where there is a description of the object in the file;
- N2 – the number of lines where there is a description of the object attributes in the file;

This is followed by lines with attributes description that have the following form:

Name=Value

Then there are lines with the object vertices coordinates. The sequence of records is delimited by * symbol.

In order to import vector objects from the ASCII-A format perform the following actions:

1. Choose **Vectors** › **Import** › **ASCII-A**. The **Import from ASCII-A format** window opens.

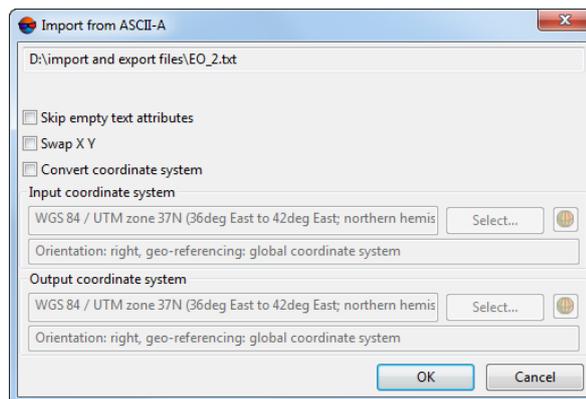


Fig. 160. Import from ASCII-A

2. [optional] In order to define additional parameters set the **Swap X Y** and **Convert coordinate system** checkboxes on (see [Section 10.5](#)). If all checkboxes are set on, then when importing first XY-coordinates of points are swapped, then the system recalculates the coordinates.



If the **Swap X Y** checkbox is cleared, the vector objects will be imported in the right coordinate system. Otherwise, in the left one.

3. [optional] To prevent creating text attributes with an empty value during import, set the **Do not create empty text attributes** checkbox on.



When the **Do not create empty text attributes** checkbox is on, in some cases a data loss may occur.

4. Click OK to complete the import operation.

13.3. Import from CSV

The system provides possibility to import vector objects (with their attributes) from the CSV format. CSV format is exchange text format, which is supported by major applications in different industries. It is used as exchange format when special geospatial data formats are not applicable for some reason. In particular, CSV format is often used the exchange data about orthomosaic splitting into sheets.

CSV-files with *.csv and *.txt extensions are supported.

In order to import vector objects from the CSV format perform the following actions:

1. Choose **Vectors > Import > CSV**. The **Import from CSV format** window opens.

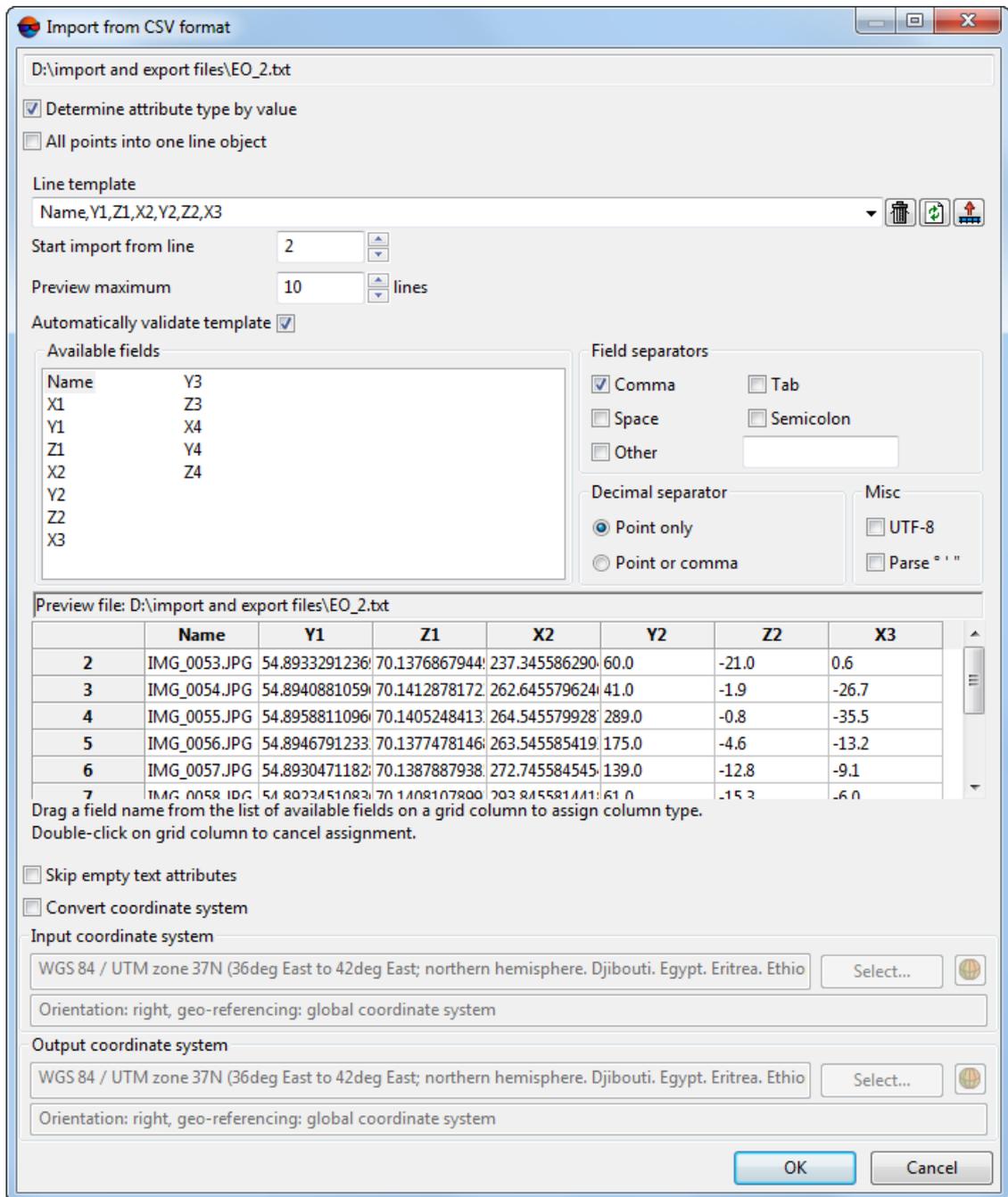


Fig. 161. Import from CSV

2. [optional] To prevent creating text attributes with an empty value during import, set the **Do not create empty text attributes** checkbox on.



When the **Do not create empty text attributes** checkbox is on, in some cases a data loss may occur.

3. [optional] After import the text type is assigned to all attributes. To assign the float type for attributes with numeric value (see [Section 7.1.1](#)), set the **Define attribute type by value** checkbox on.
4. [optional] To import flight path files set the **All points into one line object**.
5. The **Line template** field displays the list of fields, contained in each line of imported CSV file:
 - Name – object's name;
 - X_n , Y_n , Z_n , where n – integer number, coordinates of the first and subsequent vertices of the object;
 - * – missed field during import.

All objects are saved using the same template. Each line of a file contains the same number of fields, that equals to number of fields in template. Lines which does not correspond to the template, are skipped. To all vertexes two (for 2D objects import) or three coordinates are specified.

In order to setup active template, perform one of the following actions:

- drag a field name from the **Available fields** list to the **Preview file** table column. After that the template in the **Line template** field is changes. To cancel a field selection, double click the **Preview file** table column;
- change the template manually in the **Line template** field. Column type of the **Preview file** table change automatically.

The  button is used to return to default template: Name X Y Z.

The  button is used to compare the **Line template** field with data shown in the **Preview file** table.



The active template corresponds only to lines shown in the **Preview file** table.

The  button is used to replace specified field names by field values taken from the first line of the **Line template** table.



It is possible to specify any names for *vectors* import. For import of *laser scanning* data the field names from the list of available names are specified.



To import together with vector objects their attributes recorded in a *.csv file together with object vertex coordinates, click the  button, and if it is necessary to import only a part of the attributes, change the line template manually in the **Line template** field.

To view attributes of vector objects after import, select a vector object and choose **Window › Object attributes**.



For correct import of vector objects with attributes, the first line of the *.csv file must be filled in appropriately.



Пример файла *.csv, содержащего координаты точечных векторных объектов (пикетов) и их атрибуты. The example of *.csv file containing coordinates of point vector objects and their attributes is the following:

```
x,y,z,attribute name 1,attribute name 2
738181.714,260663.890,570.127,attribute value 1,attribute value 2
738186.630,260691.792,567.264,attribute value 1,attribute value 2
<...>
738341.832,260696.672,572.350,attribute value 1,attribute value 2
```

6. [optional] Set the following additional parameters:
 - **Automatically validate template** – allows to use template, specified in the first string of file; set the checkbox off to change template manually;
 - **Start import from line** – allows to choose file string from which is data import starts;
 - **Preview maximum** – allows to define number of strings displayed in the **Preview file** table (10 by default).
7. In the **Available fields** section select necessary field name and drag it to the table column. To cancel the field name double click the column header.
8. In the **Field separators** section set on one or multiple checkboxes to specify possible fields delimiter symbol: **comma**, **space**, **tab**, **semicolon** or **other**. Default settings are comma and space.
9. In the **Decimal separator** section setup the following parameters:
 - **Point only** – to use point only as a decimal separator in coordinates;
 - **Point or comma** – to use both point and comma as a decimal separator in coordinates.



If a **comma** is used as *field separator*, it is strongly not recommended for the **Decimal separator** use **point or comma**, since objects will import incorrect.

10. In the **Misc** section set the following checkboxes:

- **UTF-8** – is used to recognize text in Unicode coding;



Unicode – symbols encoding format that allows to provide symbols of almost all written languages.

- **Parse ° ’ “** – is used to recognize records of projection centers or GCP.



When using this parameter it is highly recommended to check recognizing correctness after import operation. To do this **select** any point in 2D-window and check coordinates values in the **Marker ???** window.

11. The **Preview file** table contains data of imported file. Fields type according to the template, located in the **Line template** field, are automatically assigned to the table columns.



The * symbols marks columns with data which is not imported.

12. [optional] To change output objects coordinate system set the **Convert coordinate system** checkbox on.

13. Click OK to import.



Current template saves after import and adds to a drop-down list.

To check for errors the import results of the catalogue of projection centers or GCP **select** a point in 2D-window; the **Marker** window will display point's coordinates in DMS format.

13.4. Import from DGN

The system provides possibility of vector objects import from DGN V7 format (other possible names – ISFF DGN/Intergraph DGN). This is exchange format with *.dgn extension, that is used in the *MicroStation 7*.



The DGN V8 format, that is used in the *MicroStation 8* and later versions is not supported. In this case to perform data exchange it is necessary in *MicroStation* to convert DGN file to V7 format.

In order to import vector objects from the DGN format perform the following actions:

1. Choose **Vectors** > **Import** > **DGN**. The **Import from DGN format** window opens.

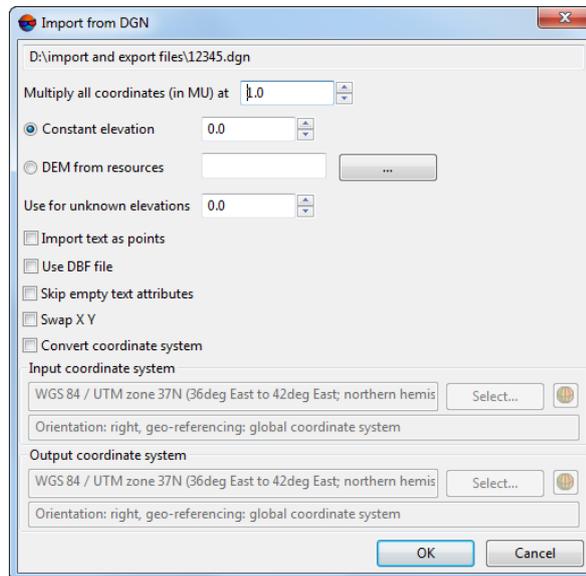


Fig. 162. Import from DGN

2. [optional] To multiply all coordinates of objects vertices during import specify the coefficient in the **Scale** field.
3. In the Z for 2D objects section define one of the calculation ways of Z coordinates of objects vertices:
 - **Constant elevation** – allows to assign the same value of Z coordinate to all objects;
 - **DEM from resources** – allows to select a resource with DEM containing Z values. Click the **...** button to choose file in active profile resources.
 - **Use for unknown elevation** – allows to fill the empty DEM cells with a predetermined elevation values.
4. [optional] To convert text objects from DGN file into point objects with label containing source object text, set the **Import text as points** checkbox on (see [Section 6.5](#)).
5. [optional] To define additional parameters set the **Use DBF file**, **Swap X Y** and **Transform reference system** checkboxes on (see [Section 10.5](#)). If all checkboxes are set on, then when importing first XY-coordinates of points are swapped, then the system recalculates the coordinates.
6. [optional] To prevent creating text attributes with an empty value during import, set the **Do not create empty text attributes** checkbox on.



When the **Do not create empty text attributes** checkbox is on, in some cases a data loss may occur.

7. Click OK to complete the import operation.

13.5. Import from DXF

The system provides possibility of vector objects import from DXF format. This is exchange format with *.dxf extension, that is used in the *AutoCAD programs*.



The DXF format, that is used in the *AutoCAD R15* and later versions is not supported. In this case to perform data exchange it is necessary in *AutoCAD program* to convert DXF file to R14 format.

In order to import vector objects from the DXF format perform the following actions:

1. Choose **Vectors > Import > DXF**. The **Import from DXF format** window opens.

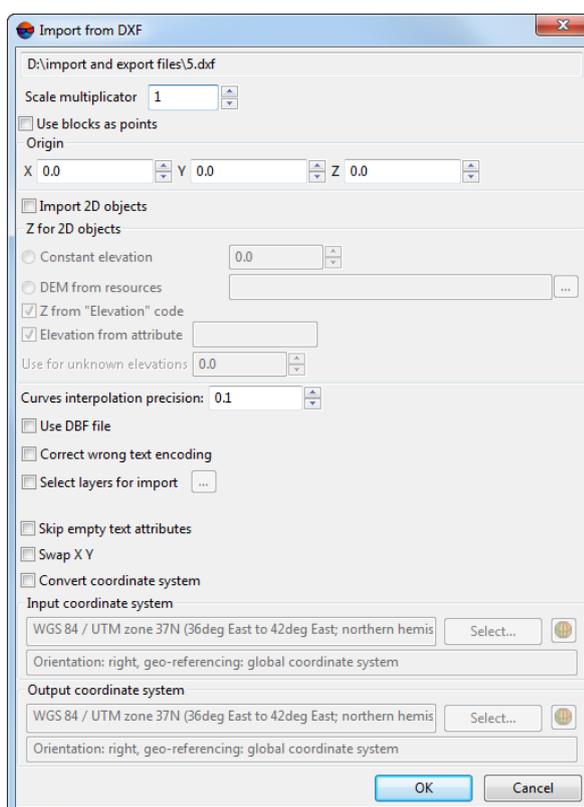


Fig. 163. Import from DXF

2. [optional] To multiply all coordinates of objects vertices during import specify the coefficient in the **Scale** field.

3. [optional] To import origin of *AutoCAD program* objects blocks as point objects, set the **Use blocks as points**.
4. In the **Point of origin** section specify origin of coordinate system.
5. [optional] To convert 2D objects from DXF file into 3D objects, set the **Import 2D objects** checkbox on. In the **Z for 2D objects** section define one of the calculation ways of Z coordinates of objects vertices:
 - **Constant elevation** – allows to assign the same value of Z coordinate to all objects;
 - **DEM from resources** – allows to select a resource with DEM containing Z values. Click the  button to choose file in active profile resources.
 - **Use for unknown elevation** – allows to fill the empty DEM cells with a predetermined elevation values.
 - **Z from “Elevation” code** – allows to import Z coordinate from “Elevation” code;
 - **Elevation from attribute** – allows to import Z coordinate from attribute, which name is specified in this field, its default value is *Elev*.
6. [optional] To define import accuracy of objects, containing curve lines, specify the **Curves interpolation precision** parameter value, after that the number of curve vertices is changed.
7. [optional] To prevent creating text attributes with an empty value during import, set the **Do not create empty text attributes** checkbox on.



When the **Do not create empty text attributes** checkbox is on, in some cases a data loss may occur.

8. [optional] To define additional parameters set the **Use DBF file**, **Swap X Y** and **Transform reference system** checkboxes on (see [Section 10.5](#)).



If all checkboxes are set on, then when importing first XY-coordinates of points are swapped, then the system recalculates the coordinates.

9. [optional] To correct wrong import of text objects set the **Correct wrong text encoding** checkbox on.
10. [optional] To import a particular number of layers set the **Select layers for import** checkbox on and click the  button. The **Layers table** window is opened, where the list of layers to be imported is displayed.

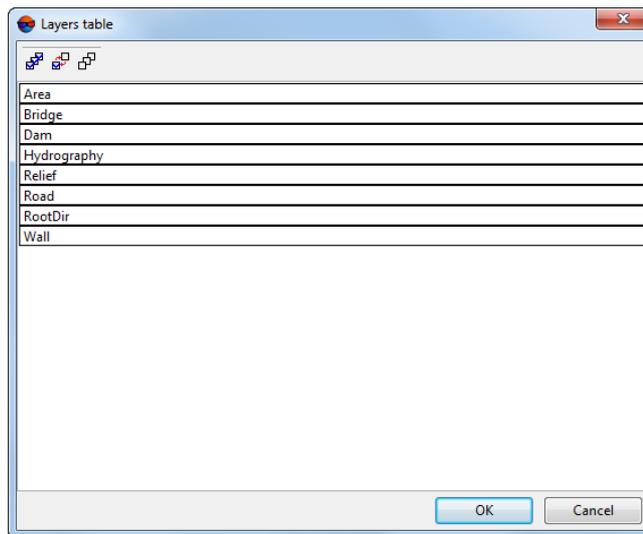


Fig. 164. Table of layers to be imported

Select layers in the table using one of the following ways:

- to import all layers, click the  button and click OK;
- to import not all layers, select them and click OK.



to invert layers selecting allows the  button, to unselect all layers – the  button.

11. Click OK to import.

13.6. Import from Generate

The system provides possibility of vector objects import from Generate format. Files with points have the *.gnp or *.pnt extension, files with polylines – *.gnl or *.lin. This format is used in the *ArCInfo* system.

In order to import vector objects from the Generate format perform the following actions:

1. Choose **Vectors** › **Import** › **Generate**. The **Import from Generate format** window opens.

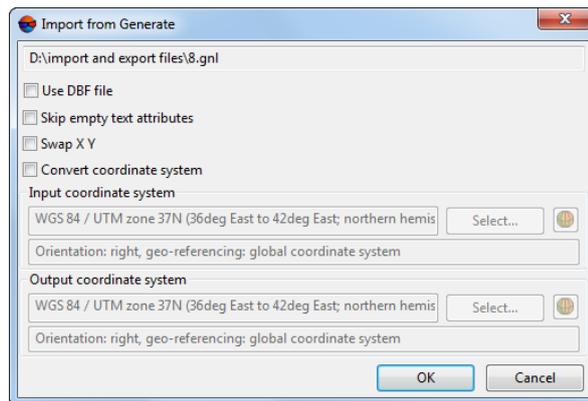


Fig. 165. Import from Generate

- [optional] To define additional parameters set the **Use DBF file**, **Swap X Y** and **Transform reference system** checkboxes on (see [Section 10.5](#)). If all checkboxes are set on, then when importing first XY-coordinates of points are swapped, then the system recalculates the coordinates.



If the **Swap X Y** checkbox is cleared, the vector objects will be imported in the right coordinate system. Otherwise, in the left one.

- [optional] To prevent creating text attributes with an empty value during import, set the **Do not create empty text attributes** checkbox on.



When the **Do not create empty text attributes** checkbox is on, in some cases a data loss may occur.

- Click OK to complete the import operation.

13.7. Import from ATLAS KLT

The system provides possibility to import vector objects from the ATLAS KLT format. Files of this format has the *.klt extension.

In order to import vector objects from the ATLAS KLT format perform the following actions:

- Choose **Vectors** › **Import** › **ATLAS KLT**. The **Import from ATLAS KLT format** window opens.

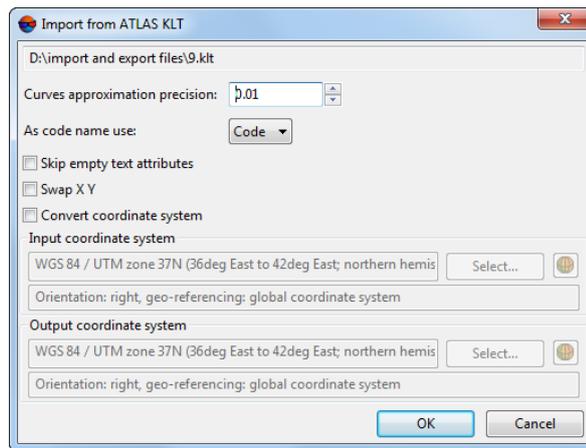


Fig. 166. Import from ATLAS KLT format

- [optional] In order to change the number of vertices in a polyline approximating an arc, input the **Curves approximation precision** parameters value.



The higher the approximation precision, the more vertices in a polyline approximating the arc/circle.

- Select in the **As a code name use**, list, which parameter is recorded as a code name when importing.
- [optional] To prevent creating text attributes with an empty value during import, set the **Do not create empty text attributes** checkbox on.



When the **Do not create empty text attributes** checkbox is on, in some cases a data loss may occur.

- [optional] In order to define standard parameters set the **Swap X Y** and **Convert coordinate system** checkboxes on (see [Section 10.5](#)). If all checkboxes are set on, then when importing first XY-coordinates of points are swapped, then the system recalculates the coordinates.



If the **Swap X Y** checkbox is cleared, the vector objects will be imported in the right coordinate system. Otherwise, in the left one.

- Click OK to complete the import operation.

13.8. Import from KML

The system provides possibility to import vector objects from the KML format. Files of this format has the *.kml extension.



Import vector objects from KML format does not perform in projects in the local coordinate system.

In order to import vector objects from the KML format perform the following actions:

1. Choose **Vectors** > **Import** > **KML**. The **Import from KML format** window opens.

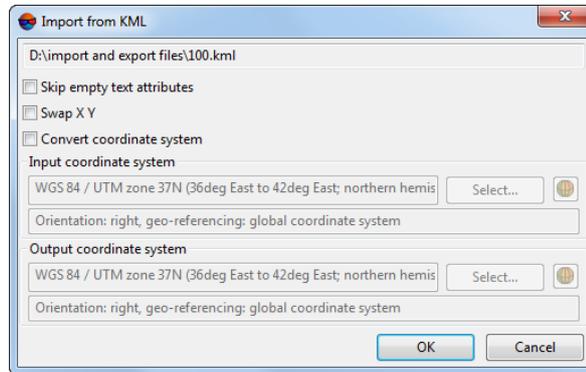


Fig. 167. Import from KML format

2. [optional] To prevent creating text attributes with an empty value during import, set the **Do not create empty text attributes** checkbox on.



When the **Do not create empty text attributes** checkbox is on, in some cases a data loss may occur.

3. [optional] In order to define additional parameters set the **Swap X Y** and **Convert coordinate system** checkboxes on (see [Section 10.5](#)). If all checkboxes are set on, then when importing first XY-coordinates of points are swapped, then the system recalculates the coordinates.



If the **Swap X Y** checkbox is cleared, the vector objects will be imported in the right coordinate system. Otherwise, in the left one.

4. Click OK to complete the import operation.

13.9. Import from LAS

The system provides possibility to import laser scanning point cloud from LAS format. Files of this format has the *.las extension.

In order to import vector objects from the LAS format perform the following actions:

1. Choose **Vectors** > **Import** > **LAS**. The **Import from LAS format** window opens.

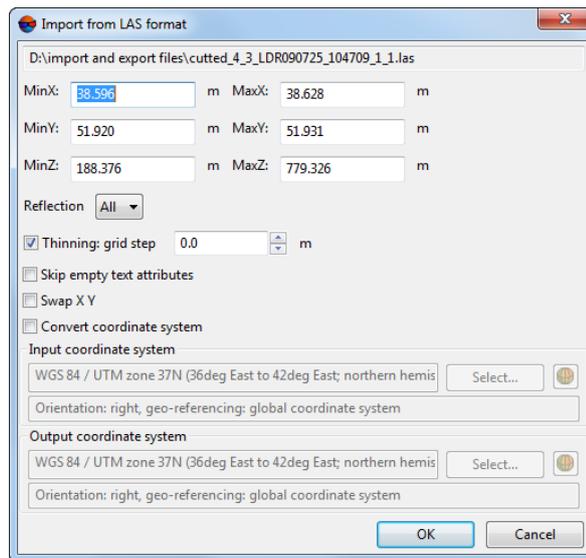


Fig. 168. Import from LAS format



In the **MinX**, **MinY**, **MinZ**, **MaxX**, **MaxY**, **MaxZ** fields the system displays coordinates range of points that are contained in imported LAS file.

2. In the **Reflection** list select number of reflections, from which the system should perform import of point objects, containing in the file.
3. Input the **Thinning: grid step** value (in meters) to reduce the amount of data to be imported during the import process.



The system's default value of thinning step parameter is 0.0 meters.



Point are thinned in such a way that the distance between them is not less than a predetermined grid step.

4. [optional] To prevent creating text attributes with an empty value during import, set the **Do not create empty text attributes** checkbox on.



When the **Do not create empty text attributes** checkbox is on, in some cases a data loss may occur.

5. [optional] In order to define additional parameters set the **Swap X Y** and **Convert coordinate system** checkboxes on (see [Section 10.5](#)). If all checkboxes are set on, then when importing first XY-coordinates of points are swapped, then the system recalculates the coordinates.



If the **Swap X Y** checkbox is cleared, the vector objects will be imported in the right coordinate system. Otherwise, in the left one.

6. Click OK to complete the import operation.

13.10. Import from LIG

The system provides possibility to import vector objects from the LIG format. Files of this format has the *.lig extension.

In order to import vector objects from the LIG format perform the following actions:

1. Choose **Vectors > Import > LIG**. The **Import from LIG format** window opens.

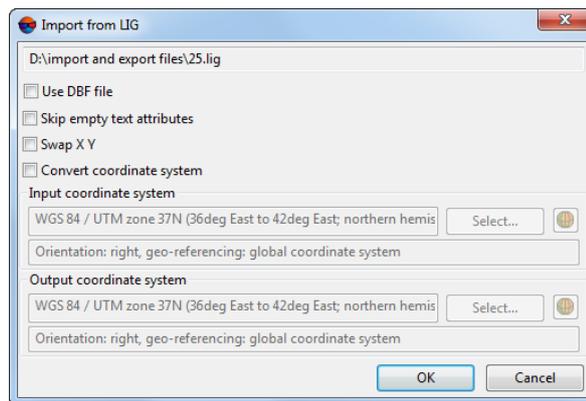


Fig. 169. Import from LIG format

2. [optional] To define additional parameters set the **Use DBF file**, **Swap X Y** and **Transform reference system** checkboxes on (see [Section 10.5](#)). If all checkboxes are set on, then when importing first XY-coordinates of points are swapped, then the system recalculates the coordinates.



If the **Swap X Y** checkbox is cleared, the vector objects will be imported in the right coordinate system. Otherwise, in the left one.

3. [optional] To prevent creating text attributes with an empty value during import, set the **Do not create empty text attributes** checkbox on.



When the **Do not create empty text attributes** checkbox is on, in some cases a data loss may occur.

4. Click OK to complete the import operation.

13.11. Import from MIF/MID

The system provides possibility to import vector objects from the MIF/MID format. This is exchange format with mif extension, that is used in the *MapInfo* system.



When importing from MIF/MID format it is not allowed to use underscores in attributes names. Replace all underscore characters in attribute names with spaces.

In order to import vector objects from the MIF/MID format perform the following actions:

1. Choose **Vectors** › **Import** › **MIF/MID**. The **Import from MIF/MID format** window opens.

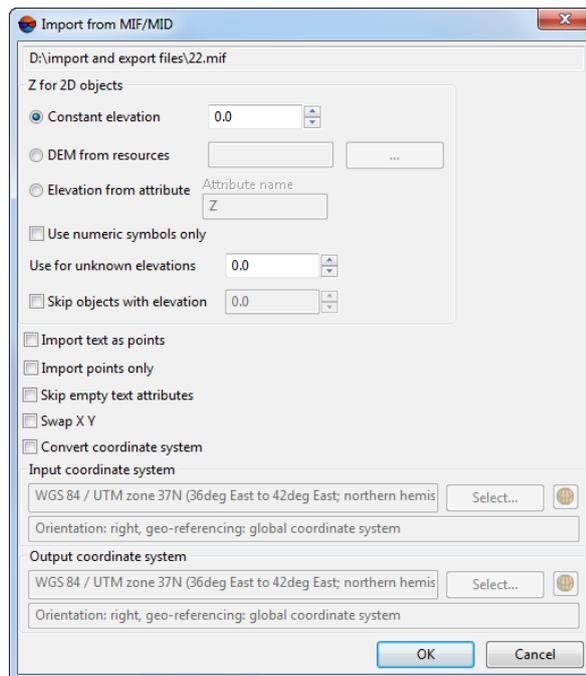


Fig. 170. Import from MIF/MID format

2. In the **Z for 2D objects** section define one of the calculation ways of Z coordinates of objects vertices:

- **Constant elevation** – allows to assign the same value of Z coordinate to all objects;
- **DEM from resources** – allows to select a resource with DEM containing Z values. To open necessary resource click the  button. To fill the empty DEM cells with a predetermined elevation values, change the **Use for unknown elevation** parameter value.
- **Elevation from attribute** – allows to import Z coordinate from attribute, which name is specified in this field, its default value is Z. In order to remove all symbols from an attribute except for digits, point, comma and minus, set the **Use numeric symbols only** checkbox;

3. [optional] In order to exclude objects with specified elevation, set the **Skip objects with elevation** checkbox on and input necessary value.
4. [optional] To convert text objects from MIF/MID file into point objects with label containing source object text, set the **Import text as points** checkbox on (see [Section 6.5](#)).
5. [optional] To split linear objects into separate points, set the **Import points only** checkbox on.
6. [optional] To prevent creating text attributes with an empty value during import, set the **Do not create empty text attributes** checkbox on.



When the **Do not create empty text attributes** checkbox is on, in some cases a data loss may occur.

7. [optional] In order to define standard parameters set the **Swap X Y** and **Convert coordinate system** checkboxes on (see [Section 10.5](#)). If all checkboxes are set on, then when importing first XY-coordinates of points are swapped, then the system recalculates the coordinates.



If the **Swap X Y** checkbox is cleared, the vector objects will be imported in the right coordinate system. Otherwise, in the left one.

8. Click OK to complete the import operation.

13.12. Import from Shape

The system provides possibility to import vector objects from the Shape format. This is exchange format with *.shp extension, that is used in *ArctInfo* softwaresystem.

The Shape format consists of three files with the same names and following extensions:

- *.shp – main file, that contains information about objects; one *Shapefile* stores objects of the only one type – points, polylines or polygons;
- *.shx – additional index file, that contains information about objects position in the main file; it is used to speed up access to the content of the *Shapefile*;
- *.dbf – additional file containing the table of DBF database (see [Section 13.14](#)).

In order to import vector objects from the Shape format perform the following actions:

1. Choose **Vectors** › **Import** › **Shape**. The **Import from Shape** window opens.

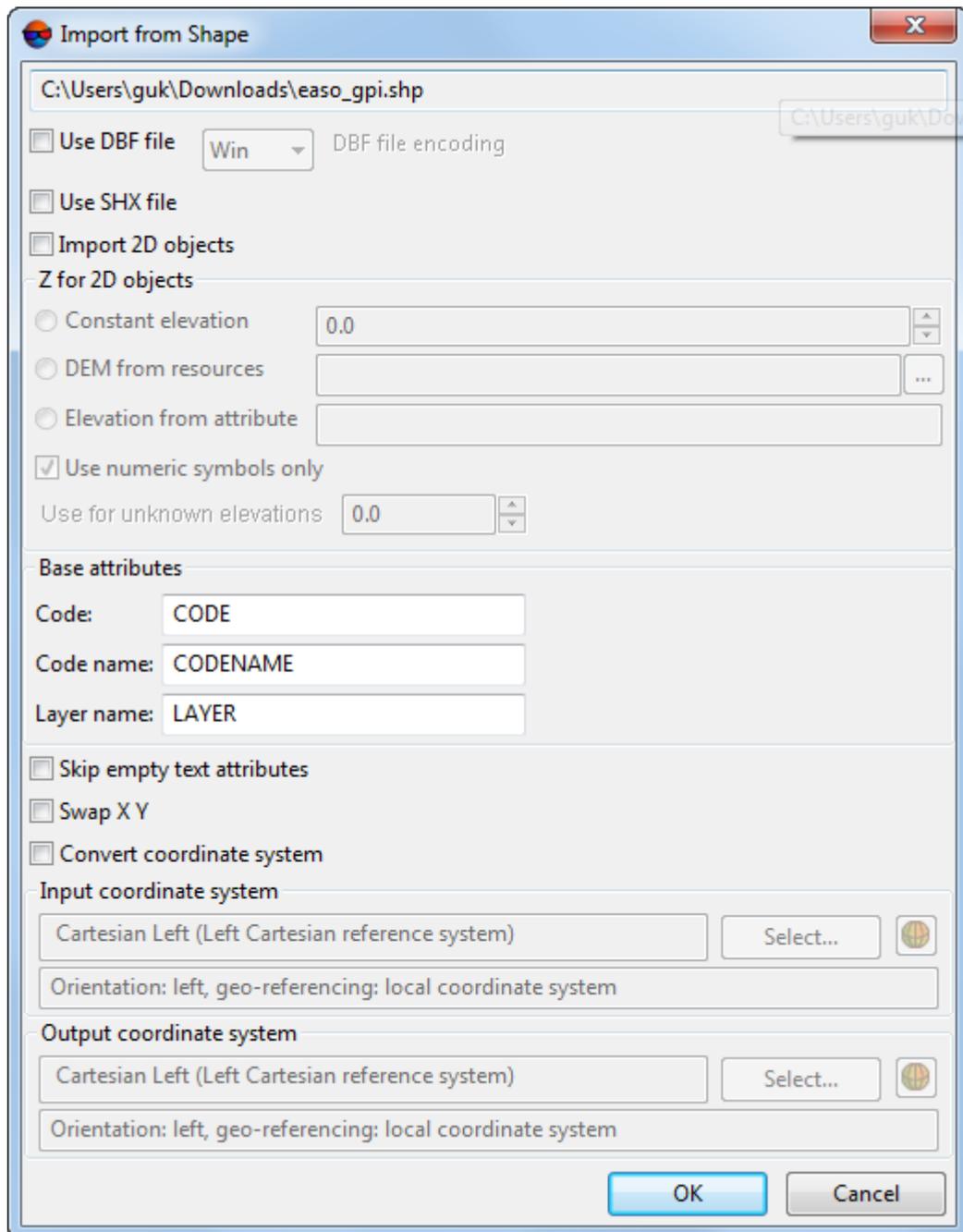


Fig. 171. Import from SHP format

2. [optional] To use file with attribute information about objects, and to assign vector objects to classifier, the **Use DBF file** checkbox is on by default (see [Section 13.14](#)).
3. [optional] To use file with information about location of objects, stored in the file with *.shp extension, the **Use SHX file** checkbox is on by default.

4. [optional] To convert 2D objects from DXF file into 3D objects, set the **Import 2D objects** checkbox on.

In the **Z for 2D objects** section define one of the calculation ways of Z coordinates of objects vertices:

- **Constant elevation** – allows to assign the same value of Z coordinate to all objects;
- **DEM from resources** – allows to select a resource with DEM containing Z values. To open necessary resource click the  button. To fill the empty DEM cells with a predetermined elevation values, change the **Use for unknown elevation** parameter value;
- **Elevation from attribute** – allows to import Z coordinate from attribute, which name is specified in this field, its default value is Z. In order to remove all symbols from an attribute except for digits, point, comma and minus, set the **Use numeric symbols only** checkbox.

5. In the **Base attributes** section specify code names in the DBF file:

- **Code** – the *CODE* by default;
- **Code name** – *CODENAME* by default;
- **Layer name** – *LAYER* by default;

6. [optional] To prevent creating text attributes with an empty value during import, set the **Do not create empty text attributes** checkbox on.



When the **Do not create empty text attributes** checkbox is on, in some cases a data loss may occur.

7. [optional] In order to define standard parameters set the **Swap X Y** and **Convert coordinate system** checkboxes on (see [Section 10.5](#)). If all checkboxes are set on, then when importing first XY-coordinates of points are swapped, then the system recalculates the coordinates.



If the **Swap X Y** checkbox is cleared, the vector objects will be imported in the right coordinate system. Otherwise, in the left one.

8. Click OK to complete the import operation.

13.13. Import from Panorama

The system provides possibility of vector objects import from Panorama format. This is exchange format with *.sit and *.map extensions, that is used in *GIS Map* system.

In order to import vector objects from Panorama format perform the following actions:

1. Select **Vectors** › **Import** › **Panorama**. The **Import from Panorama format** window opens.

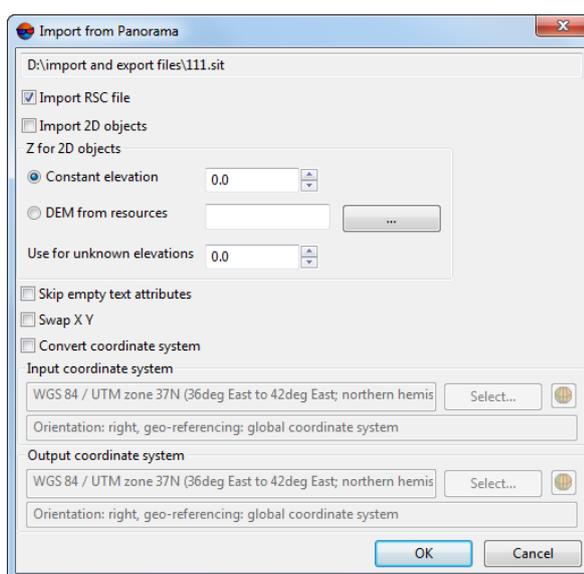


Fig. 172. Import from Panorama format

2. In order to convert the *Панорама* classifier into inner classifier of the system, the **Import classifier** checkbox is on by default (see [Section 6.4](#)).
3. [optional] To convert 2D objects from DXF file into 3D objects, set the **Import 2D objects** checkbox on. In the **Z for 2D objects** section define one of the calculation ways of Z coordinates of objects vertices:
 - **Constant elevation** – allows to assign the same value of Z coordinate to all objects;
 - **DEM from resources** – allows to select a resource with DEM containing Z values. To open necessary resource click the  button. To fill the empty DEM cells with a predetermined elevation values, change the **Use for unknown elevation** parameter value. The default value is 0.0.
4. [optional] To prevent creating text attributes with an empty value during import, set the **Do not create empty text attributes** checkbox on.



When the **Do not create empty text attributes** checkbox is on, in some cases a data loss may occur.

- [optional] In order to define standard parameters set the **Swap X Y** and **Convert coordinate system** checkboxes on (see [Section 10.5](#)). If all checkboxes are set on, then when importing first XY-coordinates of points are swapped, then the system recalculates the coordinates.



If the **Swap X Y** checkbox is cleared, the vector objects will be imported in the right coordinate system. Otherwise, in the left one.

- Click OK to complete the import operation.

The system provides possibility to import just point objects and linear object vertices without attribute from Panorama format.

Perform the following actions to do this:

- Choose **Vectors > Import > Panorama (points only)**. The **Import from Panorama format** window opens.

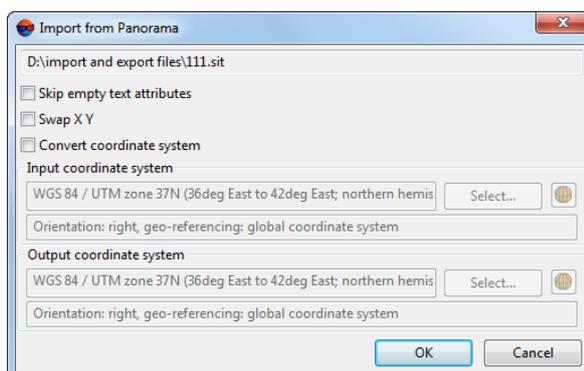


Fig. 173. Import points from Panorama format

- [optional] To prevent creating text attributes with an empty value during import, set the **Do not create empty text attributes** checkbox on.



When the **Do not create empty text attributes** checkbox is on, in some cases a data loss may occur.

- [optional] In order to define additional parameters set the **Swap X Y** and **Convert coordinate system** checkboxes on (see [Section 10.5](#)). If all checkboxes are set on, then when importing first XY-coordinates of points are swapped, then the system recalculates the coordinates.



If the **Swap X Y** checkbox is cleared, the vector objects will be imported in the right coordinate system. Otherwise, in the left one.

4. Click OK to complete the import operation.

13.14. Using DBF file

The system allows to use DBF file if it is near to imported file. This is a file with the *.dbf extension contains dBASE database table and is used as a file with attribute information about objects, as well as for assigning vector objects to classifier.

Set the **Use DBF** checkbox on in the import settings window to use DBF file.

The database fields contain attribute information. In the first four fields DBF file stores the following information:

- *NAME* – a unique object name;
- *CODE* – a code in classifier, to which the object is assigned;
- *CODENAME* – a code name in classifier, to which the object is assigned;
- *LAYER* – the layer name in the classifier, in which there is the object's code.

Starting with the fifth field in the file are stored both basic and additional attributes of vector objects.

When importing objects with the classifier from external exchange formats the objects are attached to the current codes of [classifier](#). To do this the system uses the information stored in the main importing file or in DBF file. Objects are assigned to classifier during import in the following way:

1. From the main importing file or from DBF file the system reads code name, code, object type (point, polyline, polygon) and layer name.
2. The system checks a presence of code in loaded classifier. If the code is present in the classifier, the object is assigned to it automatically. If there is no such code in the classifier, the system creates a new layer and imported objects are assigned to it.

13.15. Batch import

The system allows to perform import of multiple files with vector objects of any format.

To perform import of triangulation points catalogue perform the following actions:

1. Choose **Vectors > Import > necessary_format**. The system opens the window used to select files to be imported.
2. To choose files for import, click on them while the **Shift** key pressed.
3. Click the **Open** button. The import parameters window opens (more details on the import options see in the relevant paragraphs of this section).
4. Setup import parameters and click OK. The **Loading** window opens.

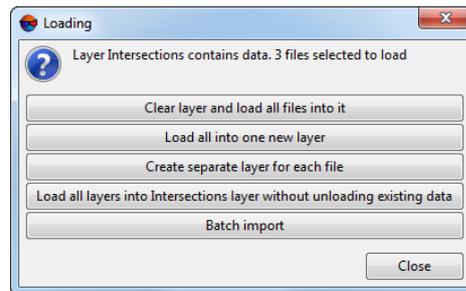


Fig. 174. Ways of multiple file loading

5. Select one of the following ways of imported layers loading:
 - **Clear layer and load all files into it** – vector data of active layer is replaced by data from loading layers;
 - **Load all into one new layer** – vector data is loaded to a single new vector layer;
 - **Create separate layer for each file** – vector data of each file are loaded to separate layers;
 - **Load all layers into Vectors without unloading existing data** – during loading vector data is added to objects of active vector layer.
 - **Batch import** – vector data is imported to system's internal format and are saved to the selected folder in active profile resources. At that the data are not loaded in the project and new layers are not created.



If there are no loaded layers in the project, the **Clear layer and load all files into it** and **Load all layers into Vectors without unloading existing data** loading options does not display.

14. Export of vector objects

14.1. Export to ASCII

The system provides possibility of export to ASCII format. In ASCII format, each vector object is referred to as a sequence of vertices with three-dimensional coordinates. A description of the file format see in the [Section 13.1](#).

In order to export vector objects to ASCII format perform the following actions:

1. Select **Vectors** › **Export** › **ASCII**. The **Export to ASCII** window opens.

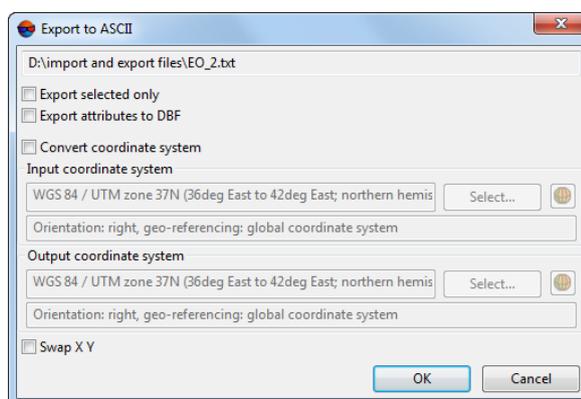


Fig. 175. Export to ASCII format

2. [optional] In order to export just selected points, set the **Export selected only** checkbox.
3. [optional] To create file with attribute information about objects, and to assign vector objects to classifier, set the **Export attributes to DBF file** checkbox on.
4. [optional] In order to define standard parameters set the **Swap X Y** and **Convert coordinate system** checkboxes on (see [Section 10.5](#)).



If the **Swap X Y** checkbox is set off, the vector objects will be exported in the right coordinate system. Otherwise, in the left one.

5. Click OK to complete the export operation.

14.2. Export to ASCII-A

The system provides possibility of vector objects export to ASCII-A format. ASCII-A format contains information about coordinates of vector objects vertices, as well as information about object type, layer number, attributes name and value. A description of the file format see in the [Section 13.2](#).

In order to export vector objects to ASCII-A format perform the following actions:

1. Choose **Vectors** > **Export** > **ASCII-A**. The **Export to ASCII-A format** window opens.

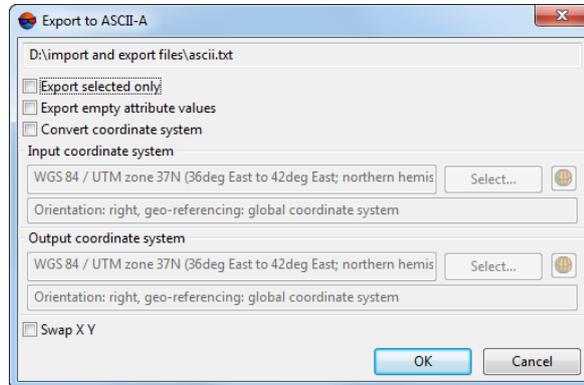


Fig. 176. Export to ASCII-A format

2. [optional] In order to export just selected points, set the **Export selected only** checkbox.
3. [optional] In order to export data without attribute information, set the **Export empty attribute values** checkbox.
4. [optional] In order to define standard parameters set the **Swap X Y** and **Convert coordinate system** checkboxes on (see [Section 10.5](#)).



If the **Swap X Y** checkbox is set off, the vector objects will be exported in the right coordinate system. Otherwise, in the left one.

5. Click OK to complete the export operation.

14.3. Export to CSV

The system provides possibility of export to CSV format. CSV format is exchange text format with csv extension, which is supported by major applications in different industries. It is used as exchange format when special geospatial data formats are not applicable for some reason. In particular, CSV format is often used the exchange data about orthomosaic splitting into sheets.

In order to export vector objects to CSV format perform the following actions:

1. Select **Vectors** > **Export** > **CSV**. The **Export to CSV** window opens.

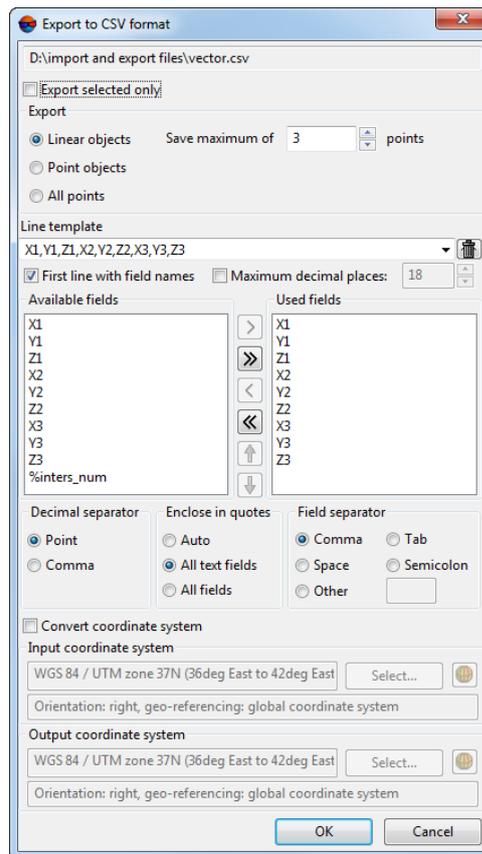


Fig. 177. Export to CSV format

2. [optional] In order to export selected points only, set the **Export selected only** checkbox on.
3. [optional] In order to export one type of objects, in the **Export** section choose objects type:
 - **Linear objects** – only polylines is exported. In the **Save maximum of .. points** field is defined maximum number of vertices of polyline for export. The other vertices are not export and polyline is cutting out;
 - **Point objects** – only points is exported;
 - **All points** – both points and vertices are exported.
4. The **Line template** field displays the list of fields of each line of CSV-file. Define the following additional parameters of data in file:



The  button allows to clear the **Line template** field.

- **First line with field names** – allows to add **Line template** in the first line of file;

- **Maximum decimal places** – allows to specify number of decimal places in points coordinates.



Line template could be specified manually or with **Available/Used fields** lists.

5. In the **Available fields** list are displayed names of fields could be used as **line template** for export. In the **Used fields** is displayed list of fields that are used as **Line template**. Prepare template with the following buttons:
 -  – allows to add selected **Available field** to the **Used fields** list (add to the template);
 -  – allows to add all **Available fields** to a line template;
 -  – allows to remove selected field name from the **Used fields** list;
 -  – allows to remove all fields names from this list;
 -  – allows to move down field selected in the **Used fields** list;
 -  – allows to move up field selected in the **Used fields** list.
6. In the **Decimal separator** section choose, point or comma to be used to separate coordinates.
7. [optional] In order to limit required parts of exported list of coordinates by quotes, in the **Enclose in quotes** section choose one of the following options:
 - **Auto** – fields limit by quotes automatically;
 - **All text fields** – only text fields are limited by quotes;
 - **All fields** – allows to limit by quotes each field, which is located in the exported file.
8. In the **Field separator** section choose, what is used to separate fields: **comma**, **space**, **tab**, **semicolon** or **other**.

 If a **comma** is used as *field separator*, it is strongly not recommended for the **Decimal separator** use **point or comma**, since objects will export incorrect.
9. [optional] To define standard parameters set the **Transform reference system** checkbox on (see [Section 10.5.2](#)).
10. Click OK to complete the export operation.

14.4. Export to DGN

The system provides possibility of export to DGN V7 format (another names are *ISFF DGN/Intergraph DGN*). This is exchange format with *.dgn extension, that is used in *MicroStation 7*.



The DGN V8 format, that is used in the *MicroStation 8* and later versions is not supported. In this case to perform data exchange it is necessary in *MicroStation* to convert DGN file to V7 format. Exported file in DGN V7 format could be opened in any *MicroStation version*, however, format features imposes restrictions on the completeness of exported data.

The file of this format contains code, code name, object type, and object attributes. Coordinates in DGN format are presented as main units *Position Units* in the range from 0 to $4 \cdot 10^9$. For floating-point numbers the additional units *Sub Units (SU)* and *Master Units (MU)* are used.



The ratio of measurement units:

$$1 \text{ SU} = N \text{ Pos. units}$$

$$1 \text{ MU} = M \text{ SU} ,$$

where N and M -- integer numbers, stored as constants in DGN file.

In order to export vector objects to DGN format perform the following actions:

1. Select **Vectors** > **Export** > **DGN**. The **Export to DGN** window opens.

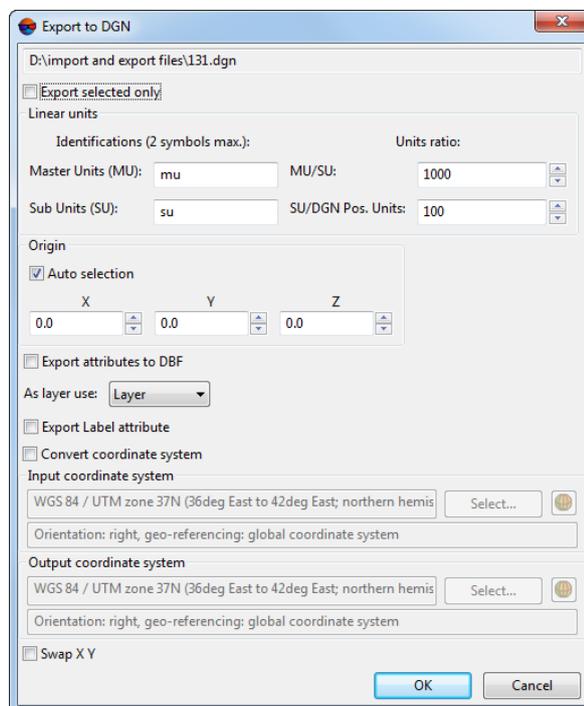


Fig. 178. Export to DGN format

2. [optional] In order to export just selected points, set the **Export selected only** checkbox.
3. [optional] To rename *Sub Units (SU)* and *Master Units (MU)*, in the **Linear units** section input notations containing two symbols. To change the ratio of units, change the **MU/SU** or **SU/DGN Pos.** parameters **Units**.
4. In the **Point of origin** section specify origin coordinates. The **Auto selection** checkbox allows to define coordinate system origin as as the center of parallelepiped circumscribing all available objects.
5. [optional] To create file with attribute information about objects, and to assign vector objects to classifier, set the **Export attributes to DBF file** checkbox on.
6. In order to specify what to assign vector objects after export, select the **As layer use:** parameter in the list.



By default the system assigns objects using layer name. After that the system creates file with *.lvl extension, which contains selected layers names.



The system allows to use assignment by object code or by the code name.

7. [optional] In order to export special objects labels (see [Section 6.5](#)), set the **Export Label attribute** checkbox.
8. [optional] To define standard parameters set the **Swap X Y** and **Transform reference system** checkboxes on (see [Section 10.5](#)).



If the **Swap X Y** checkbox is set off, the vector objects will be exported in the right coordinate system. Otherwise, in the left one.

9. Click OK to complete the export operation.

14.5. Export to DXF

The system provides possibility of export to DXF format. This is exchange format with *.dxf extension, that is used in the *AutoCAD program*.



The DXF format, that is used in the *AutoCAD R15* and later versions is not supported. In this case to perform data exchange it is necessary in *AutoCAD program* to convert DXF file to R14 format. During vector objects export the system also preserves the selected line style used when exported DXF file is opened in the *AutoCAD program*.

In order to export vector objects to DXF format perform the following actions:

1. Load a vector layer with points.

2. Select **Vectors** > **Export** > **DXF**. The **Export to DXF** format window opens.

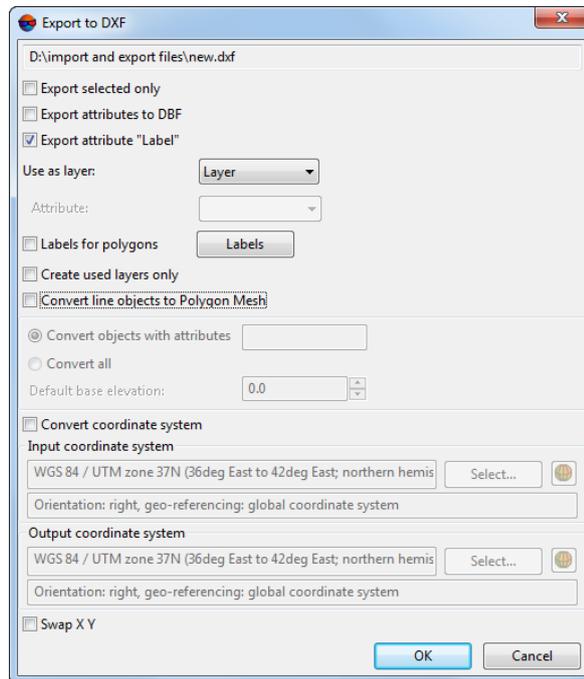


Fig. 179. Export to DXF format

3. Specify the following parameters of export:

- **Export selected only** – allows to export only selected object from active layer;
- **Export attributes to DBF** – allows to create file with with attribute information about objects, as well as for assigning vector objects to classifier;
- **Export attribute “Label”** – allows to export special object labels (see [Section 6.5](#));
- **Use as layer** – allows to choose what to assign vector objects after export;



By default the system assigns objects using layer name. After that the system creates file with *.lvl extension, which contains selected layers names.



The system allows to use assignment by object code or by the code name. When vector objects are assigned by attribute value, select the *Label* name in the **Attribute** list.

- **Create used layers only** – allows to export only classifier layers with vector objects;
- **Labels for polygons** – allows to export labels for polygons in a separate layer. Click the **Labels** button to specify parameters of labels export.

The **Labels for polygons** window opens.

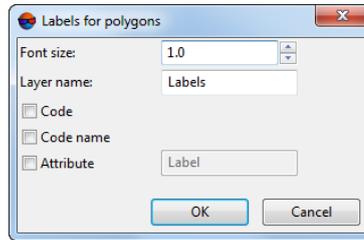


Fig. 180. Parameters polygon labels

Define the following parameters:

- **Font size** of labels;
 - **Layer name** – name of layer with labels;
 - **Code**, **Code name** or **Attribute** – allows to specify layer name (see [Section 7.2.1](#)).
4. [optional] To convert linear objects to polyhedral object (see example below) set the **Convert linear objects to Polygon Mesh** checkbox on and specify, what objects to convert:
 - **Convert objects with attributes** – used to convert linear objects with attribute;
 - **Convert all** – used to convert all linear objects; to set the orthogonal projection of a linear object on a horizontal plane, change the **Default base elevation**.
 5. [optional] In order to define additional parameters set the **Swap X Y** and **Convert coordinate system** checkboxes on (see [Section 10.5](#)).
 6. Click OK to complete the export operation.

There is an example of export vector objects to DXF format with converting them to a polyhedral object.

1. Load a *Roofs* layer with vector objects (roofs) to export in DXF format with converting on polyhedral object.

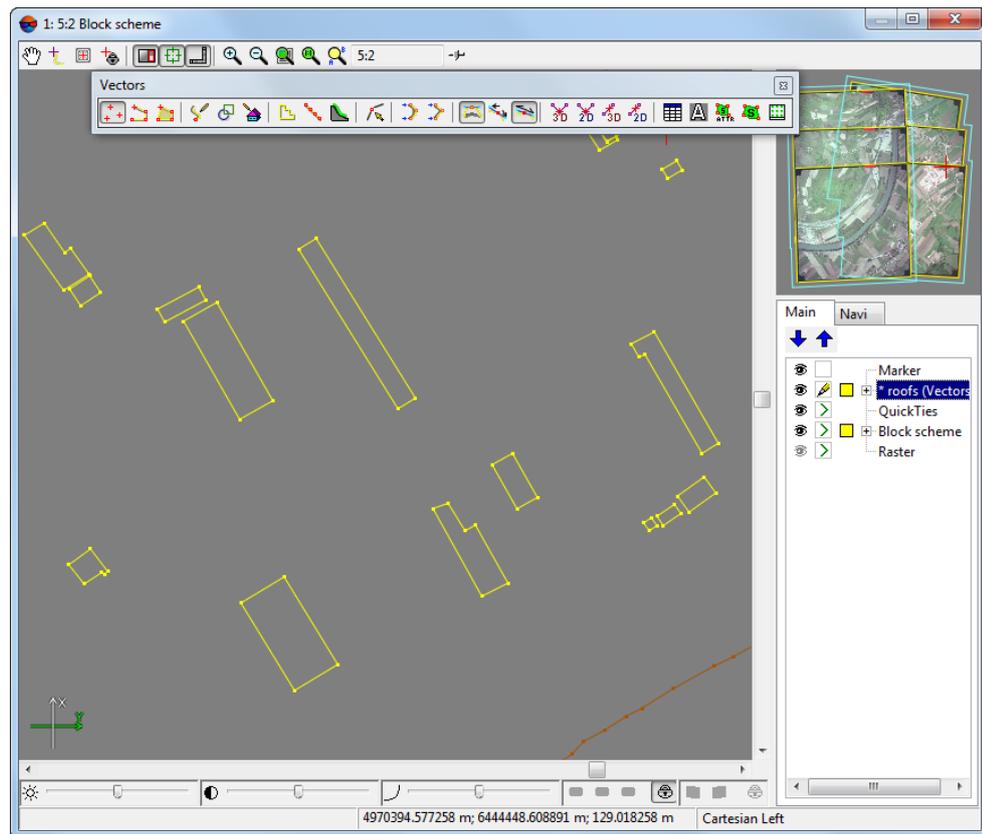


Fig. 181. Source vector layer

2. In the **Export to DXF** window set the set the **Convert linear objects to Polygon Mesh** checkbox on and export objects to a DXF file.

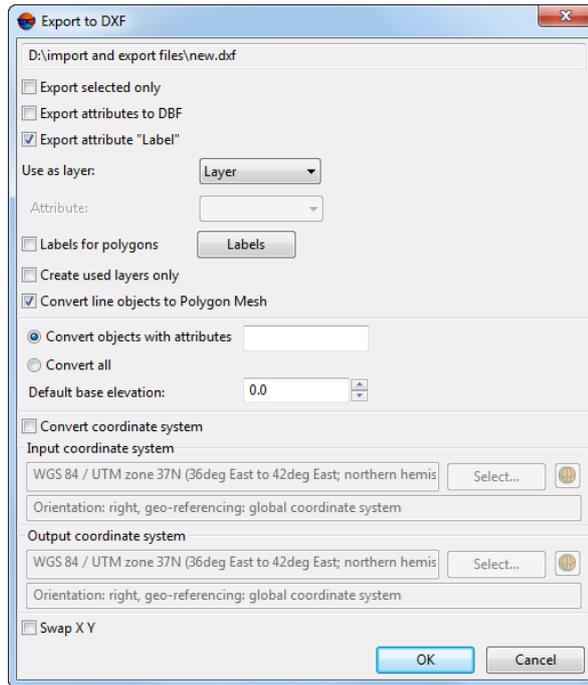


Fig. 182. Parameters of export to DXF format

3. Open exported file in the *Autodesk* program. Roofs are displayed as polyhedral objects.

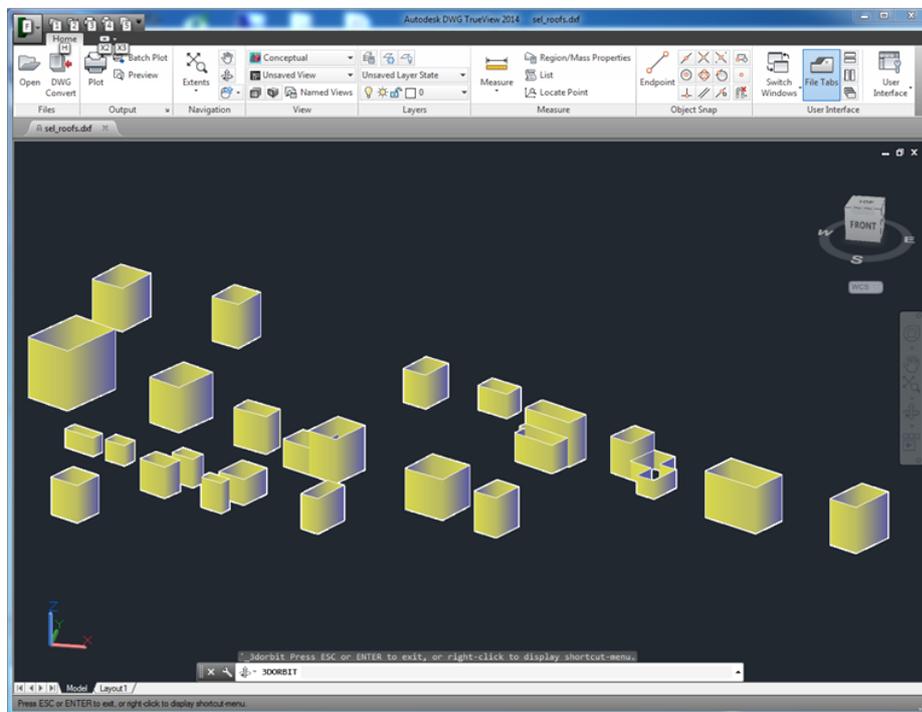


Fig. 183. Roofs, displayed as polyhedral objects

The system also provides possibility of batch vector objects export to DXF format. Batch export is used to export classifier layer to separate files.

Perform the following actions to do this:

1. Open a layer with classifier.

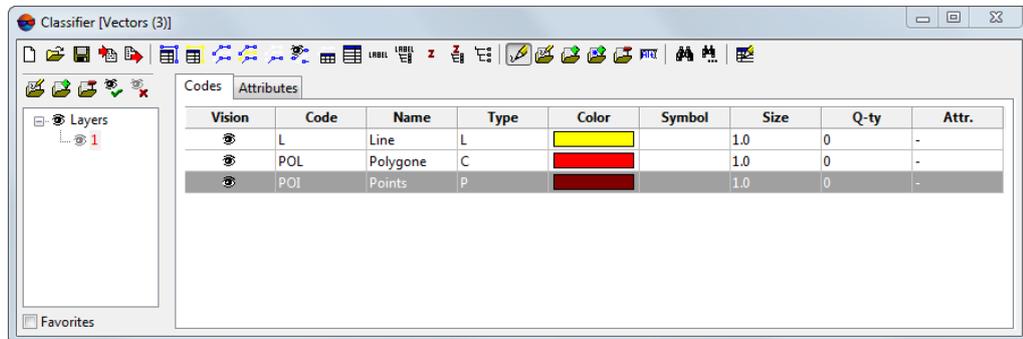


Fig. 184. Batch export to DXF format

2. Select **Vectors** > **Batch export** > **DXF**. The **Browse for folder** window opens.
3. Select folder to export files.
4. Click OK. The **Export to DXF** window opens.

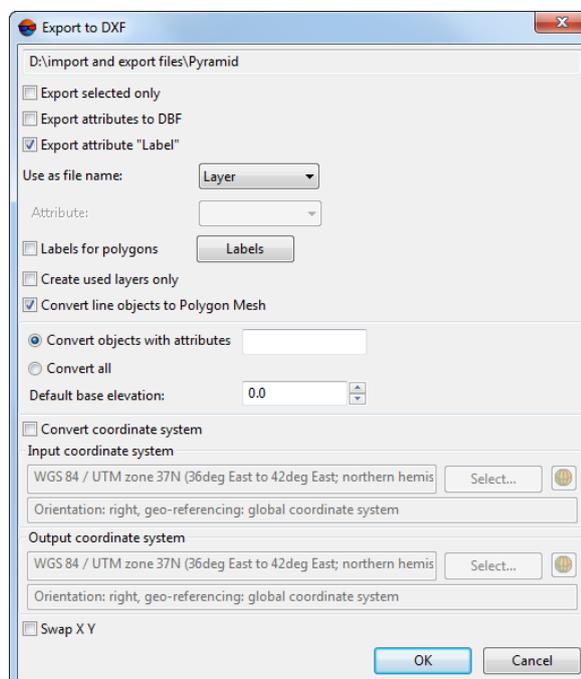


Fig. 185. Batch export to DXF format

5. Choose in the **As file name use** list classifier parameter, by which vector data divides to files and names assign to these files: **Layer**, **Code Code name** or **Attribute value**.
6. Configure the rest parameters of export in the same way as for usual export to DXF format.
7. Click OK. In chosen path are created files, each of them contains data of only selected classifier layer (or parameter).

14.6. Export to Generate format

The system provides possibility of export to Generate format. This format is used in *ArcInfo* softwaresystem. Files with points have the *.gnp or *.pnt extension, files with polylines – *.gnl or *.lin.

During export to *Arc Generate* integer index is assigned to each object. If the layer with classifier is exported, the object code, which is an integer is used as this index. Otherwise, the object is assigned an index equal to the maximum value of all already used codes plus 1.

In order to export vector objects to Generate format perform the following actions:

1. Select **Vectors** > **Export** > **Generate**. The **Export to Generate** window opens.

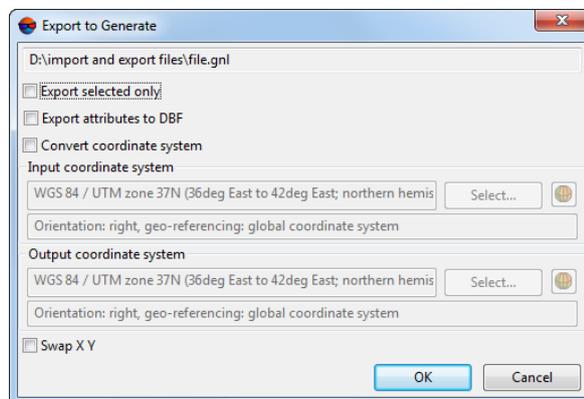


Fig. 186. Export to Generate format

2. [optional] In order to export just selected points, set the **Export selected only** checkbox.
3. [optional] To create file with attribute information about objects, and to assign vector objects to classifier, set the **Export attributes to DBF file** checkbox on.
4. [optional] In order to define standard parameters set the **Swap X Y** and **Convert coordinate system** checkboxes on (see [Section 10.5](#)).



If the **Swap X Y** checkbox is set off, the vector objects will be exported in the right coordinate system. Otherwise, in the left one.

- Click OK to complete the export operation.

14.7. Export to ATLAS KLT format

The system provides possibility of vector objects export to ATLAS KLT format.

Files of this format has the *.klt extension.

In order to export vector objects to ATLAS KLT format perform the following actions:

- Choose **Vectors > Export > ATLAS KLT**. The **Export to ATLAS KLT format** window opens.

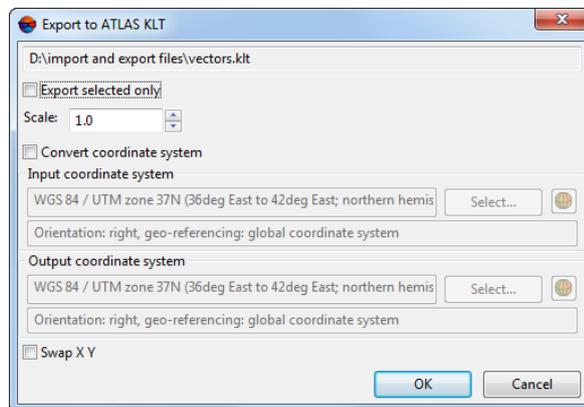


Fig. 187. Export to ATLAS KLT format

- Define the following parameters of datum: [optional] In order to export just selected points, set the **Export selected only** checkbox.

- **Export selected only** – allows to export only selected object from active layer;
- **Scale** – allows to change scale that adds in the head of file.



Scale value adds in the head of ATLAS KLT file. By default scale is 10 000.

- [optional] In order to define additional parameters set the **Swap X Y** and **Convert coordinate system** checkboxes on (see [Section 10.5](#)).



If the **Swap X Y** checkbox is set off, the vector objects will be exported in the right coordinate system. Otherwise, in the left one.

- Click OK to complete the export operation.

14.8. Export to KML

The system provides possibility of vector objects export to KML format. Files of this format has the *.kml extension.



Vector objects in local coordinate system could not be exported in the KML format. To perform export change the coordinate system to the global one (see [Section 10.5.2](#)).

In order to export vector objects to KML format perform the following actions:

- Select **Vectors** > **Export** > **KML**. The **Export to KML format** window opens.

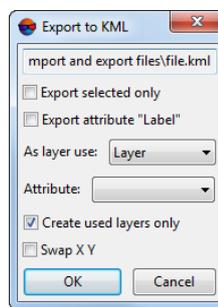


Fig. 188. Export to KML format

- Specify the following parameters of export:

- **Export selected only** – allows to export only selected object from active layer;
- **Export attribute “Label”** – allows to export special object labels (see [Section 6.5](#));
- **Use as layer** – allows to choose what to assign vector objects after export;



The system allows to use assigning by classifier layer, object code, name of this code or attribute value. When vector objects are assigned by attribute value, choose **Attribute** in the list.

- **Create used layers only** – allows to export only classifier layers with vector objects;

- [optional] To define additional parameters set the **Swap X Y** checkbox on (see [Section 10.5](#)).



If the **Swap X Y** checkbox is set off, the vector objects will be exported in the right coordinate system. Otherwise, in the left one.

- Click OK to complete the export operation.

14.9. Export to LIG

The system provides possibility of vector objects export to LIG format. Files of this format has the *.lig extension.

In order to export vector objects to LIG format perform the following actions:

- Select **Vectors** › **Export** › **LIG**. The **Export to LIG** window opens.

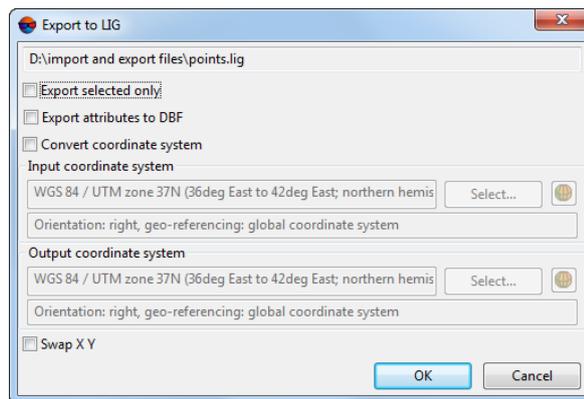


Fig. 189. Export to LIG format

- Specify the following parameters of export:
 - **Export selected only** – allows to export only selected object from active layer;
 - **Export attributes to DBF** – allows to create file with with attribute information about objects, as well as for assigning vector objects to classifier.
- [optional] In order to define additional parameters set the **Swap X Y** and **Convert coordinate system** checkboxes on (see [Section 10.5](#)).
- Click OK to complete the export operation.

14.10. Export to MIF/MID

The system provides possibility of export to MIF/MID format. The MIF/MID format is the exchange format with mif extension, that is used in the *MapInfo* system.



When exporting to MIF/MID format it is not allowed to use space in attributes names. Replace all spaces in attribute names with underscores.

In order to export vector objects to MIF/MID format perform the following actions:

1. Choose **Vectors** › **Export** › **MIF/MID**. The **Export to MIF/MID** window opens.

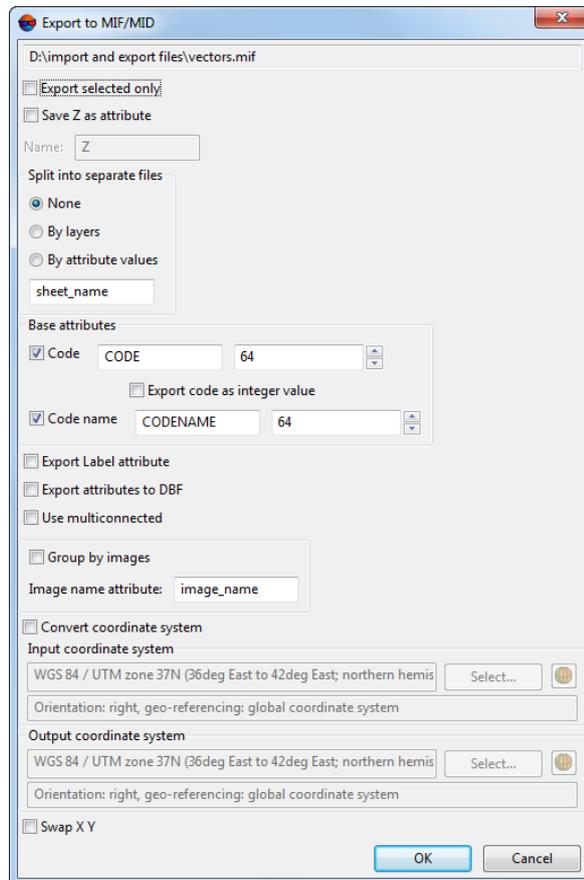


Fig. 190. Export to MIF/MID format

2. [optional] In order to export just selected points, set the **Export selected only** checkbox.
3. Specify the following parameters of export:
 - **Export selected only** – allows to export only selected object from active layer;
 - **Export attribute “Label”** – allows to export special object labels (see [Section 6.5](#)).
 - **Export attributes to DBF** – allows to create file with with attribute information about objects, as well as for assigning vector objects to classifier.
4. [optional] To preserve Z coordinate as attribute in classifier, set the **Save Z as attribute** checkbox and specify attribute name in the **Name** field.
5. In the **Split into separate files** section specify one of the ways of export to a separate file:

- **None** – all objects of opened layer are exported in one file;
 - **By layers** – each layer of classifier is exported to separate file, file is named with name of corresponding classifier layer;
 - **By attribute values** – used to export objects of opened layer by attribute value, which name is specified in this field.
6. [optional] In the **Base attribute** section choose classifier attributes for DBF-file: **Code** and/or **Code name**. Define their names and line length of attribute in correspondent fields.



Attribute line has default length – 64 symbols. If it is necessary to display in *MapInfo* attributes with code with are not integer, set the **Export code as integer value** checkbox on.

7. [optional] In order to export splitting into sheets as separate objects (for example, to export separately polygons that correspond to images borders, and separately “gaps”), set the **Use multiconnected** checkbox on. To merge separate objects with the same attributes (for example, to group just “gaps”) set the **Group by images** checkbox on and input attribute name into the **Image name attribute:** field.
8. [optional] In order to define additional parameters set the **Swap X Y** and **Convert coordinate system** checkboxes on (see [Section 10.5](#)).



If the **Swap X Y** checkbox is set off, the vector objects will be exported in the right coordinate system. Otherwise, in the left one.

9. Click OK to complete the export operation. Two files with the same names is created. The first file has the *.mif extension and contains vector objects. The second file has the *.mid extension and contains attributes of these vector objects.

14.11. Export to PLY

The system provides possibility of vector objects export to PLY format. Files of this format has the *.ply extension.

In order to export vector objects to PLY format perform the following actions:

1. Select **Vectors** › **Export** › **PLY**. The **Export to PLY format** window opens.

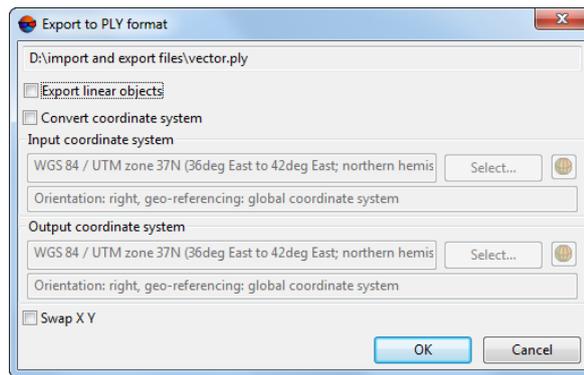


Fig. 191. Export to PLY format

2. [optional] In order to export just linear objects, set the **Export selected only** checkbox.
3. [optional] In order to define standard parameters set the **Swap X Y** and **Convert coordinate system** checkboxes on (see [Section 10.5](#)).



If the **Swap X Y** checkbox is set off, the vector objects will be exported in the right coordinate system. Otherwise, in the left one.

4. Click OK to complete the export operation.

14.12. Export to Shape

The system provides possibility of export to Shape format. This is exchange format with *.shp extension, that is used in *ArctInfo* system.

The Shape format consists of three files with the same names and following extensions:

- *.shp – main file, that contains information about objects; one *Shapefile* stores objects of the only one type – points, polylines or polygons;
- *.shx – additional index file, that contains information about objects position in the main file; it is used to speed up access to the content of the shape-file;
- *.dbf – additional file containing the table of DBF database (see [Section 13.14](#)).
- *.prj – additional file containing parameters of project projection.

In order to export vector objects to Shape format perform the following actions:

1. Select **Vectors** › **Export** › **Shape**. The **Export to Shape** window opens.

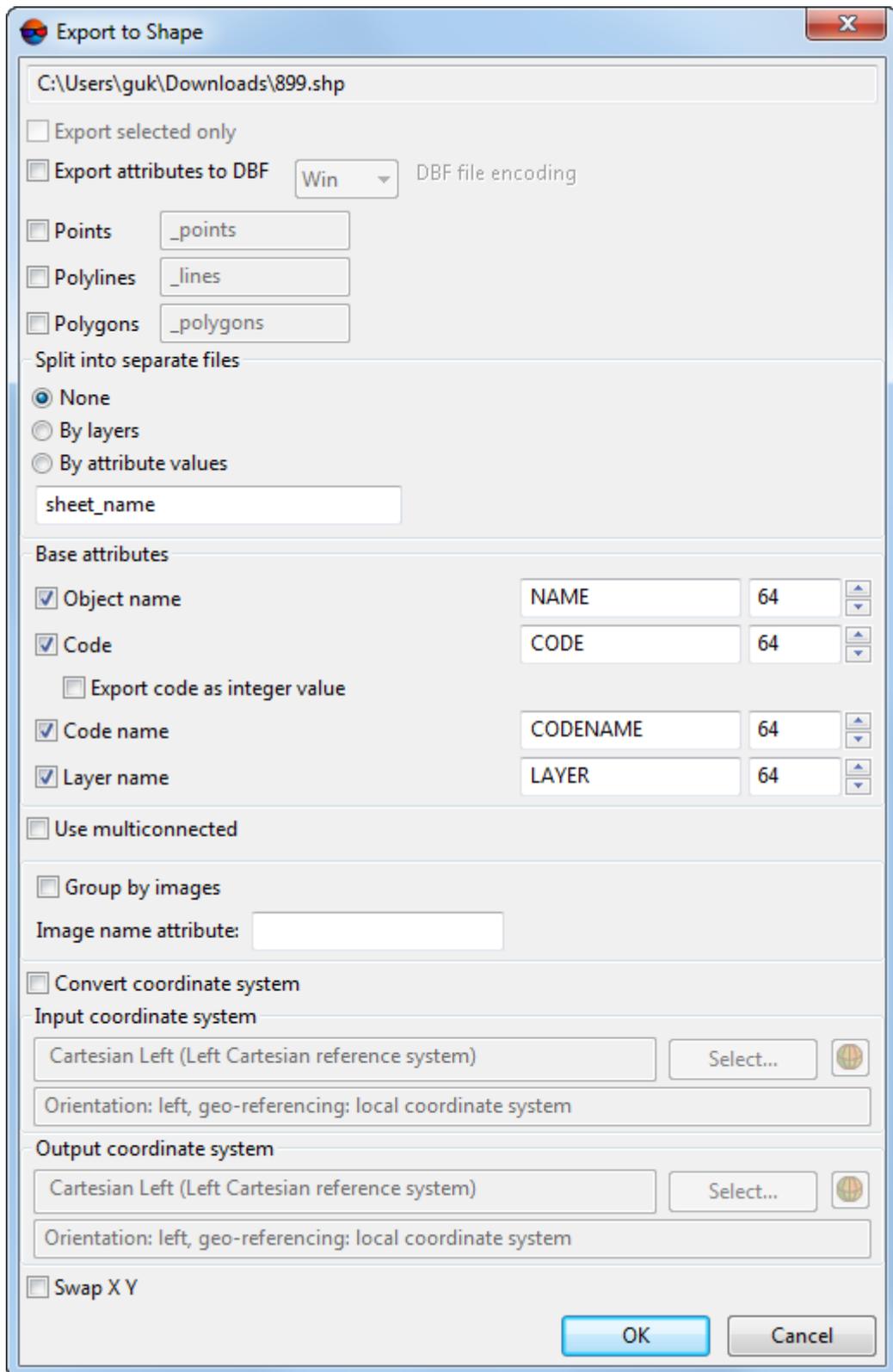


Fig. 192. Export to SHP format

2. Specify the following parameters of export:
 - **Export selected only** – allows to export only selected object from active layer;
 - **Export attributes to DBF** – allows to create file with with attribute information about objects, as well as for assigning vector objects to classifier.
3. Select object types for export: **Points**, **Polylines**, **Polygpns** and specify names of objects types.
4. In the **Split into separate files** section specify one of the ways of export to a separate file:
 - **No** – used to export all objects of one layer to a single file.
 - **By layers** – used to export each layer to separate file; each file receives the name of the corresponding layer;
 - **By attribute values** – used to export objects of opened layer by attribute value, which name is specified in this field.
5. [optional] To specify code names in classifier of the DBF file, in the **Base attributes** section the **Object name**, **Code**, **Code name**, and **Layer name** checkboxes are set on by default.



Attribute line has default length – 64 symbols. If it is necessary to display in *ArclInfo software* attributes with code with are not integer, set the **Export code as integer value** checkbox on.

6. [optional] In order to export splitting into sheets as separate objects (for example, to export separately polygons that correspond to images borders, and separately “gaps”), set the **Use multiconnected** checkbox on. To merge separate objects with the same attributes (for example, to group just “gaps”) set the **Group by images** checkbox on and input attribute name into the **Image name attribute:** field.
7. [optional] In order to define additional parameters set the **Swap X Y** and **Convert coordinate system** checkboxes on (see [Section 10.5](#)).



If the **Swap X Y** checkbox is set off, the vector objects will be exported in the right coordinate system. Otherwise, in the left one.

8. Click OK to complete the export operation.

14.13. Export to Panorama

The system provides possibility of TIN export to the Panorama format. This is exchange format with *.sit and *.map extensions, that is used in *GIS Map* system.

In order to export vector objects to Panorama format perform the following actions:

1. Select **Vectors** › **Export** › **Panorama**. The **Export to Panorama** window opens.

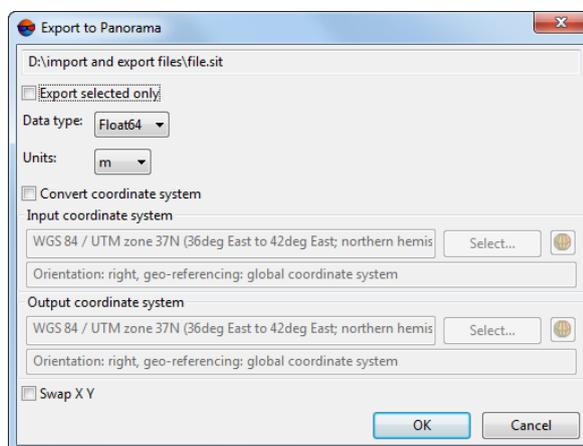


Fig. 193. Export to Panorama

2. [optional] In order to export just selected points, set the **Export selected only** checkbox.
3. [optional] To define standard parameters set the **Swap X Y** and **Transform reference system** checkboxes on (see [Section 10.5](#)).



If the **Swap X Y** checkbox is set off, the vector objects will be exported in the right coordinate system. Otherwise, in the left one.

4. Click OK. The **Creation of Panorama map** window opens.

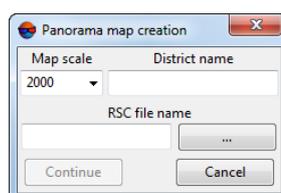


Fig. 194. Creation of Panorama map

5. Select in the list the **map scale** to create a map of particular scale (in a range from 2 000 to 1 000 000).
6. In the **District name** field input necessary name.
7. In the **Output file** section click the **...** button to choose classifier file (with *.rsc extension).

8. Click the **Continue** button to complete the export.

14.14. Batch export

The system provides possibility of batch vector objects export to separate files with the same extension.

To export multiple vector layers perform the following actions:

1. **Open** multiple vector layers.
2. Select **Vectors > Export > Batch export**. The **Batch object export** window opens.

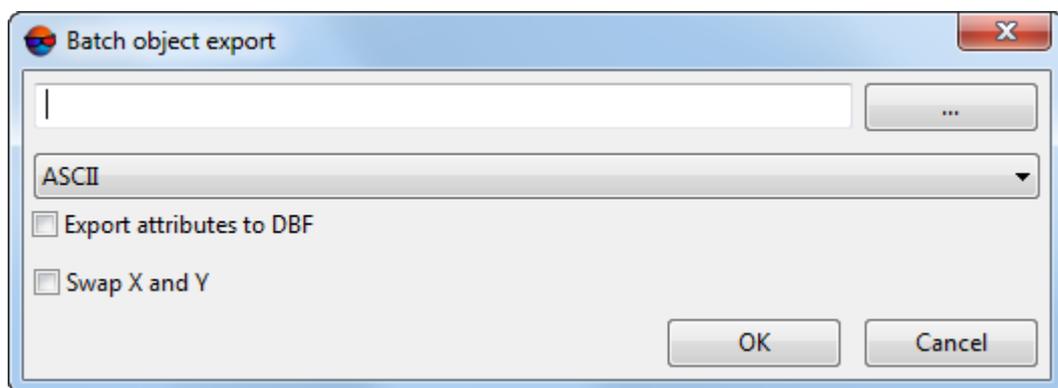


Fig. 195. Batch object export

3. Click the **...** button to choose destination folder for files export.
4. Choose one of the following formats from the list:
 - ASCII;
 - ASCII-A;
 - CSV;
 - DGN;
 - DXF;
 - Generate;
 - ATLAS KLT;
 - KML;
 - LIG;

- MIF/MID;
 - PLY;
 - Shape;
 - Panorama.
5. Set the export parameters, according to the chosen format.
 6. Click OK to export multiple vector objects to separate files with the same extension.

15. Generators of splitting into sheets

15.1. Standard orthomap sheet frames generator

The program provides possibility to split survey area for notation sheets of chosen scale, which consist of vector polygons.

Generators of splitting into sheets are used to:

- to split orthomaps into sheets by images;
- for further use in the *GeoMosaic* program;
- for contours sheets export.

Perform the following to split survey area to notation sheets of chosen scale:

1. Choose **Vectors** › **Create standard orthomap sheet frames**. The **Generate standard sheets** window opens.

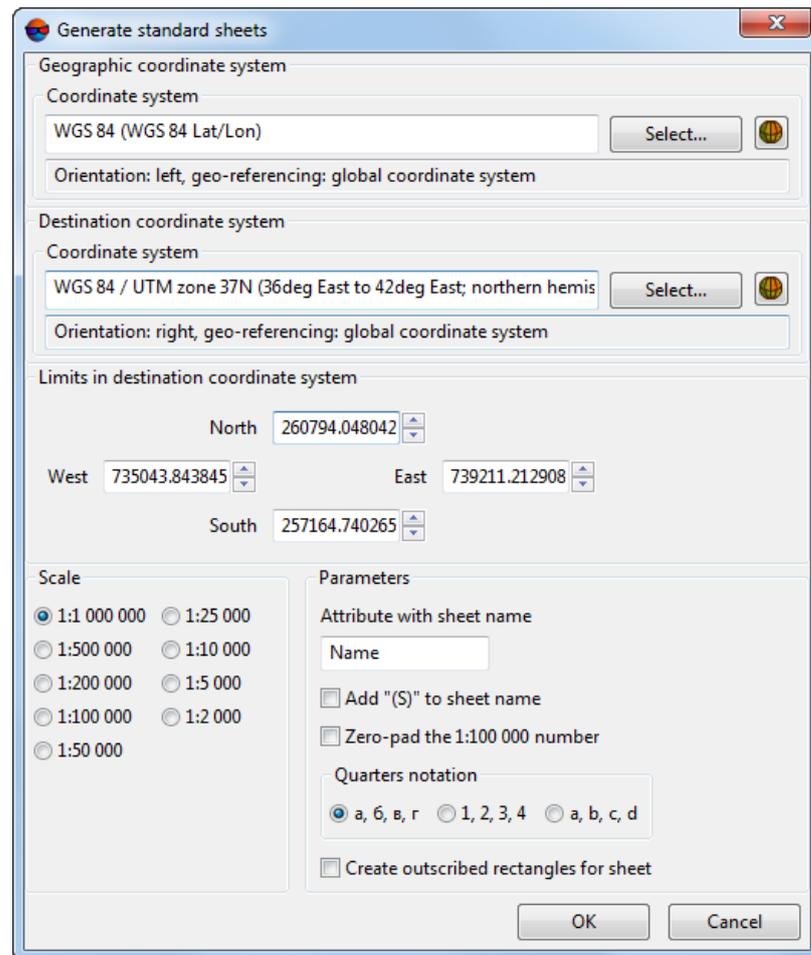


Fig. 196. Standard orthomap sheet frames generator parameters

2. In the **Geographic coordinate system** section choose the input coordinate system, which is used to specify splitting into sheets by latitude and longitude.
3. In the **Destination coordinate system** section choose the coordinate system to recalculate coordinate system of sheets during splitting into sheets (coordinate system of the project, for example).
4. In the **Limits in destination coordinate system** section are specified coordinates of area borders for splitting into sheets. To change area size input coordinates of corners in the **North**, **West**, **East**, **South** fields.



The program provides possibility to split survey area for predefined by user notation sheets of chosen scale.

5. Choose the scale of orthomap in the **Scale** section.
6. In the **Parameters** section define the following settings:

- **Attribute with sheet name** – allows to define the name of attribute to write the sheet names;
 - **Add “(S)” to sheet name** – allows to clarify map position, located in south hemisphere;
 - **Zero-pad the 1:100 000 number** – allows to add zeros before zone numbers to notation for lists of 1:100 000 scale;
 - **Quarters notation** – allows to choose type of quarters notation.
7. [optional] In case when 1:5 000 or 1:2 000 scale is chosen, set on the **Create outscribed rectangles for sheet** checkbox.
 8. Click OK. After that the system starts the splitting orthomaps into sheets with specified notation.

The figure below displays an example of splitting of the survey area on map sheets with the following data: orthophotomap scale – 1:200 000; geographic coordinate system – Latitude-Longitude Pulkovo 1942; target coordinate system – SK-42, Zone 6.

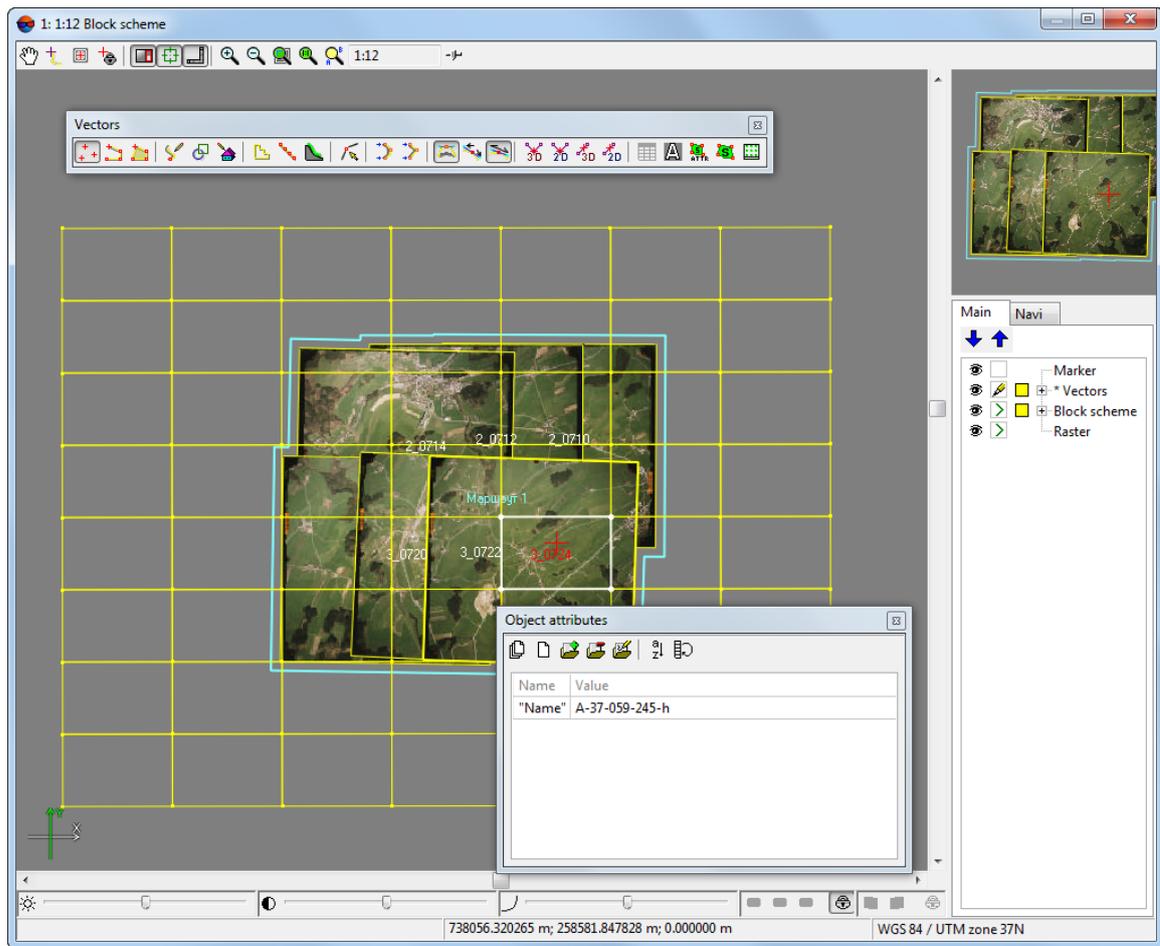


Fig. 197. Example of splitting orthomaps into sheets with specified notation

15.2. Custom orthomap sheet frames generator

Program provides possibility creating sheets from several orthomaps, merged by cutlines and created in local coordinate system.

Perform the following to split orthomaps by notation sheets in local coordinate system:

1. Choose **Vectors** > **Create custom orthomap sheet frames**. The **Generate arbitrary sheets** window opens.

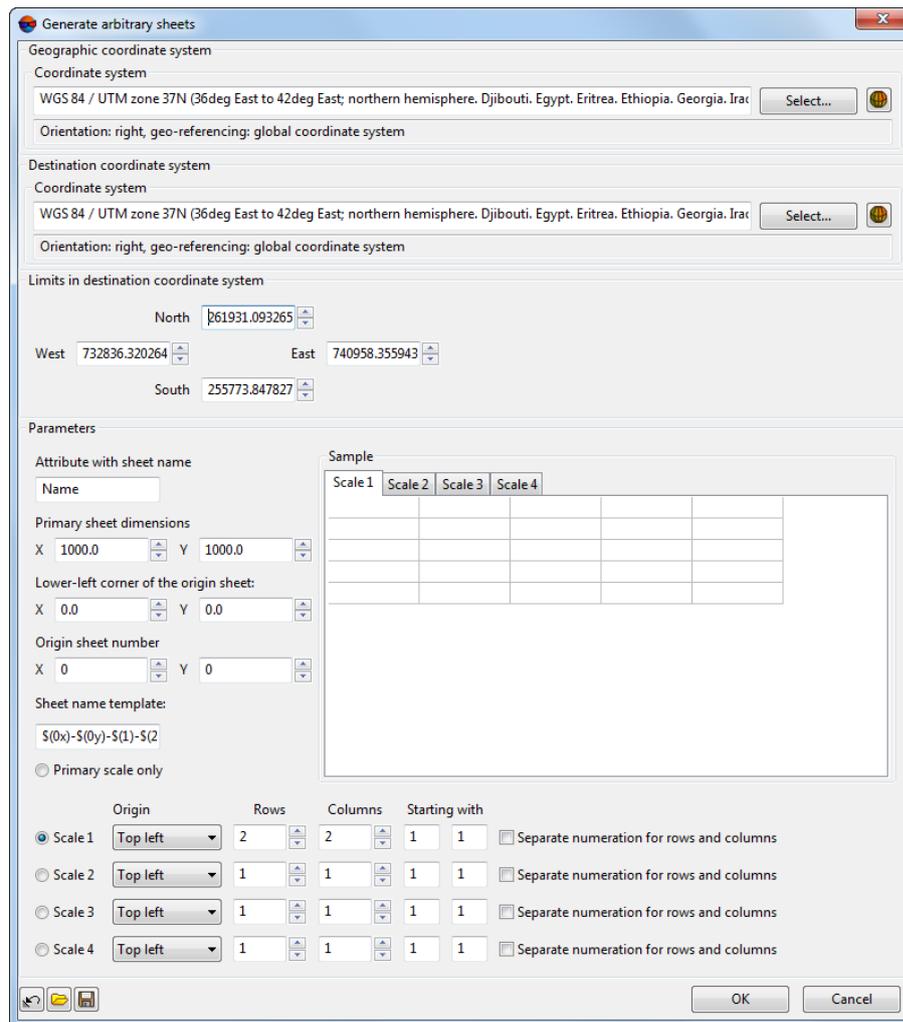


Fig. 198. Custom orthomap sheet frames generator parameters

The bottom toolbar of window contains the following buttons:

-  – allows to reset parameters to default;
-  – allows to load parameters from the file;
-  – allows to save parameters into a file.

2. In the **Geographic coordinate system** section choose the input coordinate system, which is used to specify splitting into sheets by latitude and longitude.
3. In the **Destination coordinate system** section choose the coordinate system to recalculate coordinate system of sheets during splitting into sheets (coordinate system of the project, for example).

4. In the **Limits in destination coordinate system** section are specified coordinates of area borders for splitting into sheets. To change area size input coordinates of corners in the **North, West, East, South** fields.
5. In the **Parameters** section specify the following parameters of primary scale sheet:



In case of using the custom orthomap sheet frames generator it is possible to use up to 5 levels of splitting orthomaps into sheets: primary and 4 additional scales. Each next level is created by splitting the previous level.

- **Attribute with sheet name** – allows to define the name of attribute to write the sheet names;
- **Primary sheet dimension** – the primary scale sheet size;
- **Lower-left corner of the origin sheet** – allows to set coordinates of the origin sheet;



Choose the reference point lower and left from work area.



The coordinates of origins of the others sheets are calculated based on this information.

- **Origin sheet number** – allows to input a number of sheet that starts numeration;
- **Sheet name template** – displays the template by which sheet names are created. By default, $\$(0x) - \$(0y) - \$(1) - \$(2) - \$(3) - \(4) , where
 - $\$(0x)$ – number by X on primary scale;
 - $\$(0y)$ – number by Y on primary scale;
 - $\$(1)$, $\$(2)$, $\$(3)$, $\$(4)$ – number on the first and next levels in case if the **Separate numeration for rows and columns** checkbox is set off;
 - $\$(1x)$ – number by X in case if the **Separate numeration for rows and columns** checkbox is set on;
 - $\$(1y)$ – number by Y in case if the **Separate numeration for rows and columns** checkbox is set on;

Notation adds as attribute of each sheet.



If template does not correspond to selected number of splitting levels, attributes are created incorrectly correct.

6. [optional] To use only one base list choose **Primary scale only** and click OK. Otherwise move to the 7 step.
7. In the **Parameters** section specify the following parameters of primary scale sheet:
 1. Choose number of additional levels of splitting: **Scale 1, Scale 2, Scale 3, Scale 4.**
 2. Select origin of sheets of additional level in the **Origin** list.
 3. Define number of **Rows** and **Columns** for each level.
 4. Define arbitrary symbol (letter or number) as a start sheet number in the **Starting with** field.



Notation with all types, except using Roman numerals, could be created.



All changes of parameters are shown in the **Sample** table.

8. Click OK. After that the system starts the splitting orthomaps into sheets with specified notation. New vector layer creates. Sheets are displayed in 2D-window.

15.3. Standard orthomap sheet frames importer

The program provides possibility to split survey area for predefined by user notation sheets of chosen scale, which consist of vector polygons. The names of notation sheets are specified in input CSV-file with *.csv or *.txt extension.



The program provides possibility to split survey area for notation sheets of chosen scale, [by setting the coordinates of area borders for splitting into sheets.](#)

An input CSV-file must meet the following requirements:

- Names of notation sheets in input *.csv or *.txt files must be sequentially rowwise arranged. Field delimiter symbols as **comma, space, tab, semicolon** or **other** are not applicable;
- An input CSV-file must contain names of notation sheets of only one scale;
- Names of notation sheets in the input CSV-file must contain a unified **Quarters notation**;

- All names of notation sheets in the input CSV-file must have either only standard or only numeric form;
- The input CSV-file must contain the names of notation sheets located in one hemisphere.

Perform the following to split survey area to predefined notation sheets of chosen scale:

1. Choose **Vectors** > **Import standard orthomap sheet frames**. The **Import standard sheets** window opens.

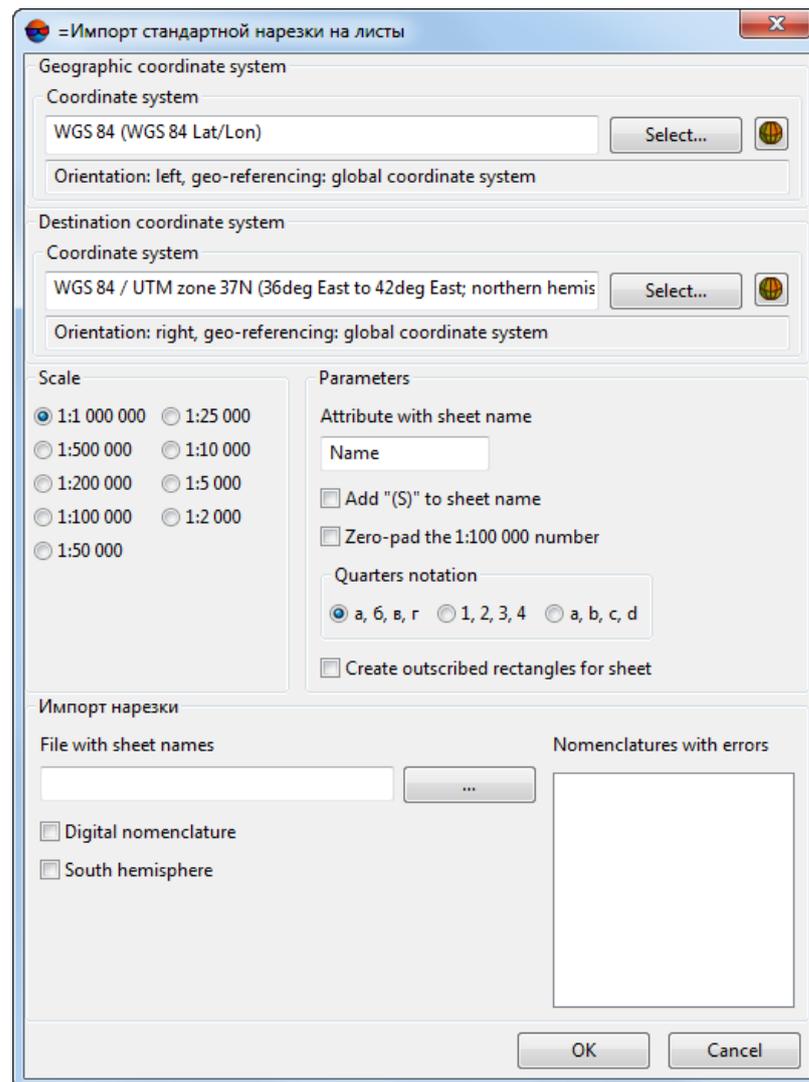


Fig. 199. Standard orthomap sheet frames import parameters

2. In the **Geographic coordinate system** section choose the input coordinate system, which is used to specify splitting into sheets by latitude and longitude.

3. In the **Destination coordinate system** section choose the coordinate system to recalculate coordinate system of sheets during splitting into sheets (coordinate system of the project, for example).
4. In the **Scale** section choose the scale of notation sheets, which names will be imported.



An input CSV-file must contain the names of notation sheets of the same **scale** which matches the selected one;

5. In the **Parameters** section define the following settings:
 - **Attribute with sheet name** – allows to define the name of attribute to write the sheet names;
 - **Add “(S)” to sheet name** – allows to clarify map position, located in south hemisphere;
 - **Zero-pad the 1:100 000 number** – allows to add zeros before zone numbers to notation for lists of 1:100 000 scale;
 - **Quarters notation** – allows to choose type of quarters notation.



The names of notation sheets in the input CSV-file must contain a unified **Quarters notation** which matches the selected one;

6. [optional] In case when 1:5 000 or 1:2 000 scale is chosen, set on the **Create outscribed rectangles for sheet** checkbox;
7. In the **Импорт нарезки** section click the button, to select input CSV-file with **sheet names** with *.csv or *.txt extension;



Names of notation sheets in input *.csv or *.txt files are sequentially rowwise arranged. Field delimiter symbols as **comma**, **space**, **tab**, **semicolon** or **other** are not applicable.

8. [optional] In case when notation sheets have solely numeric names, set on the **Digital nomenclature** checkbox;



All names of notation sheets in the input CSV-file must have either standard or numeric form.



In numeric form of notation sheets names, each letter denoting zones is replaced by double figures. These figures correspond to the counting number of the zone (or the letter in the Latin alphabet). For example, A — 01, B — 02, C — 03, D — 04, E — 05, and F — 06. The numeric notation of a sheet of 1:1 000 000 K-38 map will be 11-38. Each sheet of 1:200 000 map is denoted by a double figure from 01 to 36, and 1:100 000 map is denoted

by three figures from 001 to 144. Letters in 1:500 000, 1:50 000, and 1:25 000 map sheet notations are replaced by the figures 1, 2, 3, and 4, respectively.

Table 14. Numeric form of notation sheets names for 1:1 000 000 - 1:25 000 scales

Map scale	Standard notations	Numeric notations
1:1 000 000	K-38	11-38
1:500 000	K-38-Б	11-38-2
1:200 000	K-38-XXXVI	11-38-36
1:100 000	K-38-99	11-38-099
1:50 000	K-38-99-B	11-38-099-3
1:25 000	K-38-99-B-Г	11-38-099-3-4

9. [optional] In case when notation sheets are located in southern hemisphere, set on the **South hemisphere** checkbox;



An input CSV-file must contain the names of notation sheets located in one hemisphere.

10. Click OK. After that the system starts the splitting orthomaps into sheets with specified notation.

If errors are detected in the input CSV-file, the operation fails. An information message showing the number of detected errors appears. The names of notation sheets with errors are displayed in the **Names with errors** field.

16. ArcSync. Synchronized vector edition

16.1. The main window of ArcSync

The **ArcSync: Synchronize to ArcInfo map** window is used to terrain objects vectorization at the same time in the PHOTOMOD system and in third-party software.

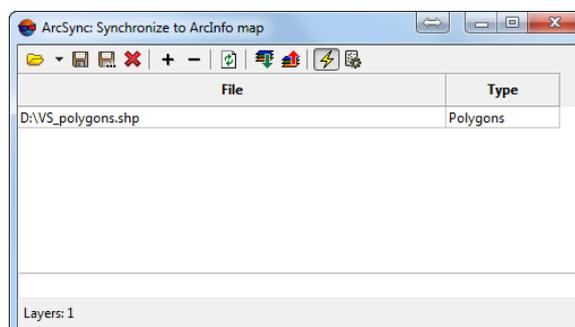


Fig. 200. The main window of ArcSync

List of synchronization files is a table. File path is displayed in the **File** column. In the **Type** column is displayed type of object chosen in layer export (points, polylines or polygons).

The **ArcSync: Synchronize to ArcInfo map** window toolbar contains the following buttons:

-  – allows to open created ArcSync map;
-  – allows to save vector layers as ArcSync map;
-  – allows to save vector layers as ArcSync map using unique name;
-  – allows to close ArcSync map or added layers;
-  – allows to add vector layer in the table;
-  – allows to remove vector layer from the table;
-  – allows to synchronize maps manually;
-  – allows to import opened layer into 2D-window;
-  – allows to save opened layers in a Shape-file;
-  – allows to enable auto synchronization mode;
-  – allows to setup auto synchronization parameters.

16.2. Workflow

To terrain objects vectorization at the same time in the PHOTOMOD system and in third-party software is used the *ArcSync module*.

To Shape-files in Windows during simultaneously vector editing in PHOTOMOD and/or another program, changes add to files gradually. It is not required to save files again after editing.

It is recommended to create Shape-files in the third-party software or export vectors from PHOTOMOD.

To terrain objects vectorization at the same time in the PHOTOMOD system and in third-party software perform the following:

1. [optional] [Export vector layer to Shape-file.](#)



During export polygons to a Shape format it is strongly recommended to set on all check-boxes **Export attributes to DBF** and **Polygons/Polylines/Points**.

- Choose **Vectors** › **Import** › **Shape** in the system and import a vector layer. Imported layer displays in 2D-window.



If DBF file was created during export, set the **Use DBF-file** checkbox on.

- Choose **Vectors** › **ArcSync** › **Map settings window** or click the  button of the **ArcSync** toolbar. The **ArcSync: Synchronize to ArcInfo map** window opens.



Fig. 201. The main window of ArcSync

- Click the **+** button. The **Add files** window opens. Choose Shape file and click the **Open** button. The file adds to the table.

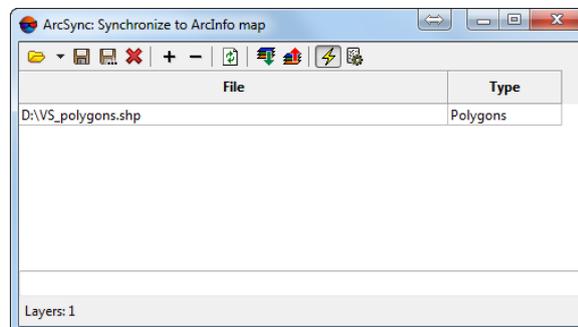


Fig. 202. Adding file in the table

- Open second program and load the same vector file in it.

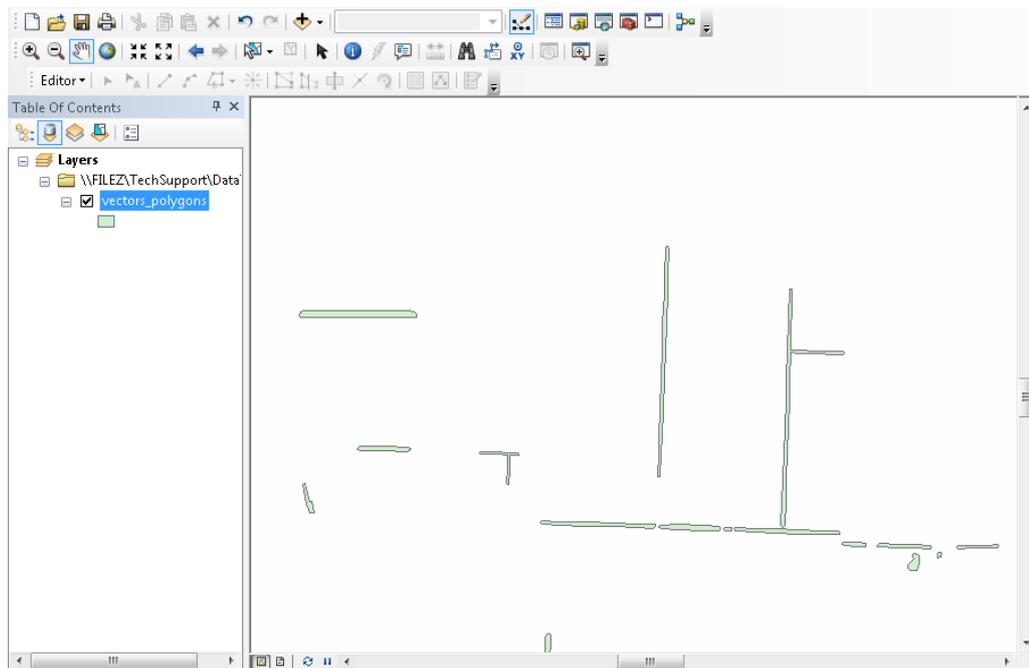


Fig. 203. Vector layer in the third party program

6. In the **ArcSync: Synchronize to ArcInfo map** window click the  button. The **Settings** window opens.

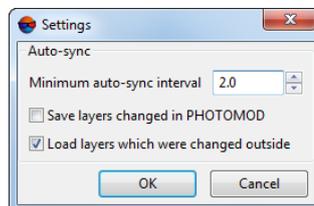


Fig. 204. Synchronization parameters

7. Define the **Minimum auto-sync interval** in seconds.
8. Set on one or more checkboxes:
 - **Save layers changed in PHOTOMOD** – changes made in PHOTOMOD are shown in the third-party program;
 - **Load layers which were changed outside** – changes made in the third-party program are shown in PHOTOMOD 2D-window.
9. Click OK to save parameters.
10. Click the  button. Auto-sync mode enables.

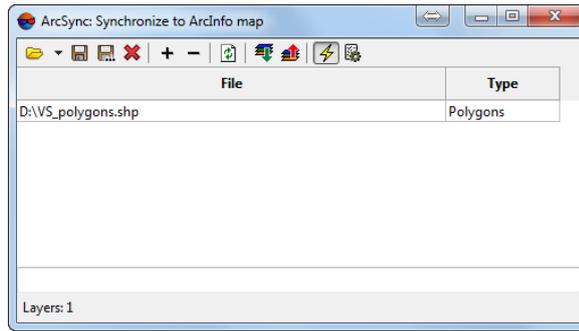


Fig. 205. Auto-sync mode is enabled

11. Change vector layer in the system.

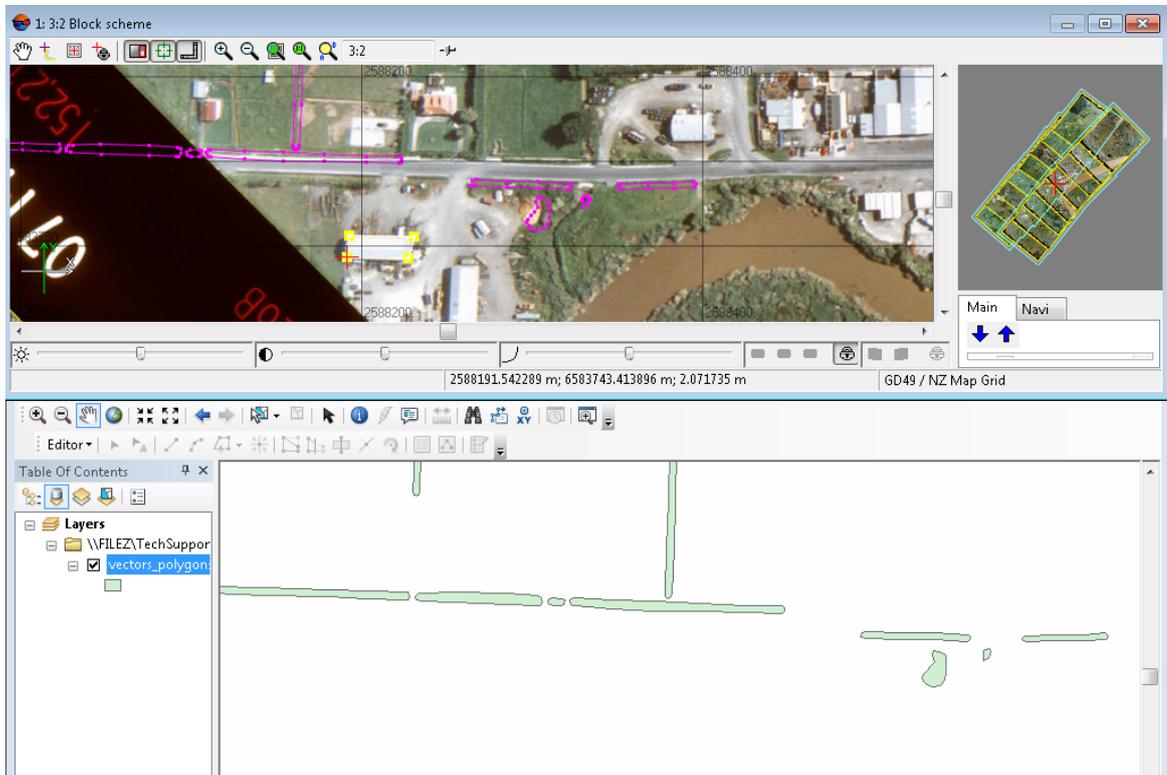


Fig. 206. Changes on vector layer in the system

12. In the other program click the **Refresh** button. As a result, changes display in this program.

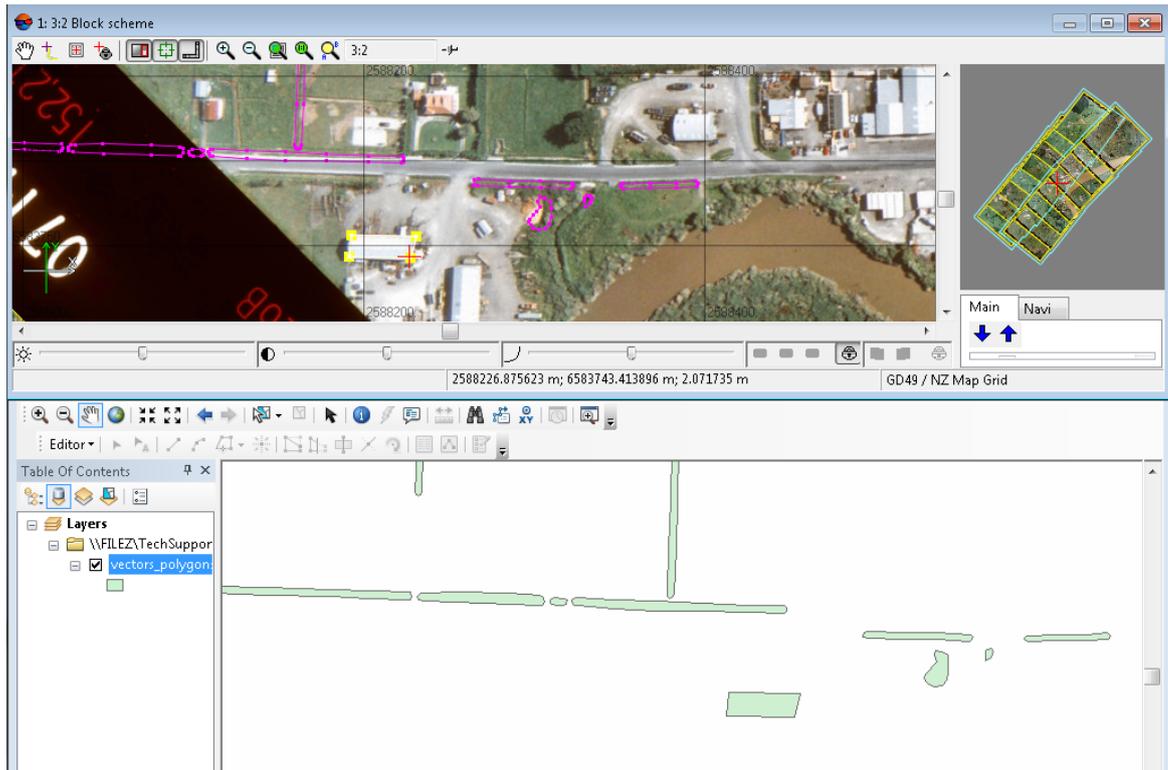


Fig. 207. Changes displaying in the third-party program

13. To save changes in file, in the **ArcSync: Synchronize to ArcInfo map** window click the  button.
14. To save changes in Shape-file of ArcSync format, in the **ArcSync: Synchronize to ArcInfo map** window click the  button and input filename.