Digital Photogrammetric System



Version 8.0

# **USER MANUAL**

# Processing of UAS data (Windows x64)



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# 1. About

# **1.1. Purpose of the document**

This document contains detailed information about UAS data processing in the *PHO-TOMOD UAS* program. The document contains recommendations of processing order, program properties to obtain the best results, and also contains description of additional possibilities when working with UAS data.

# **1.2. Brief description of system features**

The *PHOTOMOD UAS* program is purposed to process data from unmanned aircraft system (UAS). There is a limit on using of the source data when working with program.



Only central projection images with size not more than 100 Mpix could be used a source data.

The following definitions for UAS projects processing are provided in the program:

- preliminary preparing of source images;
- images interior orientation;
- relative orientation of images;
- input and measurement of GCP coordinates;
- Images exterior orientation;
- vectorization;
- stereovectorization;
- building DEM;
- creating orthomosaic;
- creating digital map;
- creating 3d-models.

# 1.3. Technical Support

The Racurs company technical support provides the actual information about system functionality, characteristics, price and services.

For technical support use one of the following ways:

- e-mail: support@racurs.ru;
- phone: +7 (495) 720-5127;
- mail: RACURS Co., UI. Yaroslavskaya, 13-A, office 15, Moscow, Russia;

#### 1.4. Distribution kit

The *PHOTOMOD UAS* program is a stand-alone software, which does not require the *PHOTOMOD* system installation. Also the program could be launched as a module of the *PHOTOMOD* system.

The hardware and software *PHOTOMOD* system requirements are given in detail in "System requirements" in the "General information" User Manual in the main *PHOTO-MOD* documentation set.

License software distribute in a branded box.

The company name is place on the front. On the reverse side are placed address, technical support service phone and e-mail, web-site of company.

The system distribution kit includes:

- CD-ROM containing the system setup files and the documentation files in PDF format;
- 'System installation and configuration Manual;
- Unique hardware lock key (see "Protection of the system" chapter of "General information" User Manual).

# 2. System installation

Prior to the system installation it is desirable to insert *Sentinel HL* security key into the USB-socket of the workstation.

The system requires 2 GB of free hard disk space.

To start the system installation, launch the setup.exe file or input the installation software and launch the autorun.exe file.

The **PHOTOMOD** window opens.



Fig. 1. PHOTOMOD installation window

Click Install > PHOTOMOD UAS. The Installation PHOTOMOD 8 UAS window opens.

The system initial installation process consists of a sequence of steps with instructions.



In case of cancel at any step, installed program files and data are not removed. To complete the system installation, restart the autorun.exe or setup.exe file and go through all steps again.

# 2.1. Preparation step



It is strongly not recommended to install the system in folder with name, which contains letters, different from Latin. By default for the *C*:\*Program Files*\*PHOTOMOD\_8\_UAS\_x64* folder is used.

1. Choose the installer language. Click OK;



2. Read the welcome and warning messages. Click the **Next** button.



3. Read the license agreement. If you agree with it, set the **I accept the terms in the License Agreement** checkbox on and click the **Next** button.

S PHOTOMOD UAS 8 x64 Setup			
RACURS 1994 – 2024 License Agreement Please review the license terms before installing PHOTOMOD UAS 8 x64.			
Press Page Down to see the rest of the agreement.			
Please read this End User License Agreement (public offer) carefully before purchasing and using the "PHOTOMOD" software.			
"PHOTOMOD" SOFTWARE END USER LICENSE AGREEMENT			
If you accept the terms of the agreement, click the check box below. You must accept the agreement to install PHOTOMOD UAS 8 x64. Click Next to continue.			
I accept the terms of the License Agreement			
PHOTOMOD UAS 8,0,4563 x64			
< Back Next > Cancel			

4. Define the folder to install the program files of the system. Click the Next button.

PHOTOMOD UAS 8 x64	Setup
RACURS 1994 - 2024	Choose Install Location Choose the folder in which to install PHOTOMOD UAS 8 x64.
	DD UAS 8 x64 in the following folder. To install in a different folder, other folder. Click Next to continue.
Destination Folder	TOMOD_8_UAS_x64 Browse
Space required: 1.9 GB Space available: 100.4 GB	
PHOTOMOD UAS 8.0.4563 x6	4 < Back Next > Cancel

 Enter a folder name for the PHOTOMOD programs and modules in the Windows Start menu. A shortcuts in the Windows Start menu will be created by default. Otherwise – clear the appropriate checkbox. Click the Install button.

🛞 рнотс	MOD UAS 8 x64	Setup		Ľ	
	RACURS	Choose Start Choose a Start shortcuts.	<b>Menu Folder</b> Menu folder for the P	PHOTOMOD UA:	S 8 x64
can also	o enter a name to c		uld like to create the	program's short	cuts. You
7-Zip Access Admini: AIMP3 Compu Compu CorelD Cygwir	strative Tools iteGridStep iteSevenParams RAW Graphics Suite	≥ X3			* III
Dr.Exp ENVI 4 EPSON	l.5 I Scan				~
	not create shortcut: D UAS 8.0,4563 x6				
			< Back	Install	Cancel

# 2.2. File copy stage

1. Wait until the installation is complete;

PHOTOMOD UAS 8 x64 Setup		
RACURS 1994 - 2024	Installing Please wait while PHOTOMOD UAS 8 x64 is being installed.	
Extract: BaseFoModData.	dl	
Show details		
Show details		
PHOTOMOD UAS 8.0.4563 x6	i4	
	< Back Next > Cancel	

2. When installation complete perform one of the following actions:



- [optional] clear the **Start PHOTOMOD 8 UAS x64** checkbox and click the **Finish** button to complete the installation process without program launch;
- [optional] leave the **Start PHOTOMOD 8 UAS x64** checkbox set and click the **Finish** button to proceed to the system configuration stage.



The **Create shortcuts on Windows desktop** checkbox is set on by default. Clear it if needed.



If the **Start PHOTOMOD 8 UAS x64** checkbox is set, the *PHOTOMOD UAS* program will launch automatically.

If the security key or security key drivers (they must be installed automatically during the program installation) were not found, the error message displays.

Make sure that the *Sentinel HL* security key is inserted into the USB-socket of the workstation. Install the security key drivers manually and restart the system.

In case of problems contact the Racurs company technical support service (see Section 1.3).

# 2.3. System configuration stage

During the first launch of the system, the message about the required detailed configuration appears. The initial setup of the program can be performed in various ways, depending on the circumstances of the system installation on a particular workstation. The most common situations are the following:

- The system was installed on this workstation for the first time. The user needs to create a folder for storing settings, a resource system, and profiles for organizing local and/or network work. This procedure will be discussed in detail below in this chapter.
- If other *Racurs* software products (*PHOTOMOD*, *PHOTOMOD Conveyor*) are already installed and configured on the workstation, the user can quickly connect the installed program to existing profiles and resource systems.

If the connection did not occur automatically during the first launch of the installed program, then in the **Initial setup** window that opens (see below), an already existing **settings folder** used by previously installed software products is indicated;

 The system is installed and configured on several workstations connected to each other via a local network. A new computer is added to the local network where this program was installed for the first time. Connecting such a workstation to an existing network profile is described in "Connecting to existing network profiles" chapter of "General information" User Manual.

#### 2.3.1. Fast system configuration

During the first launch of the system the *PHOTOMOD UAS* initial (fast) setup windows are opened.



If other *Racurs* software products (*PHOTOMOD*, *PHOTOMOD Conveyor*) are already installed and configured on the workstation, the user can quickly connect the installed program to existing profiles and resource systems. To do this choose the already existing **settings folder** used by previously installed software products in **PHOTOMOD initial setup** window.

To minimize the process of the program quick setup and go to the **PHOTOMOD initial setup** window (as part of the standard setup of the program), close the quick setup window (or click **Cancel**).

1. Click the <u>\_\_\_\_</u> button to select a physical folder on a local PC to store *resources* of the *PHOTOMOD UAS* projects (see the "Main definitions of resources system" chapter of the "General information" User Manual). Click OK.



It's impossible to use logical disk root folder.



Resources can take up a significant amount of free space on hard drive.

😍 Initial setup	×
Select data storage directory	
C:\Users\guk\Documents\AutoUAS	
	OK Cancel

Fig. 2. Choosing a folder to store the projects (an intermediate data)

2. In the **Settings folder** field is displayed path to the *PHOTOMODUAS8.VAR* folder, that is used to store configuration files. Click the <u>\_\_\_\_</u> button to change path to configuration folder or click OK to finish fast system configuration and create the *local profile* automatically (see the "Creating local profile" chapter of the "General information" User Manual).

👽 Initial setup	×
Settings folder	
C:\PHOTOMODUAS8.VAR\	
	OK Cancel

Fig. 3. Choosing a folder to store the configuration files

The *Control Panel* module is used to configure detailed system settings during the further work. More details about program resources, recommendations on organizing of local or network work, and about creating profiles and virtual folders connecting see the "Control Panel. Profiles management" chapter of the "General information" User Manual.

#### 2.3.2. Advanced system configuration

If the existing folder for data storage (or configuration files folder) are not specified during the fast system setup, the message about the required detailed configuration appears. To do this, perform the following:

1. Click OK.



Fig. 4. Information message

2. The PHOTOMOD initial setup window opens:

Initial setup
Settings folder
C:\PHOTOMODUAS8.VAR\
For all users on this computer Only for me
Centralized profile management
🔲 Use
Centralized management folder
Manage network profiles
OK Cancel

Fig. 5. The PHOTOMOD initial setup window

In the **Settings folder** section is displayed path to the *PHOTOMODUAS8.VAR* folder, that is used to store configuration and temp files. Click the \_\_\_\_\_ button to change path to configuration folder.

If other *Racurs* software products (*PHOTOMOD*, *PHOTOMOD Conveyor*) are already installed and configured on the workstation, the system provides for connecting the program to existing profiles and resource systems.

For this, the **settings folder** is to be specified which is used by these software products. In this case, the user will not be required to perform the steps described below to create a new local profile.



Choose **For all users on this computer** to use one configuration folder for all users of current workstation, otherwise choose **Only for me**.

In the **Centralized management folder** section set the **Use** checkbox on and define a folder.



Creation of a *local profile* is described in this Chapter. *Network profiles* management is described in "Creating network profile" chapter of the "General information" User Manual.

3. An info that at least one *local profile* must be created appears:

C	iontrol Panel	X
ſ	Profile Resources Service Help	
	Profiles	Resource tree
	Profile Free	Node Path Free
	<u> </u>	X
	Information	
	At least or	one profile must be created
		ОК
	Managing network profile is available only in network profiles manager	ement mode Manage network profiles
		OK Apply Close

Fig. 6. Information message

Нажмите ОК.

4. Specify a *local profile* name:

Input new profile name	9	x
New profile		
Local profile 1		
ОК	Can	icel

Fig. 7. Local profile name setup

Click OK.

5. Input a virtual folder name – arbitrary text is used to identify data in folder.

Connect virtual folder	×
Virtual folder name	
Folder	
	OK Cancel

Fig. 8. Connect virtual folder

In the Folder section choose a physical space for connecting as a virtual folder:

choose Folder to use only one *network or local* physical folder click the <u>button</u> button and choose a folder;



It's impossible to use logical disk root folder.



To connect folder only read access for this folder is required.



Local profile folder could be placed both on a workstation, where the system runs, and on any workstation of the network.

• [optional] choose **Storage group** to use several local or network folders as virtual.



The use of a group of storages is described in detail in "Storages" chapter of the "General information" User Manual.

Click OK.

#### 2.4. System deinstallation

To remove the system from computer, close all modules of the system and choose **Start > Programs > PHOTOMOD 8 UAS x64 > Uninstall PHOTOMOD UAS x64** or use standard tools in **Control panel** of *Windows* operation system.

# 3. Interface and its elements

#### 3.1. Work area interface



Fig. 9. The main program's window

The GUI contains the following elements:

- title with name of opened project (A);
- the main menu bar (B);
- the Aerial Triangulation, Compute DEM and Compute Orthophoto tabs (*P*). The tabs layout and content displays the main steps of UAS data processing workflow;
- the main toolbar is used for quick access to main program functions (C);
- the optional toolbars is used for quick miscellaneous program functions access (O);
  - The system interface is flexible for customizing the locations of additional toolbars according to the user's needs. Additional toolbars can either be fixed in designated sections of the work area (top or bottom, right or left) or undocked by the user and placed in any place in the 2D window.

Depending on the user-set interface configuration, docked additional toolbars can be partly minimized (some buttons will be hidden). Docked (optionally minimized) subtoolbars are displayed as one line, vertical or horizontal, depending on their location.

By default, additional toolbars are docked at the top of the workspace, to the right of the main toolbar. Additional toolbars are marked with a special icon  $\square$  located on the left or top (depending on the location) edge of the panel. To maximize the toolbar, click  $\gg$  ( $\bigotimes$ ) on the right (at the bottom).

Undocked additional toolbars are always displayed horizontally, in one line, in a fully maximized form. To undock a toolbar (or pinpoint it in any place), move the cursor over the **in** icon and, holding down the **left mouse button**, drag the toolbar to the area of its targeted location (the cursor's shape changes ()) when it is possible to capture the toolbar).

- the 2D-window, used for data displaying, contains the following elements:
  - $\circ$  the toolbar is used for the 2D-window modes managing (*D*);
  - the work area is used for viewing and processing with loaded data of project (N);
  - the navigation bar is used for fast moving on the specified block images area of project (*E*);



To do this, click on the chosen point in **Navigation bar**. To set the layers visibility, move to the **Navi** tab in the *layer manager*.

- the *Layer manager* is used for managing of project layers (*F*);
- the axes direction of project coordinate system (M);
- the status bar is used for viewing current real (ground) and pixel marker coordinates and brightness, contrast and gamma data adjustment in the work area (G, K, L);



- RGB brightness values are displayed to the right of the current marker coordinates. When placing the marker within the work area, the following brightness values are displayed: R=128 G=128 B=128.
- scroll bar in 2D-window (*H*);
- the **Status** bar, near the current marker coordinates (*K*), displaying messages of error or success (e.g., after marker was not successfully placed to ground with correlator Bad point: correlation error).

#### 3.2. The main toolbar

The main toolbar is used for quick access to main program functions and also contains **Aerial Triangulation**, **Compute DEM** and **Compute Orthophoto** tabs. The tabs layout and content displays the main steps of UAS data processing workflow;

Buttons	Function
5	to open block editor window (see the "Project creation" User Manual)
¢)	to reload project to display the last saved version of project
¥E	to perform import of exterior orientation from metadata
翻	to open block layout window (see the "Aerial triangulation" User Manual)
	to open block editor window (see the "Project creation" User Manual)
8	to display all images, loaded to project, in the <b>Block scheme</b> window
2	to display only selected on scheme images in the <b>Block scheme</b> window
*** **	to load triangulation points
	to open 2D-window for selected stereopair (see the "Vectorization" User Manual)
<b>X</b>	to launch the <i>DustCorrect module</i> to edit MS-TIFF images (see the "Project creation" User Manual)
4	to run the <i>GIS Panorama Mini</i> (this software is not included with the <i>PHOTOMOD</i> but can be installed separately)
<b>E</b>	to launch the 3D-mod module
	to create, open and save regular nodes grid (see the "Create DTM" User Manual)
1	to load vector file into the project (see the "Vectorization" User Manual)
1	to load DEM file
	to load georeferenced raster image to project as a layer
	to load web-map
5	to undo the last action (see the "General system's parameters" User Manual)
	to display the list of last actions (see the "General information about system" User Manual)
2	to redo the last undone action (see the "General system's parameters" User Manual)
0,0	to open the <b>Marker</b> window (see the menu description in "Vectorization" User Manual)
10,0	to open the <b>Measurements</b> window (see the menu description in "Vectorization" User Manual)
	to arrange 2D-windows evenly
Ē	to stack 2D-windows
¢®	to refresh all opened 2D-windows
×	to close all 2D-windows
	to open the general program parameters window (see the "General system's parameters" User Manual)

Table 1. Brief	description o	f main too	lbar
----------------	---------------	------------	------

😌 Question	<b>—</b>	
Panorama executable file not found Use following link in order to dowload Panorama software KB Panorama		
Edit path to executable file in settings?		
Yes No		

If the *GIS Panorama* executable file is not found, an appropriate system message will appear. The software description and URL hyperlink (for download) are indicated in this message. Click **Yes** to go to path settings (see the "Paths settings" chapter of the "General system's parameters" User Manual.

Buttons	Function
🔁 From files	is used for adding image files, locating in the re- sources out of active profile, to the selected strip (see the "Adding images from files" chapter of the "Creating project" User Manual)
From resources	is used for adding image files, locating in the re- sources of active profile, to the selected strip (see the "Adding images from resources" chapter of the "Creating project" User Manual)
🔛 Import from metadata	to perform import of exterior orientation and interior orientation parameters from metadata (see the "Import orientation from metadata" chapter of the "Aerial triangulation" User Manual)
🚳 Cameras	to input/edit parameters of project cameras, and also to assign cameras to project images (see the "Images interior orientation" chapter of the "Aerial triangulation" User Manual)
import from file	to perform import of exterior orientation data from file of text format (see the "Import of exterior orient- ation parameters" chapter of the "Aerial triangula- tion" User Manual)
Exterior orientation data list	to open exterior orientation data list (see the "List of exterior orientation parameters" chapter of the "Aerial triangulation" User Manual)
sure tie points 🖗	to setup and start automatic tie points measurement using UAS data (see the "Automatic measurement of tie points coordinates (aerial survey)" chapter of "Aerial triangulation" User Manual)
💏 Tie points list	to open <b>tie points list</b> (see the "The "Triangulation points" window" chapter of the "Aerial triangulation" User Manual)
import catalog	to perform import of ground control points from *.txt and *.csv files (see the "Import of GCP catalogue" chapter of "Aerial triangulation" User Manual)
GCP list	to open <b>GCP list</b> (see the "GCP list" chapter of the "Aerial triangulation" User Manual)
Block adjustment	to open the <b>adjustment</b> toolbar (see the "Block ad- justment" User Manual)
Direct georeferencing	to perform adjustment using imported exterior orient- ation parameters (see the "Aerial triangulation" and "Block adjustment" User Manuals)

Table 2. Brief description of the Triangulation tab of the main toolbar

Buttons	Function
Compute points	to start automatic points calculation (see the "Points automatic calculating" chapter of "DTM Generation" User Manual)
dildings and vegetation filter	to launch the buildings and vegetation filter <i>for points</i> (see the "Buildings and vegetation filter" chapter of "DTM Generation" User Manual)
📉 Build TIN	to build TIN by points and breaklines ( <b>Ctrl+N, T</b> , see the "Building TIN" chapter of "DTM Generation" User Manual)
🛃 Build from TIN	to build DEM by loaded TIN ( <b>Ctrl+N, D</b> , see the "DEM creation by TIN" chapter of "DTM Generation" User Manual)
Build contours	to create contour lines by DEM (see the "" chapter of "DTM Generation" User Manual)
Sense model	to build dense DEM using SGM method (see the "Dense DEM generation using SGM method" chapter of "DTM Generation" User Manual)
Slope based filter	to launch the buildings and vegetation filter <i>for DEM</i> (see the "Slope based filter" chapter of "DTM Generation" User Manual)
Fill NULL cells	to restore null cells of DEM using the smooth inter- polation method (see the "Filling null cells using smooth interpolation" chapter of "DTM Generation" User Manual)

Table 3. Brief description of the Compute DEM tab of the main toolbar

Table 4. Brief description of the Compute Orthophoto tab of the main toolbar

Buttons	Function
	to display the orthorectification toolbar ( <b>Ctrl+Alt+M</b> ) (see the Orthomosaic building User Manual)
👹 Start GeoMosaic	to start <i>PHOTOMOD GeoMosaic</i> program (see the The Orthophotomaps creation User Manual)

# 3.3. Brief description of main menu

The program main menu contains the menu items for mosaic creation, vector data processing, additional applications starting and setting parameters.

Menu	Function
	contains menu items to create, open, save and convert project, and also to get an information about project
Block	to form images block of mosaic project

Table 5. Main menu

Menu	Function
Orientation	contains menu items to interior orientation, load and use ground control and triangulation points, exterior orientation parameters and also to import and export triangulation points for various formats
Grid	to create, open and save regular nodes grid (see the "Regular grid of nodes" chapter of the "Create DTM" User Manual)
Terrain	to prepare the base layers for the further DTM/DSM creation: calculating 3D-points, building TIN & tex- tured TIN 3D surface, building DEM, building LAS point clouds, building true ortho, building smooth contours
Vectors	purposed for creating, editing, import/export of vec- tor data (see the "Vectorization" User Manual)
Rasters	to load and georeference raster images, and also to launch additional modules for editing and orthorec- tification images
Service	to launch applications, load additional data, set general parameters and edit coordinate systems
Window	to open additional toolbars and windows: new 2D- window, Marker and Measurements windows, win- dow of Object Attributes (see "The "Windows" menu" chapter of the "General information about system" User Manual)
Help	to start the "Help" system

# 3.4. The "Project" menu

Table 6. Brief description of Project menu
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Menu items	Function
New	to create a new project (see the "Project creation" chapter of the "Creating project" User Manual)
⊘Open/Manage (Ctrl+Alt+O);	to open the project management window (see the "Project management window" chapter of the "Cre- ating project" User Manual)
Сору	to create a copy of project selected in the list (see the "Copying project" chapter of the "Creating pro- ject" User Manual)
Backup project	to create project backup (see the "Creating project backup" chapter of the "Creating project" User Manual)
Project export	exports project data into a *.xml file, which is used in <i>Blocks Exchange XML</i> protocol between <i>PHOTO-</i> <i>MOD</i> and external software such as <i>Agisoft</i> <i>Metashape</i> or <i>Bentley ContextCapture</i> (only for central projection projects, see the "Export and Im-

Menu items	Function
	port of Projects" chapter of the "Creating project" User Manual)
Project import	imports project data from a *.xml file, which is used in <i>Blocks Exchange XML</i> protocol between <i>PHOTO-</i> <i>MOD</i> and external software such as <i>Agisoft</i> <i>Metashape</i> or <i>Bentley ContextCapture</i> (only for central projection projects, see the "Export and Im- port of Projects" chapter of the "Creating project" User Manual)
n Reload	to reloads a project to update it after changes appeared during mutual work
Synchronize	to re-calculate a project data after editing of some parameters, e.g. re-calculates interior orientation after changing camera parameters
Close	to close current project and to start "without project" mode (see the "\$QUOTE\$"Without project" mode" chapter of the "Creating project" User Manual)
Properties	to open the window used to view and edit some parameters of opened project (see the "Project properties" chapter of the "Creating project" User Manual)
Recent	to open a list of projects opened recently in the system
Join projects	to merge data from several projects of active profile (see the "Joining projects" chapter of the "Creating project" User Manual)
Project state	to display processing status of the following project stages (see the "Viewing project report" chapter of the "Creating project" User Manual)

#### 3.5. The "Block" menu

The **Block** menu, buttons of **Block editor** window's toolbar and **Block forming** additional toolbar are used to work with images block in 2D-window. It includes extended features for images block forming, as well as additional functions for block scheme creation and obtaining of auxiliary data.

Some menu items allow to manage operations with selected images in 2D-window. The **Tools** additional toolbar is used for group selection (highlighting) of images block in 2D-window (see the "Vectorization" User Manual).

Detailed information about **Block** menu items, buttons of **Block editor** window's toolbar and **Block forming** additional toolbar see in the "Project creation" User Manual.

Menu items	Function
🔁 Add images from files	to add image files, locating in the resources out of active profile, to the selected strip (see the "Adding images from files" chapter in "Creating project" User Manual)
🚺 Add images from resources	to add image files, locating in the resources of active profile, to the selected strip (see the "Adding images from resources" chapter in "Creating project" User Manual)
Add images from resource folder	to automatically add images from specified folder of active profile resources to selected strip, with or without its subfolders
Split to strips	contains menu items used to split images block to strips automatically using images names or exterior orientation parameters (see the "Splitting into strips" chapter in "Creating project" User Manual)
Block editor (Ctrl+Alt+B)	to open the Block editor window
Block layout (Ctrl+Alt+L)	to open the <b>Block layout</b> window to build block scheme in 2D-window considering source or ac- quired data (see the "Aerial triangulation" User Manual)
Create overlap map	to create map of images and/or strips overlap in new vector layer (see the "Creating overlap map" chapter of the "Creating project" User Manual)
Additional	contains the Additional menu (see below)

Table 8. Brief description of the Block menu (Additional)

Menu items	Function
🔤 Add strip	to add new strip
🔀 Delete strip	to delete selected strips of block in 2D-window
强 Strip properties	to view and edit properties of selected strips – strip's name and type (regular or irregular)
Invert image order in strip	to invert strips order
Selected strips to block start	to move selected strips to the beginning
Selected strips to block end	to move selected strips to the end
🔤 Add strip	to add new strip
🔀 Delete strip	to delete selected strips of block in 2D-window
强 Strip properties	to view and edit properties of selected strips – strip's name and type (regular or irregular)
🏦 Move selected strips up	to move selected strips one strip up
🐺 Move selected strips down	to move selected strips one strip down
Make selected strips irregular	to change regular strip to irregular
Make selected strips regular	to change irregular strip to regular
🐹 Delete images	to remove selected images from project

Menu items	Function
Delete images selectively	to select images in accordance with specified criteria for deleting (see the "Deleting images selectively" chapter of the "Creating project" User Manual)
🌆 Image properties	to display and edit properties of selected image
Move images	opens a group of menu items used to images block editing; allows to invert images order in a strip, and to move selected image left/right/up/down
🚰 Image radiometric correction	to perform radiometric correction of selected image (see the "Radiometric correction" chapter in the "Project creation" User Manual)
🚰 Show images	to show images of block in 2D-window if the limita- tion on images display is specified on the <b>Block</b> <b>scheme   Raster</b> tab in the <b>Settings</b> window (see "General information" User Manual)
💕 Show selected images only	to turn on/of selected images display
Check images	to perform search for 16-bit project images without radiometric correction (no *.rmc file associated with the image, see "Radiometric correction" in the "General information" User Manual). If images are found in the project that meet the criteria described above, an appropriate info message is issued
Mark all images as checked	to exclude project images validation - check their presence and compliance to images files during project opening at the next working session
Marker to selected image	to move marker to center of the image, selected in the list of the <b>Block editor</b> window
Brightness adjustment	to build brightness adjustment for all block scheme (see the "Brightness adjustment" chapter in the "Project creation" User Manual)
Delete brightness adjustment	to delete the brightness adjustment results (see the "Brightness adjustment" chapter in the "Project cre- ation" User Manual)
Rotate selected images	to rotate selected images at any angle relatively to initial or current position of block images
Rotate images by block layout	to rotate all or selected images of block considering block layout data; images don't rotate if the <b>w\o</b> <b>layout</b> was used (see the "Aerial triangulation" User Manual)
Set GSD for selected images	to define/calculate GSD value in meters for all or selected images of block (see the "Specifying ground sample distance (GSD)" chapter in the "Project creation" User Manual)
Create vector layer from block layout	to create vector layers with common block outline, boundaries of all images or selected image of the block (see the "Creating vector layers from block layout" chapter in the "Project creation" User Manual)

Menu items	Function
	to create pre-regions by images/stereopairs to provide joint work on a project (see the "Creation pre-regions for a block" chapter in the "Project cre- ation" User Manual)
Export block layout to KML	to export block scheme to KML format

# 3.6. The "Orientation" menu

To perform work on data collection for aerial triangulation serves the **Orientation** menu, and also buttons of the main toolbar and of the **AT** additional toolbar.

Menu items	Function
Manage projects cameras (Ctrl+Alt+I)	to input/edit parameters of project cameras, and also to assign cameras to project images (see the "Project cameras management" chapter of the "Aerial triangulation" User Manual)
almport orientation from metadata	to perform import of exterior orientation from metadata (see the "Import orientation from metadata" chapter of the "Aerial triangulation" User Manual)
Import exterior orientation	to open the Exterior orientation data list (see the "Import of exterior orientation parameters" chapter of the "Aerial triangulation" User Manual)
Automatic tie points measurements	contains menu items used to measure tie points coordinates in automatic mode (see the "Automatic measurement of tie points coordinates (general in- formation)" chapter of the "Aerial triangulation" User Manual)
Tie points list (Ctrl+Alt+T)	to open catalogue of all <i>tie points</i> with their meas- urements (see "The "Triangulation points" window" chapter of the "Aerial triangulation" User Manual)
GCP list (Ctrl+Alt+G)	to open catalogue of <i>all ground control points</i> , includ- ing non-measured on block images (see the "GCP list" chapter of the "Aerial triangulation" User Manual)
Block adjustment (Ctrl+Alt+S)	to open the adjustment module, to view adjustment results and errors correction (see the "Block adjust- ment" User Manual)
Direct georeferencing	to perform adjustment using imported exterior orient- ation parameters
Subblock analysis	to perform the subblock analysis by triangulation points (see the "Subblock analysis" chapter of the "Aerial triangulation" User Manual)
Processing report	to create the processing report (see the "Processing report" chapter of the "Aerial triangulation" User Manual)

Table 9. Brief description of the Orientation menu

Menu items	Function
-	to delete adjustment data (see the "Block adjust- ment" User Manual)
Additional	contains the Additional menu (see below)

Table 10. Brief description	of the Orientation menu	(Additional)
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Menu items	Function
Report on interior orientation	to open a report about interior orientation results (see the "Report on interior orientation" chapter of the "Aerial triangulation" User Manual)
Manual interior orientation	[only for film camera images] to measure manually coordinates of fiducial marks on images (see the "Manual measurement of fiducial marks coordinates" chapter of the "Aerial triangulation" User Manual)
Semiautomatic interior orientation	[only for film camera images] to perform semiauto- matic interior orientation, which is to use image- standard with template of fiducial marks position used to search the same fiducial marks on other project images (see the "Semi-automatic interior orientation" chapter of the "Aerial triangulation" User Manual)
Automatic interior orientation	[only for film camera images] to perform automatic interior orientation, which is the automatic recogni- tion of fiducial marks by their type, peculiar to certain analog camera images (see the "Automatic interior orientation" chapter of the "Aerial triangulation" User Manual)
Calculate interior orientation	to re-calculate interior orientation parameters (see the "Images interior orientation" chapter of the "Aerial triangulation" User Manual)
Delete interior orientation data	to open the <b>Select images</b> window that is used to delete results of fiducial marks measurements on selected images (see the "Images interior orienta- tion" chapter of the "Aerial triangulation" User Manual)
Quick Ties	contains menu items used to perform quick ties in order to use the data for block layout creation (see the "Manual images linking (quick ties)" in "Aerial triangulation" User Manual)
Open selected images for measurements	to open the <b>Points measurement</b> module used to measure points coordinates in manual mode on images <i>selected</i> in 2D-window (see the "" chapter of the "Aerial triangulation" User Manual)
ROpen images containing marker (Ctrl+Alt+K)	to open the <b>Points measurement</b> module used to measure points coordinates in manual mode on <i>images, that contain marker position in 2D-window</i> (see the "The "Points measurement" module" chapter of the "Aerial triangulation" User Manual)

Menu items	Function
Open in-strip stereopair	to open the <b>Points measurement</b> module used to measure points coordinates in manual mode on selected <i>in-strip stereopair</i> in 2D-window (see the "The "Points measurement" module" chapter of the "Aerial triangulation" User Manual)
Open inter-strip stereopair	to open the <b>Points measurement</b> module used to measure points coordinates in manual mode on selected in 2D-window <i>inter-strip stereopair</i> (see the "The "Points measurement" module" chapter of the "Aerial triangulation" User Manual)
Report on relative orientation (Ctrl+Alt+R)	to open the report with results of images relative orientation in order to perform analysis and removal of errors in tie points measurements (see the "The "Points measurement" module" chapter of the "Aer- ial triangulation" User Manual)
🔐 Delete point measurements	to choose types of triangulation points to be deleted and delete them (see the "The "Triangulation points" window" chapter of the "Aerial triangulation" User Manual)
₩Clear point catalogue	to remove the whole list of triangulation points (GCP, check, tie) from triangulation points catalogue (see the "The "Triangulation points" window" chapter of the "Aerial triangulation" User Manual)
Load triangulation points	to load measured coordinates of triangulation points to 2D-window with possibility to setup of display of certain type of points (see the "Triangulation points display in 2D-window" chapter of the "Aerial triangu- lation" User Manual)
Delete points outside useful areas	to delete points out of useful areas (with specified background color) (used mainly during automatic points measurements on spaceborne images)
Delete border points	to delete points of selected types from near-bound- ary areas of project images marked in the list (see the "Deleting points at image boundaries" chapter of the "Aerial triangulation" User Manual)
Delete duplicated points	to delete tie points duplicates (see the "Removing point duplicates" chapter of the "Aerial triangulation" User Manual)
Import	contains menu items used to import of triangulation points measurements from files of PAT-B, X-Points formats from PHOTOMOD 4.x (XPT) projects, as well as data import from flight path file (see the "Import of triangulation points" chapter of the "Aerial triangulation" User Manual)
Export	contains menu items used to export of triangulation points measurements to files of PAT-B and X-Points formats, and for export of ties or GCP for further use them in <i>Geomosaic module</i> (see the "Export of

Menu items	Function
	triangulation points" chapter of the "Aerial triangula- tion" User Manual)
Exterior orientation parameters	to open the Exterior orientation data list (see the "List of exterior orientation parameters" chapter of the "Aerial triangulation" User Manual)
Export exterior orientation	to perform export of list of source exterior orientation parameters and adjustment results to PAT-B and CSV formats (see the "Export of exterior orientation parameters" chapter of the "Aerial triangulation" User Manual)
Load projection centres as vectors	to load projection centres data as vector point ob- jects and to open them in 2D-window to perform analysis, at that an image name is saved to the Name point attribute
Create images georeferencing files	to perform export of georeference data after prelim- inary block exterior orientation and adjustment (to files of <i>ArcInfo World File</i> and <i>MapInfo TAB</i> formats)
Select subblock	to select part of block images to perform adjustment
Adjustment in batch mode	to specify adjustment parameters and to perform block adjustment without using the the <b>Adjustment</b> toolbar (see the "Block adjustment" User Manual)

# 3.7. The "Terrain" menu

Menu items	Function
Points	The <b>Points</b> menu contains usual menu items used for automatic points measurement, filtering, import and export (see the "Points" chapter of the "Creating DTM" User Manual)
TIN	The <b>TIN</b> menu contains menu items used to load and save TIN layers, as well as to perform different operations on creation, editing and accuracy control of TIN building
DEM	The <b>DEM</b> menu contains standard menu items used to load and save DEM layers, as well as menu items used to perform various operations on DEM cre- ation, accuracy control, filtering and editing
Compute volumes	allows to calculate a volume (i.e. <i>embankment</i> or <i>excavation</i> ) located between DEM surface and <b>ar-bitrary</b> Z-plane or in a more complex case, the volume which is the overlap between the two (roughly, "top" and "bottom") <b>DEM</b> or <b>TIN</b> surfaces (see the "Volumes calculation" chapter of the "Creating DTM" User Manual)
Contours	The <b>Contours</b> menu contains usual menu items used for contours generating, editing, import and

Table 11. Brief description of the Terrain menu

Menu items	Function
	export (see the "Contour lines" chapter of the "Cre- ating DTM" User Manual)
LAS	The <b>LAS</b> menu contains usual menu items used for converting the LIDAR data to DEM which is saved into the file of active profile (see the "LIDAR Data processing" User Manual)
3D-Mod	The <b>3D-Mod</b> menu allows to run module for creation 3d-objects based on 2D-vectors (see the "Three-dimensional modeling" User Manual)

#### 3.7.1. The "TIN" menu

The **TIN** menu contains standard menu items used to load and save TIN layers, as well as to perform different operations on creation, editing and accuracy control of TIN building.



The **Points** menu is located in the **Terrain** menu.

The TIN menu	Function
Load TIN (Ctrl+O, T)	to load TIN from *.x-tin file (see the "TIN loading" chapter in "DTM Generation" User Manual)
Recent	to perform the quick access to recently loaded TIN files
Save	to save or rewrite active TIN layer as file with *.x- tin extension (see the "TIN saving" chapter in "DTM Generation" User Manual)
Save as	to save active TIN layer with new name as file with *.x-tin extension (see the "TIN saving" chapter in "DTM Generation" User Manual)
Close	to close TIN
Close all opened layers	to close all opened TIN layers
Layers visibility	contains menu items which allow to perform batch management of TIN layers visibility in the <i>Layer</i> manager
🔀 Build (Ctrl+N, T)	to create TIN using loaded base layers (see the "Building TIN" chapter in "DTM Generation" User Manual)
Build 3D-TIN	to create textured 3D-TIN surfaces (see the "Cre- ation of textured TIN 3D surface" chapter in "DTM Generation" User Manual)
Build 3D-TIN (Batch mode)	to create textured 3D-TIN surfaces in batch mode (see the "Batch 3D-TIN creation" chapter in "DTM Generation" User Manual)

Table 12. Brief description of the "TIN'\$QUOTE\$"menu

The TIN menu	Function
Convert 3D-TIN CS	to change coordinate system of 3D-TIN (see the "Transformation of 3D-TIN coordinate system" chapter in "DTM Generation" User Manual)
Filter	contains menu items which can be used to filter DEMs (see the "TIN filtering" chapter in "DTM Gen- eration" User Manual)
Export	Contains menu items to export results of TIN cre- ation to DXF and CSV formats (see the "Export TIN" chapter in "DTM Generation" User Manual)
Import	Contains menu items allowing to import TIN from different formats (see the "Import TIN" chapter in "DTM Generation" User Manual)
Additional	contains the Additional menu (see below)

Table 13. Brief description of the "TIN'\$QUOTE\$"menu (additional)

The TIN menu	Function
Restore	to restore TIN from contours (see the "TIN restoring" chapter in "DTM Generation" User Manual)
Compute border	to create TIN border in automatic mode (see the "TIN borders creation" chapter in "DTM Generation" User Manual)
🎇 Rebuild	to rebuild TIN after editing of base layer objects (see the "TIN re-building" chapter in "DTM Generation" User Manual)
Check against adjustment points	to control TIN creation accuracy by triangulation points (see the "Check against adjustment points" chapter in "DTM Generation" User Manual)
Check against vector objects	to control TIN creation accuracy by vector objects, which were not used during TIN creation (see the "Check TIN against vector objects" chapter in "DTM Generation" User Manual)
Verify topology	to check topology of TIN creation (see the "Verifying of TIN topology" chapter in "DTM Generation" User Manual)
The area of a polygon on the surface	to calculate TIN surface area within a polygon (see the "TIN area info" chapter in "DTM Generation" User Manual)
Calculate area	to calculate TIN projection area on plane and area of TIN 3D surface (see the "TIN area info" chapter in "DTM Generation" User Manual)
Statistic	to view statistic information about TIN (see the "General TIN info" chapter in "DTM Generation" User Manual)
Interpolate	to interpolate TIN to smooth DTM in order to build or enhance contour lines (see the "Smooth TIN in- terpolation" chapter in "DTM Generation" User Manual)

The TIN menu	Function
Convert to vector layer	to convert TIN into a vector layer (see the "Convert- ing TIN into a vector layer" chapter in "DTM Gener- ation" User Manual)
🛃 Embed objects	to embed vector objects layer to created TIN (see the "Insert objects into TIN" chapter in "DTM Gener- ation" User Manual)
Export	Contains menu items to export results of TIN cre- ation to DXF and CSV formats (see the "Export TIN" chapter in "DTM Generation" User Manual)
Import	Contains menu items allowing to import TIN from different formats (see the "Import TIN" chapter in "DTM Generation" User Manual)
On/Off TIN visibility (Ctrl+T)	to enable/disable editable TIN layer visibility

#### 3.7.2. The "DEM" menu

The **DEM** menu contains standard menu items used to load and save DEM layers, as well as menu items used to perform various operations on DEM creation, accuracy control, filtering and editing.



The **DEM** menu is located in the **Terrain** menu.

Menu items	Function
Load DEM (Ctrl+O, D)	to load DEM from *.x-dem file (see the "DEM load- ing" chapter in "DTM Generation" User Manual)
Open from file	to load DEM from external data without its conver- sion to internal format (see the "DEM loading" chapter in "DTM Generation" User Manual)
Recent	to perform the quick access to recently loaded DEM files
Save copy	to save opened DEM to a new file (see the "DEM saving" chapter in "DTM Generation" User Manual)
Save selection	to save DEM area (see the "DEM saving" chapter in "DTM Generation" User Manual)
Close	to close DEM
Close all opened layers	to close all opened DEM layers
Layers visibility	contains menu items which allow to perform batch management of DEM layers visibility in the <i>Layer manager</i>
Build DEM	contains menu items used to create DEM with help of various source data (see the "DEM creation" chapter in "DTM Generation" User Manual)

Menu items	Function
Filter	contains menu items which can be used to filter DEMs (see the "DEM filtering" chapter in "DTM Generation" User Manual)
Fill null cells	contains menu items used to restore blank cells of DEM using various methods (see the "Null cells in DEM" chapter in "DTM Generation" User Manual)
Import	contains items used to import DEM from files with *.grd, *.asc, *.tif, *.dem, *.mtw, *.dt1, *.dt2, *.img, *.pix, *.hgt extensions (see the "DEM im- port" chapter in "DTM Generation" User Manual)
Batch import	to simultaneous import of multiple DEM (see the "Batch DEM import" chapter in "DTM Generation" User Manual)
Batch import from folder	to simultaneous import of multiple DEM from a specified folder (see the "Batch import from folder" chapter in "DTM Generation" User Manual)
Export	contains menu items used to perform export of DEM to different formats (see the "DEM export" chapter in "DTM Generation" User Manual)
Additional	contains the Additional menu (see below)

Table 15. Brief description of the DEM menu (additional)

Menu items	Function
Save as georeferenced raster	to save a DEM as a raster file with geodetic refer- ence (see the "DEM saving" chapter in "DTM Gen- eration" User Manual)
Build DEM	contains menu items used to create DEM with help of various source data (see the "DEM creation" chapter in "DTM Generation" User Manual)
Rebuild by TIN	to recreate DEM after changing of TIN base layer (see the "DEM creation by TIN" chapter in "DTM Generation" User Manual)
Restore	to restoring of DEM consistency, which may be disrupted by applying various operations or DEM filtering (see the "DEM recovering" chapter in "DTM Generation" User Manual)
Slope based filter	to filter objects based on slope angle (see the "Slope based filter" chapter in "DTM Generation" User Manual)
Filter by image properties	to filter DEMs depending on image characteristics (see the "Filter by image properties" chapter in "DTM Generation" User Manual)
Cut DEM by Z-range	to convert DEM cells with specified elevation to null cells (see the "Converting cells to null" chapter in "DTM Generation" User Manual)
Set elevation in selected polygons	to set the same elevation of DEM cells inside and outside of selected polygons (see the "Change DEM

Menu items	Function
	parts elevation" chapter in "DTM Generation" User Manual)
Interpolate elevation in selected polygons	to interpolate a value of DEM cells inside and out- side of selected polygons (see the "DEM interpolat- ing" chapter in "DTM Generation" User Manual)
Cut by selected polygons	to edit coverage area of DEM (see the "DEM cutting by polygons" chapter in "DTM Generation" User Manual)
Cut null edges	to remove edge areas of DEM, that include blank cells (see the "DEM cutting by polygons" chapter in "DTM Generation" User Manual)
Transpose	to transpose DEM from the left coordinate system to the right one and vice versa (see the "DEM transpose" chapter in "DTM Generation" User Manual)
Transform to another coordinate system	to change coordinate system of DEM (see the "Transformation of DEM coordinate system" chapter in "DTM Generation" User Manual)
Batch transform to another coordinate system	to change coordinate system of multiple DEMs (see the "Batch transformation of DEMs coordinate sys- tem" chapter in "DTM Generation" User Manual)
Rebuild considering last adjustment	to recreate DEM considering results of the last ad- justment (if the project was adjusted after DEM creation once more – see the "Rebuilding DEM considering last adjustment" chapter in "DTM Gen- eration" User Manual)
Shift	to parallel displacement of DEM by axes (see the "DEM shift" chapter in "DTM Generation" User Manual)
Split DEM into sheets	to split DEM into sheet to save DEM in parts in separate files (see the "Split DEM into sheets" chapter in "DTM Generation" User Manual)
Merge DEMs	to merge DEMs, that have overlap area (see the "DEM merging" chapter in "DTM Generation" User Manual)
Accuracy control	to perform accuracy control DEM creation using various data (see the "Accuracy control of DEM creation" chapter in "DTM Generation" User Manual)
Compute volumes	to calculate a volume (i.e. <i>embankment</i> or <i>excava-</i> <i>tion</i> ) located between DEM surface and <b>arbitrary</b> Z-plane or in a more complex case, the volume which is the overlap between the two (roughly, "top" and "bottom") DEM surfaces (see the "Volumes Calculation" chapter in "DTM Generation" User Manual)
Calculate slope map	to calculate a slope map (see the "Slopes map cre- ation" chapter in "DTM Generation" User Manual)

Menu items	Function
Convert to points	to convert DEM cells to points with specified simpli- fying (see the "Convert DEM to points" chapter in "DTM Generation" User Manual)
Convert to LAS	to convert DEM to LAS point cloud (see the "Convert DEM to point cloud (LAS)" chapter in "DTM Gener- ation" User Manual)
Write points to DEM	to add points to DEM that helps to refine DEM cells values (see the "Adding of points to DEM" chapter in "DTM Generation" User Manual)

# 3.7.3. The "Contours" menu

The **Contours** menu contains usual menu items used for contours generating, editing, import and export.



The **Contours** menu is located in the **Terrain** menu.

Menu items	Function
Load (Ctrl+O, V)	to load contour lines from *.x-data file (see the "Vectorization" User Manual)
Recent	to perform the quick access to recently loaded con- tour lines
Save	to save or rewrite active contours layer (see the "Saving contour lines" chapter in "DTM Generation" User Manual)
Save as	to save active layer with new name (see the "Saving contour lines" chapter in "DTM Generation" User Manual)
Save selected as	to save <i>just</i> selected contours (see the "Saving contour lines" chapter in "DTM Generation" User Manual)
Close	to close contour lines layer
Build contours	contains menu items used to create contour lines with help of various source data (see the "Contour lines generation" chapter in "DTM Generation" User Manual)
Import	contains items used to import contour lines from files with different extensions (see the "Import of vector objects" chapter of the "Vectorization" User Manual)
Export	contains menu items used to perform export of contour lines to files with different extensions (see the " <i>Export of vector objects</i> " chapter of the "Vector- ization" User Manual)

Menu items	Function
Prepare/export contours sheets	to save, edit, and export contours within the given notation sheets to the Panorama format (see the "Export of contours sheets" chapter in "DTM Gener- ation" User Manual)
Additional	contains the Additional menu (see below)

#### Table 17. Brief description of the Contours menu (additional)

Manual Hanna	
Menu items	Function
Build contours	contains menu items used to create contour lines with help of various source data (see the "Contour lines generation" chapter in "DTM Generation" User Manual)
Check contours intersections	to check created contours for crossing/self-crossing, that occur after operation of contours smoothing (see the "Control of contours crossing" chapter in "DTM Generation" User Manual)
Check contours by points	to perform quality control of contours creation using regular points, if they were not used for contours creation (see the "Check contours by points" chapter in "DTM Generation" User Manual)
Merge contours	to merge created contours in automatic or manual mode (see the "Contours merging" chapter in "DTM Generation" User Manual)
Check merging contours	to check contours for breaks that occur after manual or automatic contours merging (see the "Check of contours merging quality" chapter in "DTM Genera- tion" User Manual)
Contours connecting	to connect created contours automatically or manually (without merging into a single vector ob- ject – see the "Contours connecting" chapter in "DTM Generation" User Manual)
Check contours vertices	to check elevations of created contours vertices (see the "Check elevations of contours vertices" chapter in "DTM Generation" User Manual)
Precision of objects coordinates	to set a precision of vector objects coordinates at level of decimal places (see the "Precision of objects coordinates" chapter in "DTM Generation" User Manual)

# 3.8. The "Raster" menu

The system provides the **Raster** menu to perform various operations with raster images.

Menu items	Function
	to create orthophoto production and mosaicking (see the "Orthorectification" User Manual)

Menu items	Function
SeoMosaic	to run the <i>GeoMosaic program</i> allows to create the orthomosaic from georeferenced orthorectified aer- ial and satellite imagery, splitting of created ortho- mosaic with the capable of saving sheets in popular raster file format (see the "Orthophotomaps creation" User Manual)
Raster Converter	to launch the <i>Raster Converter</i> program for prepar- ing and converting raster images into the internal format files and then for placing them in active profile resources (see the "General information" User Manual).
🔯 ImageWizard module	to edit path to image files (see the "ImageWizard Adjustment of images" chapter in "Creating project" User Manual)
Load georeferenced images (files)	to load georeference images from folder in <i>Windows</i> <i>file system</i> (see the "Georeferenced external data" section of the "Aerial triangulation" User Manual and the "Pseudo-stereo mode" section of the "Vectoriz- ation" User Manual)
Load georeferenced images (resources)	to load georeference images from active profile re- sources (see the "Georeferenced external data" section of the "Aerial triangulation" User Manual and the "Pseudo-stereo mode" section of the "Vectoriz- ation" User Manual)
🔄 Load web-map	to load georeferenced web-maps from the Internet (see the "Web-map loading" chapter in "Creating project" User Manual)
Show rasters	to use one of three modes of displaying raster im- ages in 2D-window: Cached only (Ctrl+Shift+1), Depending on zoom (Ctrl+Shift+2) or Source only (Ctrl+Shift+3)
Additional	contains the Additional menu (see below)

#### Table 19. Brief description of Raster menu (additional)

Menu items	Function
Image georeferencing	to perform georeferencing images by geodetic co- ordinates GCP points, obtained from vector/raster maps or from a list of file *.txt (see the "Aerial tri- angulation" User Manual)
Affine georeference correction	to perform affine correction of georeferenced images (see the "Affine georeference correction" chapter in "Creating project" User Manual)
Save raster layer	to save a georeference raster image of the active layer with specified parameters in output file format (TIFF, MS-TIFF, MegaTIFF – see the "Saving of raster image" chapter in "Creating project" User Manual)
Close all opened layers	to close all opened raster layers

Menu items	Function
Layers visibility	contains menu items which allow to perform batch management of raster layers visibility in the <i>Layer</i> manager
ScanCorrect	to run the <i>ScanCorrect</i> program for compensation of metric errors occurred when scanning graphical data on flatbed polygraphic scanners (see the "ScanCorrect program" User Manual)
📓 Dust Correct	to 'clean' images of dust particles, photo emulsion defects etc (see the "Dust Correct" chapter in "Creating project" User Manual)
Clear cache	to delete raster cache from RAM
Images order	to rearrange block images by z-order
Rebuild Mega Tiff pyramids	to rebuild image pyramids for MegaTIFF images (see the "Image pyramid creation" chapter in "Cre- ating project" User Manual)
Adjust zoom	to set zoom of images in 2D-window by set GSD in pixels

# 3.9. "Service" menu

#### Table 20. Brief description of the Service menu

Menu	Function
Explorer	to open the <i>PHOTOMOD Explorer</i> module to view resources system (see the "PHOTOMOD Explorer module. Resources management" chapter in "Gen- eral information" User Manual)
GeoCalculator	to launch the GeoCalculator program that is used for coordinates transformation form one reference system to another
GIS Panorama	to run the <i>GIS Panorama Mini</i> (this software is not included with the <i>PHOTOMOD</i> but can be installed separately)
Show in Google Maps	to display area on images in the GoogleMaps ser- vice (Internet connection required); it is possible only for projects in geodetic coordinate systems or if the coordinate system could be transformed to geodetic
Show in Yandex Maps	to display area on images in the YandexMaps ser- vice (Internet connection required); it is possible only for projects in geodetic coordinate systems or if the coordinate system could be transformed to geodetic
Recalc working area	to refresh 2D-window and fit displayed area depend- ing on load data
Activate mouse driver	to turn on/off defined mouse driver

Menu	Function
Mouse setup	to setup or connect mice, including special mice, hand wheels and foot pedals, and also to macros setup (see the "Using of special mice, hand wheels and foot pedals in the system" chapter in "General information" User Manual)
₩ Undo (Ctrl+Z)	to cancel the last operation of vector objects editing on a layer (see the "Undo editing operations" chapter in "Vectorization" User Manual)
📓 Undo log	o open the <b>Undo log</b> containing a list of recent editing operations (see the "Undo editing operations" chapter in "Vectorization" User Manual)
☐ Redo (Ctrl+Shift+Z)	to redo the last undone operation (see the "Undo editing operations" chapter in "Vectorization" User Manual)
Last log	to display the last log of system actions
Parameters	to open the window to set the general parameters of the system
Additional	contains the Additional menu (see below)

Table 21. Brief description of the Service menu (additional)

Menu	Function
Distributed Processing	contains menu items to run, test and setup distrib- uted processing (see the "Distributed Processing" chapter in "General information" User Manual)
Working coordinate system	to choose working coordinate system (see the Pro- ject creation User Manual)
Autodetect Gauss-Krueger zone	to detect the Gauss-Krueger zone automatically for the selected object, provided that any Global coordin- ate system is used (see the "Automatic detection of the Gauss-Krueger zone" chapter in "General inform- ation" User Manual)
CSV converter	to launch the CSV converter to transform points coordinates in CSV and TXT files and also for other transformations for CSV files (see the "CSV convert- er" chapter in "General information" User Manual)
Load atlas	to load the World map to a new vector or raster layer (see the "Loading atlas" chapter in "General information" User Manual)
Save scene	to save visible part of images in active 2D-window as a raster image with specified size and quality
Customize hotkeys	to adjust hotkeys using in the system, edit, delete or create new hotkeys (see the "Customize hotkeys" chapter in "General information" User Manual)
Customize fast commads	to use so called shortcut commands, the custom button combinations for quick access to various functions when working with the layers such as <b>Vectors</b> , <b>DEM</b> , <b>Raster</b> , <b>Grid</b> , or <b>TIN</b> (see the

Menu	Function
	"Shortcut commands" chapter in "General informa- tion" User Manual)
	to save projects parameters and use it automatically when restart the system

ee Question	×	
Panorama executable file not found Use following link in order to dowload Panorama software KB Panorama		
Edit path to executable file in settings?		
Yes No		

If the *GIS Panorama* executable file is not found, an appropriate system message will appear. The software description and URL hyperlink (for download) are indicated in this message.

Click **Yes** to go to path settings (see the "Paths settings" chapter of the "General system's parameters" User Manual.

# 3.10. The "Windows" menu

Menu items	Function
New 2D-window (block)	to open window with a block scheme
New 2D-window (stereopair) (Ctrl+Alt+W)	to open window with a stereopair
3D-window	to open the 3D-window (see the "General informa- tion" User Manual)
im Marker window (Ctrl+Alt+C)	to open marker parameters window (see the "Vec- torization" User Manual)
Measurements window (Ctrl+Alt+D)	to open window that allows to perform measure- ments by images (see the "Vectorization" User Manual)
Elassifier	to open the <b>Classifier</b> window to show set of standard vector objects attributes (see the "Classifier \$QUOTE\$" chapter in the "Vectorization" User Manual)
A Objects attributes	to open the <b>Attributes</b> window to display attributes of selected vector objects (see the "Vector objects attributes \$QUOTE\$" chapter in the "Vectorization" User Manual)
Toolbars	contains menu items allows to open additional tool- bars
Additional	contains the Additional menu (see below)

Table 22. Brief de	escription of the	Windows menu
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See detailed description of the system's windows in the "General information about the system" User Manual.

To get quick access to the *main* windows of the system, select **Windows > Toolbars > Windows**. The **Windows** toolbar is opened.

Menu items	Function	
🔤 Block editor	to open block editor window (see the 'Project cre- ation' User Manual)	
🔀 Block layout	to open the block layout window (see the 'Aerial tri- angulation' User Manual)	
Show all toolbars	to show all toolbars	
Find all toolbars	to show all opened toolbars in visible part of the screen	
Temporarily hide toolbars (TAB)	to hide/show all opened toolbars	
Image list	to open the <b>Images list</b> window (see the 'Creating project' User Manual)	
New 2D-window (single image)	to open window with image selected on a block scheme	
Open image under marker	to open all 2D-windows with marker place. Press and hold <b>Alt</b> key while clicking the menu item to open images with 1:1 zoom , otherwise, full images are displayed	
Close all single image windows	to close all 2D-windows with images	
🚰 Refresh all 2D-windows	to refresh information in all opened 2D-windows	
🔀 Refresh all 2D-windows	to close all 2D-windows	
Arrange	contains menu items allow to arrange opened 2D- windows in a work area with one of the following ways:	
	<ul> <li>Image: Tile – to tile 2D-windows;</li> </ul>	
	• <b>Row</b> – to row 2D-windows;	
	<ul> <li>Eolumn – to column 2D-windows;</li> </ul>	
	<ul> <li>The stack – to stack 2D-windows;</li> </ul>	
	<ul> <li>Table Arrange 2D-windows in a tabsheet;</li> </ul>	
	<ul> <li>Evenly – to arrange 2D-windows evenly.</li> </ul>	
Stereopairs	contains menu items allows to move to other stereo-	
	pairs (see the 'Vectorization' User Manual)	
Triangulation points coordinates	to show table with triangulation points coordinates	

Table 23. Brief description of the 'Windows 'menu (Additional)

Menu items	Function
Contours classifier table	to open contours classifier window to edit parameters of contours display (see the 'DTM generation' User Manual)
Objects list	to display list of active layer vector objects (see the 'Vectorization' User Manual)
Marker motion in pixel coordinates	to set on the mode allows to move marker in stereo- pair 2D-window in pixel coordinates
Zoom all in (Shift+* NumPad)	to zoom in all 2D-windows
Zoom all out (Shift+/ NumPad)	to zoom out all 2D-windows
Layer view mask	to use a view mask for active layer (see the 'General information' User Manual)
Windows list	to view list of opened 2D-windows

#### 3.11. The "Block editor" window

The **Block editor** window is used to form a block of project images.

The **Block editor** window contains a table of created strips and images loaded to project and contains tools for images block editing.

The **Block editor** window is synchronized with 2D-window, so all changes in the images list of the **Block editor** (choosing, adding, deleting, moving of strips and images) are shown in the block scheme in 2D-window and vice versa.

Choose the Block > Block editor (Ctrl+Alt+B) to open the Block editor window.

Block editor					
👎 🔺 🏘 🗄	🗄 🚡 👒 🛣 🏪 )	🛋 🏦 🏹 🖾 造 🕻		1 💷 🚳 🎇 🛛	f 🗗 🖥
	1	2	3	4	5
1	Aalen04~0112_rgb	Aalen04~0113_rgb	Aalen04~0114_rgb	Aalen04~0115_rgb	Aalen04~0116_rgb
2	Aalen05~0050_rgb	Aalen05~0049_rgb	Aalen05~0048_rgb	Aalen05~0047_rgb	Aalen05~0046_rgb
Strip: 2 [2/2]		Image:	Fon	t size: 8 🌻	

Fig. 10. The Block editor window

The **Block editor** window contains the following elements:

- toolbar to form and edit block images;
- · the list of existed strips and loaded there images;
- the status bar with the following data:

- Strip the Strip name [item No/total] is displayed for strip selected in the table;
- Image the Image name [item No/total in strip/total in block] is displayed for image selected in the table;
- **Font size** allows to change the font size of table text.

To select (highlight) the image in the **Block editor** window click the image name in the list. To select strip click on the name of strip.



To select multiple images\strips use Shift and Ctrl keys

To highlight several images in 2D-window use additional toolbar of group selection (see the *Tool* section in the "Vectorization" User Manual).

The **Block** menu items, buttons of the **Forming block** toolbar and the toolbar of the **Block editor** window.

Buttons	Function
<b>₽</b> •	allows to change the <b>Block editor</b> window size so that window displays all list of strips/images
	allows to show/hide the list of strips/images and the status bar to comfort work with block images in 2D-window (in the <b>Block editor</b> window only toolbar displays)
<b>#</b>	is used to search for an image by name (part of name)
<del>[]3</del>	allows to select in the list initial images, which contain marker position
<u>C</u> e	allows to edit names of several strips of the block at the same time
	is used to display and edit properties of selected strip (name and type of strip)
	reverse images in the strip order
<b>*</b>	allows to add new strip
×	allows to remove selected strip
<b>£</b>	allows to move selected strip up by one strip
Ţ.	allows to move selected strip down by one strip
<b>5</b>	is used to display and edit properties of selected image
2	is used for adding image files, locating in the resources out of active profile, to the selected strip
1	is used for adding image files, locating in the resources of active profile, to the se- lected strip
X	allows to remove selected images from project
۵	is used to radiometric correction of selected image
🔩, 🔄, 🚮, 🖳	allows to move selected images left/right/up/down
\$	allows to rotate selected images to any angle in relation to source or current image's position in block scheme

Table 24. The toolbox of Block editor window

Buttons	Function
	allows to open the <b>Block layout</b> window to build block scheme in 2D-window considering source or acquired data (see the Aerial triangulation User Manual)
R	allows to open the ImageWizard window to setup images
<b>1</b>	allows to show block images in 2D-window, if they were not displayed during project loading, due to limitation specified in the program's setting window (see the "General system's parameters" User Manual)
2	allows to set on/off displaying only selected images mode

# 4. Workflow of UAS processing

Prior to UAS data processing it is necessary to perform the following actions:

- Creating and selecting active profile creating local profile or creating/connecting network profile to place all project/project group files – resources, and selecting the profile as active;
- Creating UAS project (see the "Creating new project" chapter of the "Creating project" User Manual).



The *PHOTOMOD UAS* program is purposed to process **Central projection** projects only (see the "Project types" chapter of the "Creating project" User Manual).

The function of fast project creation is supported for the **Central projection** project type (see the "Fast project creation" chapter of the "Creating project" User Manual).

Fast project creation allows for automatic execution of some primary project processing stages which are usually executed manually. This method facilitates and accelerates data processing.

Fast project creation is also recommended while working with *PHOTOMOD UAS* software, but only if high quality initial data are available, i.e. \*.jpg or \*.tiff images, as well as interior and exterior orientation elements.

Processing of data acquired by UAS implies performing the following steps: **Aerial Triangulation**, **Compute DEM**, and **Compute Orthophoto** (see Section 3.2).



Fig. 11. Workflow of UAS processing





# Appendix A. Input and output data

#### Input data

During the project creation, aerial triangulation and block adjustment the following source data is used:

- [optional] The *list of GCP coordinates* is necessary for block adjustment. The system provides opportunity to measure GCP coordinates manually and also to perform import of GCP list from a text file.
- [optional] The *list of projection centers* coordinates to process central projection images. The program also provides the ability to import on-board data (coordinates) about projection centers from CSV files.



Block adjustment could be process only by projection centers without using ground control points. It is recommended to use GCP coordinates to increase adjustment accuracy.

• Raster images

For working with images in program, it is recommended to use MS-TIFF internal raster format, which is the TIFF format with overview pyramid (set of subsampled images copies) for higher image display performance.

The *Raster Converter* module is used to preliminary raster image processing. It is possible to convert image into internal format both manually, before creating project, and on the stage of adding images into project with saving converted images into active profile resources. See the *Raster Converter module* description in the "General information" User Manual.

The following image formats are available to process central projection images:

- JPEG (JPEG);
- Tag Image File Format (TIFF) TIFF и GeoTiff format, included tags for saving of georeference information;
- Windows Bitmap File (BMP);
- Advanced Systems Format (ASF).
- Information about coordinate system and map projection during project creation it is necessary to define coordinate system of GC points. By default there is an International coordinate system database and map projection (see the details in the "Geo-Calculator" User Manual);
- also it is possible to use the following exterior data:

- import of triangulation points from PAT-B and X-POINTS;
- import of ground control points from text files \*.txt and \*.csv (see above The list of GCP coordinates);
- o import of interior and exterior orientation data from metadata;
- import of external orientation data from PAT-B and CSV-files (see above The list of projection centers);
- GPS data;
- import additional data from different formats.

#### Output data

The program allows to process UAS data and acquire all types of value added photogrammetric products: DEM, 2D and 3D-vectors, orthomosaics.

There are the main output products:

- *Digital Terrain Model (DTM)* digital cartographic presentation of terrain surface both as regular grid of elevations (DEM) and as triangulated irregular network (TIN). They are used for solving applied research problems.
- 3D vector objects used for creating a topographical base for cartographic production or as source data for a mathematical representation of a scene in three-dimensional digital terrain modeling;
- orthophoto production single raster images in the form of a single frame or a set of sheets in a selected map projection with marginalia. In the resulting image, geometric and photometric distortions are corrected, creating seamless, color-balanced orthophotos with uniform brightness as an output;
- *3D models of terrain* can be used to solve applied research problems, as well as for creation of multimedia presentations and commercials.



There is opportunity to export all photogrammetric products to various formats.

# Appendix B. The PHOTOMOD8UAS.VAR configuration folder

At the stage of system first configuration is automatically created the *PHOTO-MODUAS8.VAR* folder. This folder is used to store configuration, temporary and other system files.

Only one *PHOTOMODUAS8.VAR* folder creates, even for several installed copies of the system.



It is not recommended to place the configuration folder in the net, because it leads to slowing of system's work.

PHOTOMODUAS8.VAR folder contains the following files and folders:

- AutoSave folder is used to store autosaved data:
- Config folder is used to store files of general parameters of all profiles;



It is possible to return to default parameters in case of changing configuration file. To do this, remove a configuration file in the *PHOTOMODUAS8.VAR* folder and restart the system. Default configuration file are copied from the *PHOTOMODUAS8.VAR* (*Config* system files folder.



Both global settings and settings for the local profile is loaded at startup of the system and saved when you exit. Local project settings is loaded when loading a project and saved when project closing. In case of working without projects, settings are stored in the *PHOTO-MODUAS8.Var\Profiles\[profile\_name]\VoidProjOptions.x-ini* file.

- Logs folder is used to store log-files for all profiles;
- Profiles folder is used to store all parameters for each profile separately. The list
  of local and network profiles is also stored in the folder. It is the same list as in the
  Control Panel module (see the "Control Panel. Profiles management" chapter of the
  "General information" User Manual). Configuration file with resource structure and
  path to local/network folder is also stored in folder of each profile;



New subfolder creates for each profile.

- *Tmp* folder is used to store temporary files;
- UserData folder is used to store data out of resources system;
- *policy.x-ini* file contains general information about configuration parameters (active profile name, name and path to centralized management folder and so on).